

3 Gbps, HD, SD, DVB-ASI SDI Serializer and Cable Driver With LVDS Interface

Check for Samples: LMH0040, LMH0050, LMH0070, LMH0340

FEATURES

- LVDS Interface to Host FPGA
- No External VCO or Clock Ref Required
- Integrated Variable Output Cable Driver
- 3.3V SMBus Configuration Interface
- Integrated TXCLK PLL Cleans Clock Noise
- Small 48-Pin WQFN Package
- Industrial Temperature range: -40°C to 85°C

APPLICATIONS

- SDI Unterfaces for:
 - Video Cameras
 - DVRs
 - Video Switchers
 - Video Editing Systems

KEY SPECIFICATIONS

- Output Compliant With SMPTE 424M, SMPTE 292M, SMPTE 259M-C and DVB-ASI (See Table 1)
- Typical Power Dissipation: 440 mW
- 30 ps Typical Output Jitter (HD, 3G)

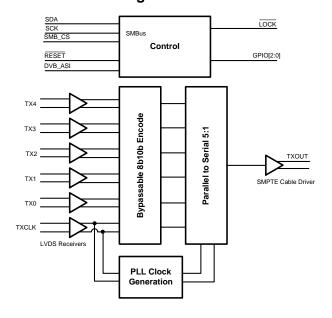
DESCRIPTION

The LMH0340/0040/0070/0050 SDI Serializers are part of TI's family of FPGA-Attach SER/DES products supporting 5-bit LVDS interfaces with FPGAs. An FPGA Host will format data with supplied IP such that the output of the LMH0340 is compliant with the requirements of DVB-ASI, SMPTE 259M-C, SMPTE 292M and SMPTE 424M standards. See Table 1 for details on which Standards are supported per device.

The interface between the SER (Serializer) and the FPGA consists of a 5 bit wide LVDS data bus, an LVDS clock and an SMBus interface. The LMH0340/0040/0070 SER devices include an integrated cable driver which is fully compliant with all of the SMPTE specifications listed above. The LMH0050 has a CML output driver that can drive a differential transmission line or interface to a cable driver.

The FPGA-Attach SER/DES family is supported by a suite of IP which allows the design engineer to quickly develop video applications using the SER/DES products. The SER is packaged in a physically small 48-pin WQFN package.

General Block Diagram



Please be aware that an important notice concerning availability, standard warranty, and use in critical applications of Texas Instruments semiconductor products and disclaimers thereto appears at the end of this data sheet.

All trademarks are the property of their respective owners.



Connection Diagram

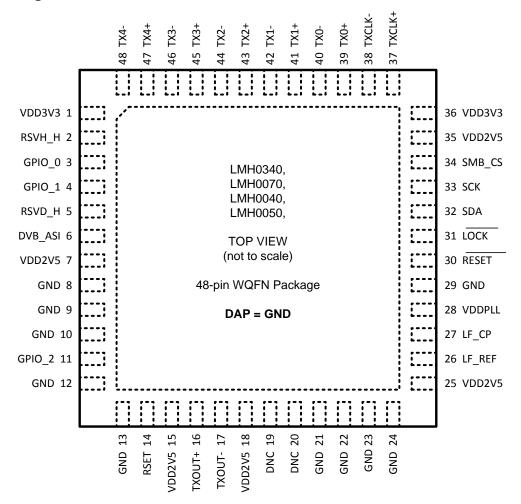


Figure 1. Connection Diagram for 48L WQFN Package



PIN DESCRIPTIONS

Pin Name	Туре	Description
LVDS Input Inter	face	
TX[4:0]+ TX[4:0]-	Input, LVDS	LVDS Data Input Pins Five channel wide DDR interface. Internal 100Ω termination.
TXCLK+ TXCLK-	Input, LVDS	LVDS Clock Input Pins DDR Interface. Internal 100Ω termination.
Serial Output Int	erface	
TXOUT+	Output, CML	Serial Digital Interface Output Pin Non-Inverting Output
TXOUT-	Output, CML	Serial Digital Interface Output Pin Inverting Output
SMBus Interface		
SDA	I/O, LVCMOS	SMBus Data I/O Pin
SCK	Input, LVCMOS	SMBus Clock Input Pin
SMB_CS	Input, LVCMOS	SMBus Chip Select Input Pin Device is selected when High.
Control and Con	figuration Pins	
RESET	Input, LVCMOS	Reset Input Pin H = normal mode L = device in RESET
LOCK	Output, LVCMOS	PLL LOCK Status Output H = unlock condition L = Device is Locked
DVB_ASI	Input, LVCMOS	DVB_ASI Select Input H = DVB_ASI Mode enabled L = Normal Mode enabled
GPIO[2:0]	I/O, LVCMOS	General Purpose Input / Output Software configurable I/O pins.
RSVD_H	Input, LVCMOS	Configuration Input – Must tie High Pull High via 5 $k\Omega$ resistor to V_{DD3V3}
Analog Inputs		
R _{SET}	Input, analog	Serial Output Amplitude Control Resistor connected from this pin to ground to set the signal amplitude. Nominally $8.06k\Omega$ for $800mV$ output (SMPTE).
LF_CP	Input, analog	Loop Filter Connection
LF_REF	Input, analog	Loop Filter Reference
DNC		Do Not Connect – Leave Open
Power Supply ar	nd Ground	
V _{DD3V3}	Power	3.3V Power Supply connection
V _{DDPLL}	Power	3.3V PLL Power Supply connection
V _{DD2V5}	Power	2.5V Power Supply connection
GND	Ground	Ground connection – The DAP (large center pad) is the primary GND connection for the device and must be connected to Ground along with the GND pins.

Table 1. Feature Table

Device	SMPTE 424M Support (3G)	SMPTE 292M Support (HD)	SMPTE 259M Support (SD)	DVB-ASI Support	SMPTE compliant Cable Driver
LMH0340	X	X	X	Х	Х
LMH0040		X	X	Х	Х
LMH0070			Х	Х	Х
LMH0050		Х	Х	Х	





These devices have limited built-in ESD protection. The leads should be shorted together or the device placed in conductive foam during storage or handling to prevent electrostatic damage to the MOS gates.

Absolute Maximum Ratings (1)(2)

-0.3V to +4.0V
-0.3V to +3.0V
-0.3V to (V _{DD3V3} +0.3V)
-0.3V to (V _{DD3V3} +0.3V)
-0.3V to +3.6V
-0.3V to +3.6V
+150°C
−65° to 150°C
25°C/W
≥±8kV

^{(1) &}quot;Absolute Maximum Ratings" are limits beyond which the safety of the device cannot be ensured. It is not implied that the device will operate up to these limits.

Recommended Operating Conditions

Parameter		Min	Тур	Max	Units
Supply Voltage (V _{DD3V3} -GND)		3.135	3.3	3.465	V
Supply Voltage (V _{DD2V5} -GND)		2.375	2.5	2.625	V
Supply noise amplitude (10 Hz to 50 MHz)				100	mV_{P-P}
Ambient Temperature		-40	+25	+85	°C
Case Temperature				100	°C
TXCLK input frequency	LMH0340	27		297	MHz
	LMH0040	27		149	MHz
	LMH0070	26.5	27	28	MHz
	LMH0050	27		149	MHz
LVDS PCB board trace length (mismatch <2%)	ı			25	cm
Output Driver Pullup Resistor Termination Volta	ge ⁽¹⁾		2.5	2.625	V

⁽¹⁾ Applies to LMH0340, LMH0040, and LMH0070.

⁽²⁾ If Military/Aerospace specified devices are required, please contact the TI Sales Office/Distributors for availability and specifications.



Electrical Characteristics

Over supply and Operating Temperature ranges unless otherwise specified. (1)

Symbol	Parameter	Condition	Min	Тур	Max	Units
I _{DD2.5}	2.5V supply current for LMH0340,	2.97 Gbps		93	102	mA
	LMH0040, or LMH0070	1.485 Gbps		80	87	mA
		270 Mbps		63	69	mA
	2.5V supply current for LMH0050	1.485 Gbps		87	95	mA
		270 Mbps		70	70 75	mA
I _{DD3.3}	3.3V supply current for LMH0340, LMH0040, or LMH0070	2.97 Gbps		73	85	mA
		1.485 Gbps		73	85	mA
		270 Mbps		73	85	mA
	3.3V supply current for LMH0050	1.485 Gbps		73	85	mA
		270 Mbps		73	85	mA
PD	Power Consumption	LMH0340 - 2.97 Gbps		475	545	mW
		LMH0040 - 1.485 Gbps		440	510	mW
		LMH0050 - 1.485 Gbps		460	525	mW
		LMH0050 - 270 Mbps		415	485	mW
		LMH0070 - 270 Mbps		400	470	mW

⁽¹⁾ Typical Parameters measured at V_{DD3V3}=3.3V, V_{DD2V5}=2.5V, T_A=25°C. They are for reference purposes and are not production tested.

Control Pin Electrical Characteristics

Over supply and Operating Temperature ranges unless otherwise specified. Applies to DVB_ASI, $\overline{\text{RESET}}$, GPIO[2:0] and $\overline{\text{LOCK}}$. (1)

Symbol	Parameter	Condition	Min	Тур	Max	Units
V_{IH}	High Level Input Voltage		2.0		V _{DD3V3}	V
V_{IL}	Low Level Input Voltage		0		0.8	V
V _{OH}	High Level Output Voltage	I _{OH} =-2 mA	2.7	3.3		V
V _{OL}	Low Level Output Voltage	I _{OL} =2 mA			0.3	V
V _{CL}	Input Clamp Voltage	I _{CL} =-18 mA		-0.79	-1.5	V
I _{IN}	Input Current	V_{IN} =0.4V, 2.5V or V_{DD}	-35		35	μΑ
Ios	Output Short Circuit Current	V _{OUT} =0V		-40		mA

⁽¹⁾ Typical Parameters measured at V_{DD3V3}=3.3V, V_{DD2V5}=2.5V, T_A=25°C. They are for reference purposes and are not production tested.

LVDS Input Electrical Characteristics

Over supply and Operating Temperature ranges unless otherwise specified. (1)

Symbol	Parameter	Condition	Min	Тур	Max	Units
V_{TH}	Differential Input High threshold	0.05V <v<sub>CM<2.4V</v<sub>			+100	mV
V_{TL}	Differential Input Low threshold		-100			mV
R _{LVIN}	Input Impedance	Measured between LVDS pairs	85	100	115	Ω

(1) Typical Parameters measured at V_{DD3V3}=3.3V, V_{DD2V5}=2.5V, T_A=25°C. They are for reference purposes and are not production tested.



LVDS Switching Characteristics

Over supply and Operating Temperature ranges unless otherwise specified. (1)

Symbol	Parameter	Condition	Min	Тур	Max	Units
t _{CIP}	TxCLKIN Period	See Figure 2	3.2	2T	37	ns
t _{CIT}	TxCLKIN Transition Time	See Figure 3	0.5	1.0	3.0	ns
t _{CIH}	TxCLKIN IN High Time	See Figure 2	0.7T	Т	1.3T	ns
t _{CIL}	TxCLKIN IN Low Time	See Figure 2	0.7T	Т	1.3T	ns
t _{XIT}	TxIN Transition Time		0.15		3	ns
t _{STC}	TxIN Setup to TxCLKIN	See Figure 2 (2)	-550			ps
t _{HTC}	TxIN Hold to TxCLKIN		900			ps

- Typical Parameters measured at V_{DD3V3} =3.3V, V_{DD2V5} =2.5V, T_A =25°C. They are for reference purposes and are not production tested. Parameter uses default settings in registers: 0x24'h and 0x30'h.

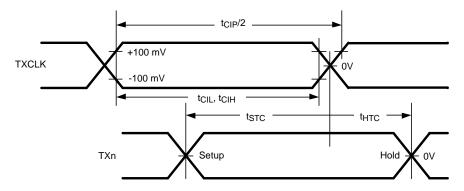


Figure 2. LVDS Input Timing Diagram



Figure 3. Transmit Clock Transition Times

SMBus Input Electrical Characteristics

Over supply and Operating Temperature ranges unless otherwise specified. (1)

Symbol	Parameter	Condition	Min	Тур	Max	Units
V _{SIL}	Data, Clock Input Low Voltage				0.8	V
V _{SIH}	Data, Clock Input High Voltage		2		V_{SDD}	V
I _{SPULLUP}	Current through pull-up resistor or current source	(2)	4			mA
V_{SDD}	Nominal Bus Voltage		2.375		3.6	V
I _{SLEAKB}	Input Leakage per bus segment	(2)	-200		200	μΑ
I _{SLEAKP}	Input Leakage per pin		-10		10	μΑ
C _{SI}	Capacitance for SMBdata and SMBclk	(2) (3)			10	pF
R _{STERM}	Termination Resistance	V _{SDD3V3} ⁽⁴⁾ (3) (2)		1000		Ω

- $\label{eq:topical_parameters} \text{ Typical Parameters measured at V}_{\text{DD3V3}} = 3.3 \text{V}, \text{ V}_{\text{DD2V5}} = 2.5 \text{V}, \text{ T}_{\text{A}} = 25 ^{\circ}\text{C}. \text{ They are for reference purposes and are not production tested.}$
- Recommended value—Parameter is not tested. (2)
- (3)Recommended maximum capacitance load per bus segment is 400 pF.
- Maximum termination voltage should be identical to the device supply voltage.

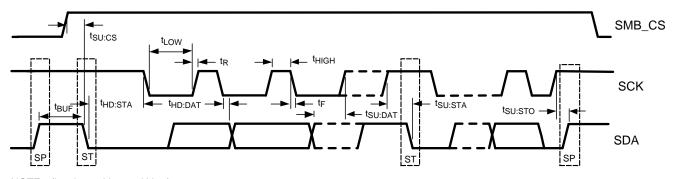


SMBus Switching Characteristics

Over supply and Operating Temperature ranges unless otherwise specified. (1)

Symbol	Parameter	Condition	Min	Тур	Max	Units
f _{SMB}	Bus Operating Frequency		10		100	kHz
t _{BUF}	Bus free time between stop and start condition		4.7			μs
t _{HD:STA}	Hold time after (repeated) start condition. After this period, the first clock is generated	At I _{SPULLUP} = MAX	4.0			μs
t _{SU:STA}	Repeated Start condition setup time		4.7			μs
t _{SU:STO}	Stop Condition setup time		4.0			μs
t _{HD:DAT}	Data hold time		300			ns
t _{SU:DAT}	Data setup time		250			ns
t _{LOW}	Clock Low Time		4.7			μs
t _{HIGH}	Clock High Time		4.0		50	μs
t _F	Clock/data fall time	20% to 80%			300	ns
t _R	Clock/data rise time				1000	ns
t _{SU:CS}	SMB_CS setup time			30		ns
t _{POR}	Time in which a device must be operational after power on				500	ms

(1) Typical Parameters measured at V_{DD3V3}=3.3V, V_{DD2V5}=2.5V, T_A=25°C. They are for reference purposes and are not production tested.



NOTE: (levels are V_{SIL} and V_{SIH})

Figure 4. SMBus Timing Parameters

SDI Output Characteristics — LMH0340 / LMH0040 / LMH0070

Over supply and Operating Temperature ranges unless otherwise specified. (1)

Symbol	Parameter	Condition	Min	Тур	Max	Units
V _{OD}	SDI Output Voltage	into 75Ω load	720	800	880	mV
DR	SDI Output Datarate	LMH0340	270		2,970	Mbps
		LMH0040	270		1,485	Mbps
		LMH0070		270		Mbps
t _r	SDI Output Rise Time	2.97 Gbps		90	135	ps
		1.485 Gbps		90	220	ps
		<1.485 Gbps	400	700	220 1000	ps
t _f	SDI Output Fall Time	2.97 Gbps		90	135	ps
		1.485 Gbps		90	220	ps
		<1.485 Gbps	400	700	1000	ps

 $(1) \quad \text{Typical Parameters measured at V_{DD3V3}=3.3V, V_{DD2V5}=2.5V, T_{A}=25°C. They are for reference purposes and are not production tested.}$



SDI Output Characteristics — LMH0340 / LMH0040 / LMH0070 (continued)

Over supply and Operating Temperature ranges unless otherwise specified. (1)

Symbol	Parameter	Condition	Min	Тур	Max	Units
Δt_t	Mismatch between rise and fall time	≥1.485 Gbps			30	ps
t _{SD}	Propagation Delay Latency	See Figure 5		9.5		TXCLK cycle
tj	Peak to Peak Alignment Jitter	≥1.485 Gbps ⁽³⁾		30	50	ps
		270 Mbps ⁽³⁾		100	200	ps
RL	Output Return Loss — EVK	Measured 5 MHz to 1485 MHz	15	20		dB
	Specification (4)	Measured 1485 MHz to 2970 MHz	10	15		dB
tos	Output Overshoot ⁽²⁾	2.97 Gbps			8	%
		1.485 Gbps			5	%
		270 Mbps			2	%

- (2) Specification ensured by characterization.
- (3) Measured in accordance with SMPTE RP184. 100% production tested.
- (4) Output Return Loss specification applies to measurement on the EVK PCB (LMH0340 ALP Daughter Card) per SMPTE requirements.

CML Output Characteristics — LMH0050

Over supply and Operating Temperature ranges unless otherwise specified. (1)

Symbol	Parameter	Condition	Min	Тур	Max	Units
V _{OD}	Output Voltage	into 100 Ω differential load	1175		1450	mV
DR	Data Rate		270		1485	Mbps
t _r	Output Rise Time				100	ps
t _f	Output Fall Time				100	ps
tJ	Peak-to-Peak Alignment Jitter	1.485 Gbps		25	50	ps
R _{OUT}	Output Termination Resistance	Output Pin to V _{DD2V5} Pin	40	50	60	Ω

⁽¹⁾ Typical Parameters measured at V_{DD3V3}=3.3V, V_{DD2V5}=2.5V, T_A=25°C. They are for reference purposes and are not production tested.

Device Switching Characteristics

Over supply and Operating Temperature ranges unless otherwise specified. (1)

Symbol	Parameter	Condition	Min	Тур	Max	Units
t _{TPLD}	Device Lock Time	2.97 Gbps			10	ms
		1.485 Gbps			11	ms
		270 Mbps			15	ms

(1) Typical Parameters measured at V_{DD3V3}=3.3V, V_{DD2V5}=2.5V, T_A=25°C. They are for reference purposes and are not production tested.

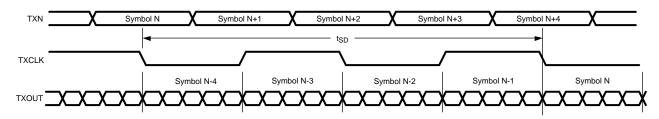


Figure 5. LVDS Interface Propagation Delay



FUNCTIONAL DESCRIPTION

DEVICE OPERATION

The SER is used in digital video signal origination equipment. It is intended to be operated in conjunction with an FPGA host which preprocesses data for it, and then provides this data over the five bit wide data path. Provided the host has properly formatted the data for the SER, the output of the device will be compliant with DVB-ASI, SMPTE 259M-C, SMPTE 292M or SMPTE 424M depending upon the output mode selected.

Texas Instruments offers IP in source code format to perform the appropriate formatting of the data, as well as evaluation platforms to assist in the development of target applications. For more information please contact your local Texas Instruments Sales Office/Distributor.

POWER SUPPLIES

The SER has several power supply pins, at 2.5V as well as 3.3V. It is important that these pins all be connected, and properly bypassed. Bypassing should consist of parallel $4.7\mu F$ and $0.1\mu F$ capacitors as a minimum, with a $0.1\mu F$ capacitor on each power pin. The device has a large contact in the center of the bottom of the package. This contact must be connected to the system GND as it is the major ground connection for the device. A 22 μF capacitor is required on the V_{DDPLL} pin which is connected to the 3.3V rail.

Discrete bypassing is ineffective above 30 MHz to 50 MHz in power plane-based distribution systems. Above this frequency range, the intrinsic capacitance of the power-ground system can be used to provide additional RF bypassing. To make the best use of this, make certain that there are PCB layers dedicated to the Power supplies and to GND, and that they are placed next to each other to provide a distributed capacitance between power and GND.

The SER will work best when powered from linear regulators. The output of linear regulators is generally cleaner with less noise than switching regulators. Output filtering and power system frequency compensation are generally simpler and more effective with linear regulators. Low dropout linear regulators are available which can usually operate from lower input voltages such as logic power supplies, thereby reducing regulator power dissipation. Cascading of low dropout regulators should not be done since this places the entire supply current load of both load systems on the first regulator in the cascade and increases its loading and thermal output.

POWER UP

The 3.3V power supply should be brought up before the 2.5V supply. The timing of the supply sequencing is not important. The device has a power on reset sequence which takes place once both power supplies are brought up. This sequence will reset all register contents to their default values, and will place the PLLs into link acquisition mode, attempting to lock on the TXCLK input.

RESET

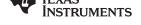
There are three ways in which the device may be reset. There is an automatic reset which happens on power-up; there is a reset pin, which when brought low will reset the device, with normal operation resuming when the pin is driven high again. The third way to reset the device is a soft reset, implemented via a write to the reset register. This reset will put all of the register values back to their default values, except it will not affect the address register value if the SMBus default address has been changed.

LVDS INPUTS

The SER has LVDS inputs that conform with the ANSI/TIA/EIA-644–A Standard. These inputs have an internal 100 Ω resistor across the inputs which allows for the closing of a current loop interface from the LVDS driver in the host. It is recommended that the PCB trace between the FPGA and the transmitter be less than 25cm. Longer PCB traces may introduce signal degradation as well as channel skew which could cause serialization errors. This connection between the host and the SER should be over a controlled impedance transmission line with an impedance which matches the termination resistor – usually 100 Ω . Setup and hold times are specified in LVDS Switching Characteristics, however there is the ability to change these by use of the CLK delay adjustment available via the SMBus, and writing to register 0x30'h.

SNLS271I - APRIL 2007 - REVISED APRIL 2013

www.ti.com



LVDS DATA ORDER

When serializing the data, the data bit latched in on TX0 is output first, followed by TX1, TX2, TX3 and then TX4. If starting with a 10 bit word, T0..T9, with T0 being the LSB, and it is desired that this be serialized such that the LSB is sent out first, then the least significant 5 bit word would be provided to the serializer first, followed by the most significant word, and the resulting serialized output would have the LSB being sent first, and the 10 bit MSB (T9) would be transmitted last. If it is desired to reverse the serialization order, such that the bit presented on TX4 is output first, this mode of operation may be selected via register 0x2E'h.

LOOP FILTER

The SER has an internal PLL which is used to generate the serialization clock from the parallel clock input. The loop filter for this PLL is external, and for optimum results in Serial Digital Interface applications, a capacitor and a resistor in series should be connected between pins 26 and 27. Recommended value for the capacitor is 0.1 μ F. Recommended value for the resistor is 500 Ω .

PLL FILTER / BYPASS

The SER has an external filter capacitor for the PLL. The recommended value for this capacitor is 22 µF with a connection to the 3.3V rail.

DVB ASI MODE

The SER has a special mode for DVB-ASI. In this mode, the input signal on TX4± is treated as a data valid bit, if high, then the four bit nibbles from TX0-TX3 are taken to form an 8 bit word, which is then converted to a 10 bit code via an internal 8b10b encoder and this 10 bit word is serialized and driven on the output. The nibble taken in on the rising edge of the clock is the most significant nibble and the nibble taken in on the falling edge is the least significant nibble. If TX4± is low, then the input on TX0-TX3 are ignored and the 10b idle character is inserted in the output stream. The Idle character can be reprogrammed to be any 10 bit code desired via registers 0x11'h and 0x12'h.

SDI OUTPUT INTERFACING

The serial outputs provide low-skew complimentary or differential signals. The output buffer is a current mode design, with a high impedance output. To drive a 75 Ω transmission line connect a 75 Ω resistor from each of the output pins to 2.5V. This resistor has two functions – it converts the current output to a voltage, which is used to drive the cable, and it acts as the back termination resistor for the transmission line. The resistor should be placed as close to the output pin as is practicable. The output driver automatically adjusts its slew rate depending on the input datarate so that it will be in compliance with SMPTE 259M, SMPTE292M or SMPTE 424M as appropriate. In addition to output amplitude and rise/fall time specifications, the SMPTE specs require that SDI outputs meet an Output Return Loss (ORL) specification. There are parasitic capacitances that will be present both at the output pin of the device and on the application printed circuit board. To optimize the return loss implement a series network comprised of a parallel inductor and resistor. The actual values for these components will vary from application to application, but the typical interface circuit shows values that would be a good starting point. Figure 6 shows an equivalent output circuit for the LMH0340 / LMH0040 / LMH0070. The collectors present a high impedance current source. The external 75Ω resistors will provide the back termination resistance as well as converting the current to a voltage - with the addition of the termination resistance at the load, there will be an overall output resistance of 37.5Ω, which in conjunction with the 24mA current source will develop the 800mV swings called for in the standard.

Submit Documentation Feedback



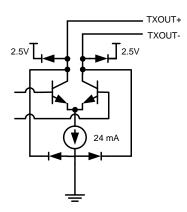


Figure 6. Simplified SDI Output Circuit

Care must be taken in the layout of the output circuitry to meet SMPTE return loss specifications as any parasitic impedances or transmission line discontinuities will result in reflections which will adversely affect the output return loss. For more details on how to get good output return loss, please refer to the application note "Successful design with the FPGA-Attach SER/DES".

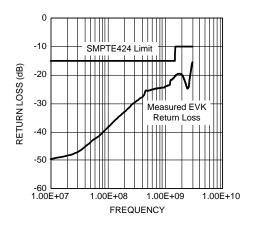


Figure 7. SDI Output Return Loss (EVK Example)

The amplitude of the output is ensured to be compliant with SMPTE specifications if the specified value of R_{SET} resistor is used, however if the designer wishes to change the output amplitude, there are two methods by which this can be done. By changing the value of resistor connected to the R_{SET} pin, the output amplitude will be adjusted.

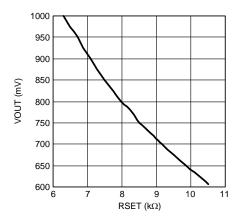


Figure 8. Output Voltage vs. R_{SET}



CML Output Interfacing

The LMH0050 does not include the internal SMPTE cable driver, as its outputs are CML, include internal 50 Ω pull up resistors, and are intended to drive 100 Ω transmission lines. The LMH0050 outputs may either be connected to a differential transmission medium such as twisted pair cable, or used to drive an external cable driver.

Power Down Mode

If the device is not to be used, some power can be saved by writing a '0x40h' to register 0x26'h, and a 0x10'h to register 0x01'h. The write to register 0x26'h will disable the input buffers of the device, and the write to register 0x01'h will power down the output buffer. In this mode, the device power dissipation can be expected to be reduced by approximately 30%. There are portions of the circuit which will automatically power down if there is no clock present on the TXCLK input, so this method can be used to further reduce the power.

SMBus INTERFACE

The configuration bus conforms to the System Management Bus (SMBus) 2.0 specification. SMBus 2.0 includes multiple options. The optional ARP (Address Resolution Protocol) feature is not supported. The I/O rail is 3.3V only and is not 5V tolerant. The use of the SMB_CS signal is recommended for applications with multi-drop applications (multiple devices to a host).

The SMBus is a two wire interface designed for the communication between various system component chips, additional signals maybe required for chip select function depending upon application. By accessing the control functions of the circuit via the SMBus, signal count is kept to a minimum while allowing a maximum amount of versatility. The SMBus has three pins to control it: an SMBus CS pin which enables the SMBus interface for the device, a Clock and a Data line. In applications where there might be several SER devices, the SDA and SCK pins can be bussed together and the individual devices to be communicated with may be selected via their respective SMB_CS pin. The SCK and SDA are both open drain and are pulled high by external pullup resistors. The SER has several internal configuration registers which may be accessed via the SMBus. These registers are listed in Table 2.

TRANSFER OF DATA TO THE DEVICE VIA THE SMBus

During normal operation the data on SDA must be stable during the time when SCK is high.

START / STOP / IDLE CONDITIONS

There are three unique states for the SMBus:

START	A HIGH-to-LOW transition on SDA while SCK is High indicates a message START condition
STOP	A LOW-to-HIGH transition on SDA while SCK is High indicates a message STOP condition.
IDLE	If SCK and SDA are both High for a time exceeding t_{BUF} from the last detected STOP condition or if they are high for a total exceeding the maximum specification for t_{HIGH} then the bus will transfer to the IDLE state.

SMBus TRANSACTIONS

A transaction begins with the host placing the SER SMBus into the START condition. Then a byte (8 bits) is transferred, MSB first, followed by a ninth ACK bit. ACK bits are '0' to signify an ACK, or '1' to signify NACK. After this the host holds the SCK line Low, and waits for the receiver to raise the SDA line as an ACKnowledge that the byte has been received.

REGISTER WRITE

To write a data value to a register in the SER, the host writes three bytes to the SER. The first byte is the device address—the device address is a 7 bit value, and if writing to the SER the last bit (LSB) is set to '0' to signify that the operation is a write. The second byte written is the register address, and the third byte written is the data to be written into the addressed register. If additional data writes are performed, the register address is automatically incremented. At the end of the write cycle the host places the bus in the STOP state.

REGISTER READ

Submit Documentation Feedback



To read the data value from a register, first the host writes the device address with the LSB set to a '0' denoting a write, and then the register address is written to the device. The host then reasserts the START condition, and writes the device address once again, but this time with the LSB set to a '1' denoting a read, and following this the SER will drive the SDA line with the data from the addressed register. The host indicates that it has finished reading the data by asserting a '0' for the ACK bit. After reading the last byte, the host will assert a '1' for NACK to indicate to the SER that it does not require any more data.

Note that the SMBus pins are not 5V compliant and they must be driven by a 3.3V source.

SMBus CONFIGURATIONS

Many different configurations of the SMBus are possible and depend upon the specific requirements of the applications. Several possible applications are described.

CONFIGURATION 1

The SER SMB_CS may be tied High (always enabled) since it is the only device on the SMBus. See Figure 9.

CONFIGURATION 2

Since the multiple SER devices have the same address, the use of the individual SMB CS signals is required. To communicate with a specific device, its SMB CS is driven High to select the device. After the transaction is complete, its SMB_CS is driven Low to disable its SMB interface. Other devices on the bus may now be selected with their respective chip select signals and communicated with. See Figure 10.

CONFIGURATION 3

The addressing field is limited to 7-bits by the SMBus protocol. Thus it is possible that multiple devices may share the same 7-bit address. An optional feature in the SMBus 2.0 specification supports an Address Resolution Protocol (ARP). This optional feature is not supported by the LMH0340/0040/0070/0050 devices. Solutions for this include: the use of the independent SMB_CS signals, independent SMBus segments, or other means. See Figure 11.

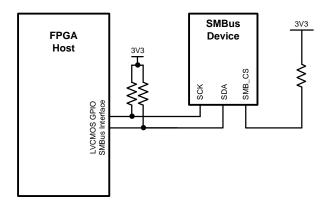


Figure 9. SMBus Configuration 1 — Host to single device

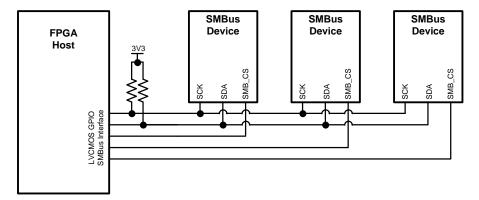


Figure 10. SMBus Configuration 2 — Host to multiple devices with SMB_CS signals



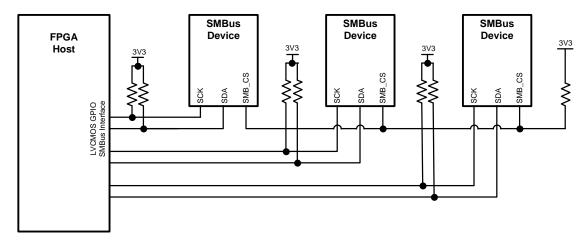


Figure 11. SMBus Configuration 3 — Host to multiple devices with multiple SMBus Interfaces

GENERAL PURPOSE I/O PINS GPIO[2:0]

The SER has three pins which can be configured to provide direct access to certain register values via a dedicated pin. For example if a particular application required fast action to the condition of the serializer losing it's input clock, the TXCLK detect status bit could be routed directly to an external pin where it might generate an interrupt for the host processor. GPIO pins can be configured to be in TRI-STATE® (High Impedance) mode, the buffers can be disabled, and when used as inputs can be configured with a pullup resistor, a pulldown resistor or no input pin biasing at all. When the GPIO pins are being used as inputs, there is the ability to have an internal pullup or pull down resistor. This is selected via the GPIO Configuration registers.

Each of the GPIO pins has a register to control it. For each of these registers, the upper 4 bits are used to define what function is desired of the GPIO pin with options being slightly different for each of the three GPIO pins. The pins can be used to monitor the status of various internal states of the SER device, to serve as an input from some external stimulus, and for output to control some external function.

GPIO 0 FUNCTIONS

Allow for the output of a signal programmed by the SMBus

Allow the monitoring of an external signal via the SMBus

Monitor Status of TXCLK signal

Monitor Status of TXCLKDetect

Monitor Power On Reset

GPIO_1 FUNCTIONS

Monitor Power On Reset

Allow for the output of a signal programmed by the SMBus

Allow the monitoring of an external signal via the SMBus

Monitor LOS for data bit 0

Monitor LOS for data bit 1

Monitor LOS for data bit 2

Monitor LOS for data bit 3

Monitor LOS for data bit 4

GPIO_2 FUNCTIONS

Allow for the output of a signal programmed by the SMBus



Allow the monitoring of an external signal via the SMBus

Serializer Clock output

Bits 2 and 3 are used to determine the status of the internal pullup/pulldown resistors on the device—they are loaded according to the following truth table:

00: pullup and pulldown disabled

01: pulldown enabled

10: pullup enabled

11: Reserved

Bit 1 is used to enable or disable the input buffer. If the GPIO pin is to be used as an output pin, then this bit must be set to a '0' disabling the output.

The LSB is used to switch the output between normal output state and high impedance mode. If the GPIO is to be used as an input pin, this bit must be set to '0' placing the output in high Z mode.

As an example, if you wanted to use the $GPIO_0$ pin to reflect the status of the \overline{LOCK} pin, you would load the appropriate register with the value 0001 0001b.

POTENTIAL APPLICATION FOR GPIO PINS

In addition to being useful debug tools while bringing a design up, there are other practical uses to which the GPIO pins can be put:

Sensing if a cable is connected to an output -

When connecting the BNC cable to the output, connect the shield of the connector to GND via a capacitor—making it an AC GND, but a DC open. Now connect that shield to one of the GPIO connections which you configure as an input with a pullup. With no cable on the BNC, the GPIO pin will see a high state, but once a terminated cable is connected, the shield will be brought down and you will read a low state.

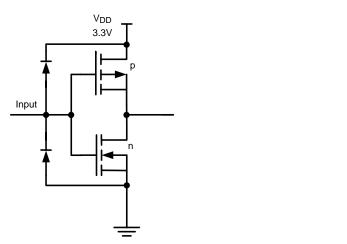


Figure 12. Simplified LVCMOS Input Circuit

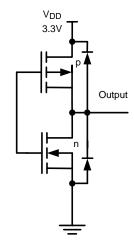


Figure 13. Simplified LVCMOS Output Circuit



APPLICATION INFORMATION

PCB RECOMMENDATIONS

The SMPTE Serial specifications have very stringent requirements for output return loss on drivers. The output return loss will be degraded by non-idealities in the connection between the SER (all variants with the exception of the LMH0050) and the output connector. All efforts should be taken to minimize the trace lengths for this area, and to assure that the characteristic impedance of this trace is 75Ω .

It is recommended that the PCB traces between the host FPGA and the SER be no longer than 10 inches (25cm) and that the traces be routed as differential pairs, with very tight matching of line lengths and coupling within a pair, as well as equal length traces for each of the six pairs. For additional information on layout and soldering of the WQFN package, please refer to the applications note AN-1187 (SNOA401).

PCB Design do's and don'ts:

- DO Whenever possible dedicate an entire layer to each power supply this will reduce the inductance in the supply plane.
- DO use surface mount components whenever possible
- DO place bypass capacitors close to each power pin
- DON'T create ground loops pay attention to the cutouts that are made in your power and ground planes to make sure that there are not opportunities for loops.
- DON'T allow discontinuities in the ground planes return currents will follow the path of least resistance for high frequency signals this will be the path of least inductance.
- DO place the SER outputs as close as possible to the edge of the PCB where it will connect to the outside world.
- DO make sure to match the trace lengths of all differential traces, both between the sides of an individual pair, and from pair to pair.
- DO remember that VIAs have significant inductance when using a via to connect to a power supply or ground layer, two in parallel are better than one.
- DO connect the slug on the bottom of the package to a solid Ground connection. This contact is used for the
 major GND connection to the device as well as serving as a thermal via to keep the die at a low operating
 temperature.
- There is an application note available which discusses layout suggestions for the SER in greater detail.

TYPICAL SMPTE APPLICATIONS CIRCUIT

A typical application circuit for the LMH0340 is shown in Figure 14. Alternately this could also employ the LMH0040 or LMH0070 Serializers in lower data rate SMPTE applications.

The TX interface between the host FPGA and the SER is composed of a 5-bit LVDS Data bus and its LVDS clock. This is a point-to-point interface and the SER includes on-chip 100 terminations. Pairs should be of equal length to minimize any skew impact. The LVDS clock (TXCLK) uses both edges to transfer the data.

An SMBus is also connected from the host FPGA to the SER. If the SMBus is shared, a chip select signal is used to select the device being addressed. The SCK and SDA signals require a pull up resistor. The SMB_CS is driven by a GPO signal from the FPGA. Depending on the FPGA I/O it may also require a pull up unless it is a push / pull output.

Depending upon the application, several other GPIO signals maybe used. This includes the DVB_ASI and RESET input signals. If these pins are not used, then must be tied off to the desired state. The LOCK signal maybe used to monitor the SER. If it is unused, leave the pin as a NC (or route to a test point).

The SER includes a SMPTE compliant cable driver. While this is a differential driver, it is commonly used single-endedly to drive 75 Ω coax cables. External 75 Ω pull up resistors are used to the 2.5V rail. The active output(s) also includes a matching network to meet the required Output Return Loss SMPTE specification. While application specific, in general a series 75 Ω resistor shunted by a 6.8 nH inductor will provide a starting value to design with. The signal is then AC coupled to the cable with a 4.7 μ F capacitor. If the complementary output is not used, simply terminate it after its AC coupling capacitor to ground. This output (even though its inverting) may still be used for a loop back or 1:2 function due to the nature of the NRZI coding that the SMPTE standards require. The output voltage amplitude of the cable driver is set by the R_{SET} resistor. For single-ended applications, an 8.06 k Ω resistor is connected between this pin and ground to set the swing to 800mV.

Submit Documentation Feedback



The PLL loop filter is external for the SER. A capacitor is connected in series to a resistor between the LF_CP and LF_REF pins. Typical values are 500 Ω and 0.1 μ F.

There are several configuration pins that requiring setting to the proper level. The RSVD_H pins should be pulled High to the 3.3V rail with a 5 k Ω resistor. Depending upon the application the DVB_ASI pin may be tied off or driven.

There are three supply connections (see PLL FILTER / BYPASS and for recommendations). The two main supplies are the 3.3V rail and the 2.5V rail. There is also a 3.3V connection for the PLL circuitry.

There are multiple Ground connections for the device. The main ground connection for the SER is through the large center DAP pad. This **must** be connected to ground for proper device operation. In addition, multiple other inputs are required to be connected to ground as show in Figure 14 and listed in .

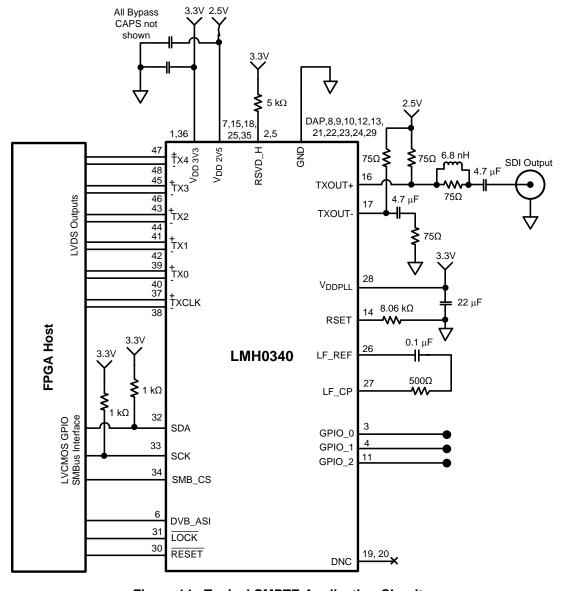


Figure 14. Typical SMPTE Application Circuit

TYPICAL LMH0050 CML APPLICATIONS CIRCUIT

A typical application circuit for the LMH0050 is shown in Figure 15.



The TX interface between the host FPGA and the SER is composed of a 5-bit LVDS Data bus and its LVDS clock. This is a point-to-point interface and the SER includes on-chip 100 terminations. Pairs should be of equal length to minimize any skew impact. The LVDS clock (TXCLK) uses both edges to transfer the data.

An SMBus is also connected from the host FPGA to the SER. If the SMBus is shared, a chip select signal is used to select the device being addressed. The SCLK and SDA signals require a pull up resistor. The SMB_CS is driven by a GPO signal from the FPGA. Depending on the FPGA I/O it may also require a pull up unless it is a push / pull output.

Depending upon the application, several other GPIO signals maybe used. This includes the DVB_ASI and RESET input signals. If these pins are not used, then must be tied off to the desired state. The LOCK signal maybe used to monitor the SER. If it is unused, leave the pin as a NC (or route to a test point).

The LMH0050 SER includes a CML cable driver. This is a differential driver, and includes internal 50 Ω pull up resistors to the 2.5V rail. The output voltage amplitude of the cable driver is set by the R_{SET} resistor. The R_{SET} resistor recommended value for the LMH0050 is 9.1K Ω . It is intended to drive 100 Ω differential pairs or twisted pair cables.

The PLL loop filter is external for the SER. A capacitor is connected in series to a resistor between the LF_CP and LF_REF pins. Typical values are 500 Ω and 0.1 μ F.

There are several configuration pins that requiring setting to the proper level. The RSVD_H pins should be pulled High to the 3.3V rail with a 5 k Ω resistor. Depending upon the application the DVB_ASI pin may be tied off or driven.

There are three supply connections (see PLL FILTER / BYPASS and for recommendations). The two main supplies are the 3.3V rail and the 2.5V rail. There is also a 3.3V connection for the PLL circuitry.

There are multiple Ground connections for the device. The main ground connection for the SER is through the large center DAP pad. This **must** be connected to ground for proper device operation. In addition, multiple other inputs are required to be connected to ground as show in Figure 15 and listed in .

Submit Documentation Feedback



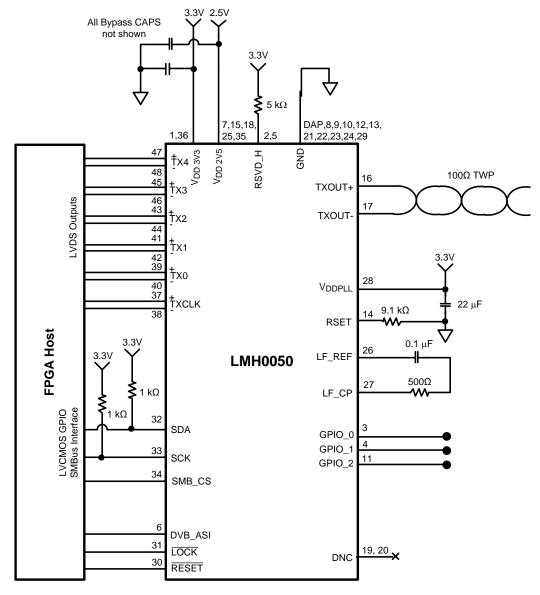


Figure 15. Typical LMH0050 CML Application Circuit

SERIAL JITTER OPTIMIZATION

The SER is capable of very low jitter operation, however it is dependent on the TXCLK provided by the host in order to operate, and depending on the quality of the TXCLK provided, the SER output jitter may not be as low as it could be.

The SER includes circuitry to filter out any TXCLK jitter at frequencies above 1MHz (see Figure 16), however, for frequencies below 100 kHz, any jitter that is in the TXCLK is passed directly through to the serialized output.

In most cases, passing the TXCLK through the FPGA will add high frequency noise to the signal, which will be filtered out by the SER, resulting in a clean output, however for better jitter performance, it is best to minimize the noise that is on the TXCLK that is provided to the SER. This can be done by careful routing of the CLK signals, both within the FPGA and on the board.

Very clean clocks can be derived from video reference signals through the use of the LMH1981 Sync Separator and the LMH1982 Clock Generator products from Texas Instruments. These products allow low jitter video frequency clocks to be generated either independently, or phase locked to a video reference signal.



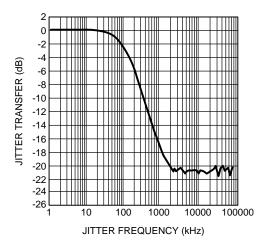


Figure 16. SER Jitter Transfer Function

Register Descriptions

Table 2 provides details on the device's configuration registers.

Table 2. SER Register Detail Table

ADD 'h	Name	Bits	Field	R/W	Default	Description						
00	device_identification	but this ma		3 of this reg	ister must always	r the device – the default value is 0x57'h, ays be '0' Note that since the address is AE'h.						
		7:1	device id	r/w	57'h	SMBus device ID						
		0	Reserved		0'b							
01	reset	the same a this register Bit 4 of this	in a '1' is written to bit 0 (LSB) of this register the device will do a soft reset, restoring it's internal state to the same as at powerup except device_id register. Once the reset operation is complete, the value in his register is reset to '0' bit 4 of this register has a default of 0, if a '1' is written to this location it will disable the analog output outfer of the device, allowing for some power savings.									
		7:5	Reserved									
		4	Analog Dis		0'b	Disables Analog						
		3:1	Reserved									
		0	sw_rst	r/w	0'b	software reset						
02	GPIO_0 Configuration	This register configures GPIO_0. Note, if this pin is to be used as an input, then the output must be TRI-STATE (bit[0]='0') and if used as an output, then the input buffer must be disabled (bit[1]='0').										
		7:4	GPIO_0_mode[3:0]	r/w	0000'b	0000: GPout register 0011: TXCLK LOS 0100: TXCLK Detect 0110: Power On Reset all others: reserved						
		3:2	GPIO_0_ren[1:0]	r/w	01'b	00: pullup and pulldown disabled 01: pulldown enabled 10: pullup enabled 11: Reserved						
		1	GPIO_0_sleepz	r/w	0'b	0: input buffer disabled 1: input buffer enabled						
		0	GPout0 enable	r/w	1'b	0: output TRI-STATE 1: output enabled						



Table 2. SER Register Detail Table (continued)

ADD 'h	Name	Bits	Field	R/W	Default	Description
03	GPIO_1 Configuration					as an input, then the output must be TRI- fer must be disabled (bit[1]='0').
		7:4	GPIO_1_mode[3:0]	r/w	0000'b	0000: Power On Reset 0001: GPout register 0010: pll lock 0100: Data LOS [0] 0101: Data LOS [1] 0110: Data LOS [2] 0111: Data LOS [3] 1000: Data LOS [4] all others: reserved
		3:2	GPIO_1_ren[1:0]	r/w	01'b	00: pullup and pulldown disabled 01: pulldown enabled 10: pullup enabled 11: Reserved
		1	GPIO_1_sleepz	r/w	0'b	0: input buffer disabled 1: input buffer enabled
		0	GPout1 enable	r/w	1'b	0: output in TRI-STATE mode 1: output enabled
04	GPIO_2 Configuration					as an input, then the output must be TRI- fer must be disabled (bit[1]='0').
		7:4	GPIO_2_mode[3:0]	r/w	0000'b	0000: GPout register 0001: always on out 0010: parallel to serial clk out 0011: parallel clock output 0100: TXCLK Digital out all others: reserved
		3:2	GPIO_2_ren[1:0]	r/w	01'b	00: pullup and pulldown disabled 01: pulldown enabled 10: pullup enabled 11: Reserved
		1	GPIO_2_sleepz	r/w	0'b	0: input buffer disabled 1: input buffer enabled
		0	GPout2 enable	r/w	0'b	0: output TRI-STATEd 1: output enabled
05	GP INPUT	If any of the those input		d as inputs	, then reading	from this register provides the values on
		7:3	Reserved			
		2		r		input data on GPIO_2
		1		r		input data on GPIO_1
		0		r		input data on GPIO_0
06	GP OUTPUT					s, then writing to this register has the rs of the appropriate GPIO pins.
		7:3	Reserved			
		2		r/w	0'b	output data on GPIO_2
		1		r/w	0'b	output data on GPIO_1
		0		r/w	0'b	output data on GPIO_0
07–10	Reserved	1	1	1	ıt.	
11	DVB_ASI Idle_A					datastream when there is no valid data to t can be redefined via this register pair.
		7:0		r/w	BC'h	K28.5 Idle character used for DVB_ASI
12	DVB_ASI Idle_B	DVB-ASI m	ode, idle character LSBs			
		7:2	Reserved			
		1:0		r/w	01'b	K28.5 Idle character used for DVB_ASI
13–1C	Reserved					



Table 2. SER Register Detail Table (continued)

ADD			2. SER Register D		<u> </u>							
'h	Name	Bits	Field	R/W	Default	Description						
1D	Device Type	Reading fr being addr	ū	an 8 bit va	lue which indi	cates which product from the SER family is						
		7:0	Device	r		xx1xxx00 for the LMH0340 xx1xxx01 for the LMH0040 xx1xxx10 for the LMH0070 xx0xxx01 for the LMH0050						
1E-20	Reserved					1						
21	Mode	This regist	er returns the mode that t	he device is	operating in.							
		7:2	Reserved									
		1:0		r/w		11 = DVB ASI mode 01,10, 00 = SDI mode						
22	DVB_ASI Override	register, th	In normal operation, the DVB_ASI mode is selected via the external pin. By setting the 0 bit in this register, the function of this pin is overridden, and the mode is set via register 21'h instead. After setting this bit, a channel reset must be executed via reg 0x26h, bit 7									
		7:1	Reserved									
		0		r/w	0'b	1: contents of register 21h will override the DVB_ASI pin 0: Pin control						
23	Reserved											
24	LVDS Clock Delay	This regist	er selects of the TXCLK d	elay adjust	is enabled or	bypassed.						
	Bypass	7		r/w	0'b	1: Bypasses TXCLK delay 0: Delay Enabled						
		6:0	Reserved									
25	Reserved											
26	Powerdown	Individual bits from this register can power down different parts of the SER – to place the part into a low power standby mode, write a '0' to this register.										
		7	channel reset	r/w	0'b	Used to reset the channel, needed when changing between DVB_ASI mode and normal operating mode via SMBus						
		6:0	Powerdown	r/w	0x3Fh	for normal operation, write x011 1111b to this register. For low power mode write x100 0000b to the register.						
27	Event Disable	The SER keeps counts of various types of events. These include FIFO over/underflows, and loss of the input signals or clocks. This register allows the user to mask these errors from being counted.										
		7:5	Reserved									
		4	PLL_CLK_disable	r/w	0'b	Clock Error disabled Clock Errors counted						
		3	fifo_error_disable	r/w	0'b	1: FIFO Errors ignored 0: FIFO Errors counted						
		2	TXCLK_detect_disable	r/w	0'b	1: TXCLK Detect Errors ignored 0: TXCLK Detect Errors counted						
		1	CLK_LOS_disable	r/w	0'b	1: CLK_LOS Errors ignored 0: CLK_LOS Errors counted						
		0	Data_LOS_disable	r/w	0'b	Data_LOS Errors ignored Data_LOS Errors counted						
28	LVDS LOS Override	These bits	are used to force the LOS	S indicator i	egardless of t	he input signal level on the LVDS pins.						
	Operation	7:2	Reserved									
		1	LVDS Preset LOS	r/w	0'b	LVDS Preset LOS 1: Forces LOS to be Low 0: normal mode						
		0	LVDS Reset LOS	r/w	0'b	LVDS Reset LOS (has priority over Preset) 1: Forces LOS to be High 0: normal mode						

Submit Documentation Feedback



Table 2. SER Register Detail Table (continued)

ADD 'h	Name	Bits	Field	R/W	Default	Description						
29	LOS Status		the LOS status register w of a signal at each of the			as six bits which represent the presence or						
		7:6	Reserved									
		5	LOS_CLK	r	0'b	No clock present on TXCLK Clock present						
		4:0	LOS_Data	r	0'b	1:No data present 0: Data Present(one bit per TX channel)						
2A	Event Status		The event status register has two user readable bits which indicate if the device is locked, and if there is a signal present on the TXCLK input.									
		7:4	Reserved									
		3	TXCLK_detect	r	0'b	1: TXCLK detected 0: TXCLK not detected						
		2	PLL_lock	r	0'b	1: PLL locked 0: PLL not locked						
		1:0	Reserved									
2B-2D	Reserved		•	•	·	•						
2E	Reverse Bit Order	This bit can be used to reverse the serialization order, however it will only work properly when the device is NOT in DVB_ASI mode										
		7	Reserved									
		6	Reverse Bit Order	r/w	0'b	1: reverses serialization order 0: normal order						
		5:0	Reserved									
2F	Reserved		•	·	•	•						
30	CLK_Delay	host FP0		uate setup		ammable delay into the TXCLK path, if the s for the SER, this register can be used to						
		7:5	TCLK Delay	r/w	011'b	000'b is minimum delay setting, 111'b is maximum delay setting, each step is approx 125ps						
		4:0	Reserved									

SNLS271I - APRIL 2007 - REVISED APRIL 2013



www.ti.com

REVISION HISTORY

Cr	hanges from Revision H (April 2013) to Revision I					
•	Changed layout of National Data Sheet to TI format	2	23			

Submit Documentation Feedback

24





17-Apr-2013

PACKAGING INFORMATION

Orderable Device	Status	Package Type	_	Pins	_	Eco Plan	Lead/Ball Finish	MSL Peak Temp	Op Temp (°C)	Top-Side Markings	Samples
	(1)		Drawing		Qty	(2)		(3)		(4)	
LMH0040SQ/NOPB	ACTIVE	WQFN	RHS	48	1000	Green (RoHS & no Sb/Br)	CU SN	Level-3-260C-168 HR	-40 to 85	LMH0040	Samples
LMH0040SQE/NOPB	ACTIVE	WQFN	RHS	48	250	Green (RoHS & no Sb/Br)	CU SN	Level-3-260C-168 HR	-40 to 85	LMH0040	Samples
LMH0040SQX/NOPB	ACTIVE	WQFN	RHS	48	2500	Green (RoHS & no Sb/Br)	CU SN	Level-3-260C-168 HR	-40 to 85	LMH0040	Samples
LMH0050SQ/NOPB	ACTIVE	WQFN	RHS	48	1000	Green (RoHS & no Sb/Br)	CU SN	Level-3-260C-168 HR	-40 to 85	LMH0050	Samples
LMH0050SQE/NOPB	ACTIVE	WQFN	RHS	48	250	Green (RoHS & no Sb/Br)	CU SN	Level-3-260C-168 HR	-40 to 85	LMH0050	Samples
LMH0050SQX/NOPB	ACTIVE	WQFN	RHS	48	2500	Green (RoHS & no Sb/Br)	CU SN	Level-3-260C-168 HR	-40 to 85	LMH0050	Samples
LMH0070SQ/NOPB	ACTIVE	WQFN	RHS	48	1000	Green (RoHS & no Sb/Br)	CU SN	Level-3-260C-168 HR	-40 to 85	LMH0070	Samples
LMH0070SQE/NOPB	ACTIVE	WQFN	RHS	48	250	Green (RoHS & no Sb/Br)	CU SN	Level-3-260C-168 HR	-40 to 85	LMH0070	Samples
LMH0070SQX/NOPB	ACTIVE	WQFN	RHS	48	2500	Green (RoHS & no Sb/Br)	CU SN	Level-3-260C-168 HR	-40 to 85	LMH0070	Samples
LMH0340SQ/NOPB	ACTIVE	WQFN	RHS	48	1000	Green (RoHS & no Sb/Br)	CU SN	Level-3-260C-168 HR	-40 to 85	L0340	Samples
LMH0340SQE/NOPB	ACTIVE	WQFN	RHS	48	250	Green (RoHS & no Sb/Br)	CU SN	Level-3-260C-168 HR	-40 to 85	L0340	Samples
LMH0340SQX/NOPB	ACTIVE	WQFN	RHS	48	2500	Green (RoHS & no Sb/Br)	CU SN	Level-3-260C-168 HR	-40 to 85	L0340	Samples

⁽¹⁾ The marketing status values are defined as follows:

ACTIVE: Product device recommended for new designs.

LIFEBUY: TI has announced that the device will be discontinued, and a lifetime-buy period is in effect.

NRND: Not recommended for new designs. Device is in production to support existing customers, but TI does not recommend using this part in a new design.

PREVIEW: Device has been announced but is not in production. Samples may or may not be available.

OBSOLETE: TI has discontinued the production of the device.

TBD: The Pb-Free/Green conversion plan has not been defined.

⁽²⁾ Eco Plan - The planned eco-friendly classification: Pb-Free (RoHS), Pb-Free (RoHS Exempt), or Green (RoHS & no Sb/Br) - please check http://www.ti.com/productcontent for the latest availability information and additional product content details.



PACKAGE OPTION ADDENDUM

17-Apr-2013

Pb-Free (RoHS): TI's terms "Lead-Free" or "Pb-Free" mean semiconductor products that are compatible with the current RoHS requirements for all 6 substances, including the requirement that lead not exceed 0.1% by weight in homogeneous materials. Where designed to be soldered at high temperatures, TI Pb-Free products are suitable for use in specified lead-free processes. **Pb-Free** (RoHS Exempt): This component has a RoHS exemption for either 1) lead-based flip-chip solder bumps used between the die and package, or 2) lead-based die adhesive used between the die and leadframe. The component is otherwise considered Pb-Free (RoHS compatible) as defined above.

Green (RoHS & no Sb/Br): TI defines "Green" to mean Pb-Free (RoHS compatible), and free of Bromine (Br) and Antimony (Sb) based flame retardants (Br or Sb do not exceed 0.1% by weight in homogeneous material)

(3) MSL, Peak Temp. -- The Moisture Sensitivity Level rating according to the JEDEC industry standard classifications, and peak solder temperature.

(4) Multiple Top-Side Markings will be inside parentheses. Only one Top-Side Marking contained in parentheses and separated by a "~" will appear on a device. If a line is indented then it is a continuation of the previous line and the two combined represent the entire Top-Side Marking for that device.

Important Information and Disclaimer: The information provided on this page represents TI's knowledge and belief as of the date that it is provided. TI bases its knowledge and belief on information provided by third parties, and makes no representation or warranty as to the accuracy of such information. Efforts are underway to better integrate information from third parties. TI has taken and continues to take reasonable steps to provide representative and accurate information but may not have conducted destructive testing or chemical analysis on incoming materials and chemicals. TI and TI suppliers consider certain information to be proprietary, and thus CAS numbers and other limited information may not be available for release.

In no event shall TI's liability arising out of such information exceed the total purchase price of the TI part(s) at issue in this document sold by TI to Customer on an annual basis.

PACKAGE MATERIALS INFORMATION

www.ti.com 24-Apr-2013

TAPE AND REEL INFORMATION





	Dimension designed to accommodate the component width
	Dimension designed to accommodate the component length
K0	Dimension designed to accommodate the component thickness
W	Overall width of the carrier tape
P1	Pitch between successive cavity centers

QUADRANT ASSIGNMENTS FOR PIN 1 ORIENTATION IN TAPE



*All dimensions are nominal

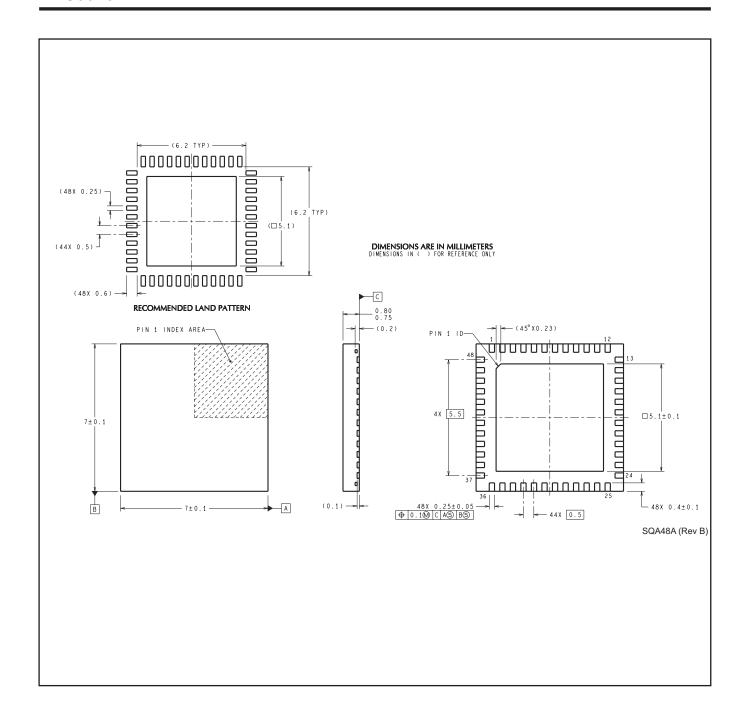
Device	Package Type	Package Drawing		SPQ	Reel Diameter (mm)	Reel Width W1 (mm)	A0 (mm)	B0 (mm)	K0 (mm)	P1 (mm)	W (mm)	Pin1 Quadrant
LMH0040SQ/NOPB	WQFN	RHS	48	1000	330.0	16.4	7.3	7.3	1.3	12.0	16.0	Q1
LMH0040SQE/NOPB	WQFN	RHS	48	250	178.0	16.4	7.3	7.3	1.3	12.0	16.0	Q1
LMH0040SQX/NOPB	WQFN	RHS	48	2500	330.0	16.4	7.3	7.3	1.3	12.0	16.0	Q1
LMH0050SQ/NOPB	WQFN	RHS	48	1000	330.0	16.4	7.3	7.3	1.3	12.0	16.0	Q1
LMH0050SQE/NOPB	WQFN	RHS	48	250	178.0	16.4	7.3	7.3	1.3	12.0	16.0	Q1
LMH0050SQX/NOPB	WQFN	RHS	48	2500	330.0	16.4	7.3	7.3	1.3	12.0	16.0	Q1
LMH0070SQ/NOPB	WQFN	RHS	48	1000	330.0	16.4	7.3	7.3	1.3	12.0	16.0	Q1
LMH0070SQE/NOPB	WQFN	RHS	48	250	178.0	16.4	7.3	7.3	1.3	12.0	16.0	Q1
LMH0070SQX/NOPB	WQFN	RHS	48	2500	330.0	16.4	7.3	7.3	1.3	12.0	16.0	Q1
LMH0340SQ/NOPB	WQFN	RHS	48	1000	330.0	16.4	7.3	7.3	1.3	12.0	16.0	Q1
LMH0340SQE/NOPB	WQFN	RHS	48	250	178.0	16.4	7.3	7.3	1.3	12.0	16.0	Q1
LMH0340SQX/NOPB	WQFN	RHS	48	2500	330.0	16.4	7.3	7.3	1.3	12.0	16.0	Q1

www.ti.com 24-Apr-2013



*All dimensions are nominal

Device	Package Type	Package Drawing	Pins	SPQ	Length (mm)	Width (mm)	Height (mm)
LMH0040SQ/NOPB	WQFN	RHS	48	1000	367.0	367.0	38.0
LMH0040SQE/NOPB	WQFN	RHS	48	250	213.0	191.0	55.0
LMH0040SQX/NOPB	WQFN	RHS	48	2500	367.0	367.0	38.0
LMH0050SQ/NOPB	WQFN	RHS	48	1000	367.0	367.0	38.0
LMH0050SQE/NOPB	WQFN	RHS	48	250	213.0	191.0	55.0
LMH0050SQX/NOPB	WQFN	RHS	48	2500	367.0	367.0	38.0
LMH0070SQ/NOPB	WQFN	RHS	48	1000	367.0	367.0	38.0
LMH0070SQE/NOPB	WQFN	RHS	48	250	213.0	191.0	55.0
LMH0070SQX/NOPB	WQFN	RHS	48	2500	367.0	367.0	38.0
LMH0340SQ/NOPB	WQFN	RHS	48	1000	367.0	367.0	38.0
LMH0340SQE/NOPB	WQFN	RHS	48	250	213.0	191.0	55.0
LMH0340SQX/NOPB	WQFN	RHS	48	2500	367.0	367.0	38.0



IMPORTANT NOTICE

Texas Instruments Incorporated and its subsidiaries (TI) reserve the right to make corrections, enhancements, improvements and other changes to its semiconductor products and services per JESD46, latest issue, and to discontinue any product or service per JESD48, latest issue. Buyers should obtain the latest relevant information before placing orders and should verify that such information is current and complete. All semiconductor products (also referred to herein as "components") are sold subject to TI's terms and conditions of sale supplied at the time of order acknowledgment.

TI warrants performance of its components to the specifications applicable at the time of sale, in accordance with the warranty in TI's terms and conditions of sale of semiconductor products. Testing and other quality control techniques are used to the extent TI deems necessary to support this warranty. Except where mandated by applicable law, testing of all parameters of each component is not necessarily performed.

TI assumes no liability for applications assistance or the design of Buyers' products. Buyers are responsible for their products and applications using TI components. To minimize the risks associated with Buyers' products and applications, Buyers should provide adequate design and operating safeguards.

TI does not warrant or represent that any license, either express or implied, is granted under any patent right, copyright, mask work right, or other intellectual property right relating to any combination, machine, or process in which TI components or services are used. Information published by TI regarding third-party products or services does not constitute a license to use such products or services or a warranty or endorsement thereof. Use of such information may require a license from a third party under the patents or other intellectual property of the third party, or a license from TI under the patents or other intellectual property of TI.

Reproduction of significant portions of TI information in TI data books or data sheets is permissible only if reproduction is without alteration and is accompanied by all associated warranties, conditions, limitations, and notices. TI is not responsible or liable for such altered documentation. Information of third parties may be subject to additional restrictions.

Resale of TI components or services with statements different from or beyond the parameters stated by TI for that component or service voids all express and any implied warranties for the associated TI component or service and is an unfair and deceptive business practice. TI is not responsible or liable for any such statements.

Buyer acknowledges and agrees that it is solely responsible for compliance with all legal, regulatory and safety-related requirements concerning its products, and any use of TI components in its applications, notwithstanding any applications-related information or support that may be provided by TI. Buyer represents and agrees that it has all the necessary expertise to create and implement safeguards which anticipate dangerous consequences of failures, monitor failures and their consequences, lessen the likelihood of failures that might cause harm and take appropriate remedial actions. Buyer will fully indemnify TI and its representatives against any damages arising out of the use of any TI components in safety-critical applications.

In some cases, TI components may be promoted specifically to facilitate safety-related applications. With such components, TI's goal is to help enable customers to design and create their own end-product solutions that meet applicable functional safety standards and requirements. Nonetheless, such components are subject to these terms.

No TI components are authorized for use in FDA Class III (or similar life-critical medical equipment) unless authorized officers of the parties have executed a special agreement specifically governing such use.

Only those TI components which TI has specifically designated as military grade or "enhanced plastic" are designed and intended for use in military/aerospace applications or environments. Buyer acknowledges and agrees that any military or aerospace use of TI components which have *not* been so designated is solely at the Buyer's risk, and that Buyer is solely responsible for compliance with all legal and regulatory requirements in connection with such use.

TI has specifically designated certain components as meeting ISO/TS16949 requirements, mainly for automotive use. In any case of use of non-designated products, TI will not be responsible for any failure to meet ISO/TS16949.

Products Applications

Audio www.ti.com/audio Automotive and Transportation www.ti.com/automotive Communications and Telecom **Amplifiers** amplifier.ti.com www.ti.com/communications **Data Converters** dataconverter.ti.com Computers and Peripherals www.ti.com/computers **DLP® Products** www.dlp.com Consumer Electronics www.ti.com/consumer-apps

DSP **Energy and Lighting** dsp.ti.com www.ti.com/energy Clocks and Timers www.ti.com/clocks Industrial www.ti.com/industrial Interface interface.ti.com Medical www.ti.com/medical logic.ti.com Logic Security www.ti.com/security

Power Mgmt power.ti.com Space, Avionics and Defense www.ti.com/space-avionics-defense

Microcontrollers microcontroller.ti.com Video and Imaging www.ti.com/video

RFID www.ti-rfid.com

OMAP Applications Processors <u>www.ti.com/omap</u> TI E2E Community <u>e2e.ti.com</u>

Wireless Connectivity <u>www.ti.com/wirelessconnectivity</u>