

## 16-BIT, 1.25 MSPS, UNIPOLAR DIFFERENTIAL INPUT, MICRO POWER SAMPLING ANALOG-TO-DIGITAL CONVERTER WITH PARALLEL INTERFACE AND REFERENCE

### FEATURES

- 1.25-MHz Sample Rate
- 16-Bit NMC Ensured Over Temperature
- Zero Latency
- Unipolar Differential Input Range:  $V_{ref}$  to  $-V_{ref}$
- Onboard Reference
- Onboard Reference Buffer
- High-Speed Parallel Interface
- Power Dissipation: 155 mW at 1.25 MHz Typ
- Wide Digital Supply
- 8-/16-Bit Bus Transfer
- 48-Pin TQFP Package

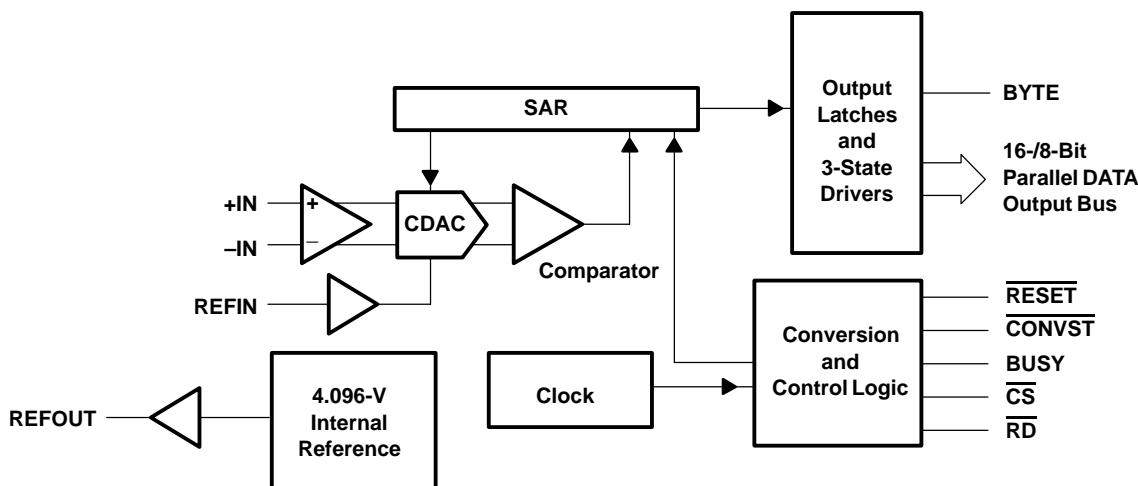
### APPLICATIONS

- DWDM
- Instrumentation
- High-Speed, High-Resolution, Zero Latency Data Acquisition Systems
- Transducer Interface
- Medical Instruments
- Communication

### DESCRIPTION

The ADS8402 is a 16-bit, 1.25 MHz A/D converter with an internal 4.096-V reference. The device includes a 16-bit capacitor-based SAR A/D converter with inherent sample and hold. The ADS8402 offers a full 16-bit interface and an 8-bit option where data is read using two 8-bit read cycles.

The ADS8402 has a unipolar differential input. It is available in a 48-lead TQFP package and is characterized over the industrial  $-40^{\circ}\text{C}$  to  $85^{\circ}\text{C}$  temperature range.



Please be aware that an important notice concerning availability, standard warranty, and use in critical applications of Texas Instruments semiconductor products and disclaimers thereto appears at the end of this data sheet.



These devices have limited built-in ESD protection. The leads should be shorted together or the device placed in conductive foam during storage or handling to prevent electrostatic damage to the MOS gates.

## ORDERING INFORMATION

MODEL	MAXIMUM INTEGRAL LINEARITY (LSB)	MAXIMUM DIFFERENTIAL LINEARITY (LSB)	NO MISSING CODES RESOLUTION (BIT)	PACKAGE TYPE	PACKAGE DESIGNATOR	TEMPERATURE RANGE	ORDERING INFORMATION	TRANSPORT MEDIA QUANTITY
ADS8402I	$\pm 6$	$-2 \sim +3$	15	48 Pin TQFP	PFB	$-40^{\circ}\text{C}$ to $85^{\circ}\text{C}$	ADS8402IPFBT	Tape and reel 250
							ADS8402IPFBR	Tape and reel 1000
ADS8402IB	$\pm 3.5$	$-1 \sim +2$	16	48 Pin TQFP	PFB	$-40^{\circ}\text{C}$ to $85^{\circ}\text{C}$	ADS8402IBPFBT	Tape and reel 250
							ADS8402IBPFBR	Tape and reel 1000

NOTE: For the most current specifications and package information, refer to our website at [www.ti.com](http://www.ti.com).

## ABSOLUTE MAXIMUM RATINGS

over operating free-air temperature range unless otherwise noted<sup>(1)</sup>

		UNIT
Voltage	+IN to AGND	+VA + 0.1 V
	–IN to AGND	+VA + 0.1 V
Voltage range	+VA to AGND	–0.3 V to 7 V
	+VBD to BDGND	–0.3 V to 7 V
	+VA to +VBD	–0.3 V to 2.5 V
Digital input voltage to BDGND		–0.3 V to +VBD + 0.3 V
Digital output voltage to BDGND		–0.3 V to +VBD + 0.3 V
Operating free-air temperature range, $T_A$		$-40^{\circ}\text{C}$ to $85^{\circ}\text{C}$
Storage temperature range, $T_{\text{stg}}$		$-65^{\circ}\text{C}$ to $150^{\circ}\text{C}$
Junction temperature ( $T_J$ max)		$150^{\circ}\text{C}$
TQFP package	Power dissipation	$(T_{J\text{Max}} - T_A)/\theta_{JA}$
	$\theta_{JA}$ thermal impedance	$86^{\circ}\text{C/W}$
Lead temperature, soldering	Vapor phase (60 sec)	$215^{\circ}\text{C}$
	Infrared (15 sec)	$220^{\circ}\text{C}$

(1) Stresses beyond those listed under “absolute maximum ratings” may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated under “recommended operating conditions” is not implied. Exposure to absolute-maximum-rated conditions for extended periods may affect device reliability.

## SPECIFICATIONS

 $T_A = -40^{\circ}\text{C}$  to  $85^{\circ}\text{C}$ ,  $+V_A = 5\text{ V}$ ,  $+V_{BD} = 3\text{ V}$  or  $5\text{ V}$ ,  $V_{\text{ref}} = 4.096\text{ V}$ ,  $f_{\text{SAMPLE}} = 1.25\text{ MHz}$  (unless otherwise noted)

PARAMETER		TEST CONDITIONS	MIN	TYP	MAX	UNIT
<b>Analog Input</b>						
Full-scale input voltage (see Note 1)		$+IN - -IN$	$-V_{\text{ref}}$		$V_{\text{ref}}$	V
Absolute input voltage		$+IN$	$-0.2$		$V_{\text{ref}} + 0.2$	V
		$-IN$	$-0.2$		$V_{\text{ref}} + 0.2$	
Common-mode input range	ADS8402I		$(V_{\text{ref}}/2) - 0.2$	$V_{\text{ref}}/2$	$(V_{\text{ref}}/2) + 0.2$	V
Input capacitance				25		pF
Input leakage current				0.5		nA
<b>System Performance</b>						
Resolution				16		Bits
No missing codes	ADS8402I		15			Bits
	ADS8402IB		16			
Integral linearity (see Notes 2 and 3)	ADS8402I		$-6$	$\pm 2.5$	6	LSB
	ADS8402IB		$-3.5$	$\pm 2$	3.5	
Differential linearity	ADS8402I		$-2$	$\pm 1$	3	LSB
	ADS8402IB		$-1$	$\pm 0.75$	2	
Offset error (see Note 4)	ADS8402I		$-3$	$\pm 1$	3	mV
	ADS8402IB		$-1.5$	$\pm 0.5$	1.5	mV
Gain error (see Notes 4 and 5)	ADS8402I		$-0.15$		0.15	%FS
	ADS8402IB		$-0.098$		0.098	
Common-mode rejection ratio		At dc ( $\pm 0.2\text{ V}$ around $V_{\text{ref}}/2$ )		80		dB
		$+IN - -IN = 1\text{ V}_{\text{pp}}$ at 1 MHz		80		
Noise				60		$\mu\text{V RMS}$
DC Power supply rejection ratio		At 7FFFh output code, $+V_A = 4.75\text{ V}$ to $5.25\text{ V}$ , $V_{\text{ref}} = 4.096\text{ V}$ , See Note 4		1		LSB
<b>Sampling Dynamics</b>						
Conversion time					610	ns
Acquisition time				150		ns
Throughput rate					1.25	MHz
Aperture delay				2		ns
Aperture jitter				25		ps
Step response				100		ns
Overvoltage recovery				100		ns

(1) Ideal input span, does not include gain or offset error.

(2) LSB means least significant bit

(3) This is endpoint INL, not best fit

(4) Measured relative to an ideal full-scale input ( $+IN - -IN$ ) of  $8.192\text{ V}$ 

(5) This specification does not include the internal reference voltage error and drift.

## SPECIFICATIONS (CONTINUED)

$T_A = -40^{\circ}\text{C}$  to  $85^{\circ}\text{C}$ ,  $+V_A = +5\text{ V}$ ,  $+V_{BD} = 3\text{ V}$  or  $5\text{ V}$ ,  $V_{\text{ref}} = 4.096\text{ V}$ ,  $f_{\text{SAMPLE}} = 1.25\text{ MHz}$  (unless otherwise noted)

PARAMETER		TEST CONDITIONS	MIN	TYP	MAX	UNIT
<b>Dynamic Characteristics</b>						
Total harmonic distortion (THD) (see Note 1)		$V_{\text{IN}} = 8\text{ V}_{\text{pp}}$ at 100 kHz		-95		dB
Signal-to-noise ratio (SNR)		$V_{\text{IN}} = 8\text{ V}_{\text{pp}}$ at 100 kHz		90		dB
Signal-to-noise + distortion (SINAD)		$V_{\text{IN}} = 8\text{ V}_{\text{pp}}$ at 100 kHz		88		dB
Spurious free dynamic range (SFDR)		$V_{\text{IN}} = 8\text{ V}_{\text{pp}}$ at 100 kHz		95		dB
-3dB Small signal bandwidth				5		MHz
<b>External Voltage Reference Input</b>						
Reference voltage at REFIN, $V_{\text{ref}}$			2.5	4.096	4.2	V
Reference resistance (see Note 2)				500		k $\Omega$
<b>Internal Reference Output</b>						
Internal reference start-up time		From 95% (+ $V_A$ ), with 1 $\mu\text{F}$ storage capacity			120	ms
$V_{\text{ref}}$ range		$\text{I}_{\text{OUT}} = 0$	4.065	4.096	4.13	V
<b>Source Current</b>		Static load			10	$\mu\text{A}$
<b>Line Regulation</b>		$+V_A = 4.75 \sim 5.25\text{ V}$		0.6		mV
Drift		$\text{I}_{\text{OUT}} = 0$		36		PPM/C
<b>Digital Input/Output</b>						
Logic family				CMOS		
Logic level	$V_{\text{IH}}$	$\text{I}_{\text{IH}} = 5\text{ }\mu\text{A}$	$+V_{\text{BD}} - 1$		$+V_{\text{BD}} + 0.3$	V
	$V_{\text{IL}}$	$\text{I}_{\text{IL}} = 5\text{ }\mu\text{A}$	-0.3		0.8	
	$V_{\text{OH}}$	$\text{I}_{\text{OH}} = 2\text{ TTL loads}$	$+V_{\text{BD}} - 0.6$		$+V_{\text{BD}}$	
	$V_{\text{OL}}$	$\text{I}_{\text{OL}} = 2\text{ TTL loads}$	0		0.4	
Data format				2's Complement		
<b>Power Supply Requirements</b>						
Power supply voltage	$+V_{\text{BD}}$ (see Notes 3 and 4)		2.95	3.3	5.25	V
	$+V_A$ (see Note 4)		4.75	5	5.25	V
$+V_A$ Supply current (see Note 5)		$f_s = 1.25\text{ MHz}$		31	34	mA
Power dissipation (see Note 5)		$f_s = 1.25\text{ MHz}$		155		mW
<b>Temperature Range</b>						
Operating free-air			-40		85	$^{\circ}\text{C}$

(1) Calculated on the first nine harmonics of the input frequency

(2) Can vary  $\pm 20\%$

(3) The difference between  $+V_A$  and  $+V_{\text{BD}}$  should not be less than 2.3 V, i.e., if  $+V_A$  is 5.25 V,  $+V_{\text{BD}}$  should be minimum of 2.95 V.

(4)  $+V_{\text{BD}} \geq +V_A - 2.3\text{ V}$

(5) This includes only  $V_A$  current.  $+V_{\text{BD}}$  current is typically 1 mA with 5 pF load capacitance on output pins.

## TIMING CHARACTERISTICS

All specifications typical at  $-40^{\circ}\text{C}$  to  $85^{\circ}\text{C}$ ,  $+V_A = +V_{BD} = 5\text{ V}$  (see Notes 1, 2, and 3)

PARAMETER		MIN	TYP	MAX	UNIT
$t_{\text{CONV}}$	Conversion time		600	610	ns
$t_{\text{ACQ}}$	Acquisition time	150			ns
$t_{\text{pd1}}$	$\overline{\text{CONVST}}$ low to conversion started (BUSY high)			35	ns
$t_{\text{pd2}}$	Propagation delay time, End of conversion to BUSY low			20	ns
$t_{\text{w1}}$	Pulse duration, $\overline{\text{CONVST}}$ low	20			ns
$t_{\text{su1}}$	Setup time, $\overline{\text{CS}}$ low to $\overline{\text{CONVST}}$ low	0			ns
$t_{\text{w2}}$	Pulse duration, $\overline{\text{CONVST}}$ high	20			ns
	$\overline{\text{CONVST}}$ falling edge jitter			10	ps
$t_{\text{w3}}$	Pulse duration, BUSY signal low	$\text{Min}(t_{\text{ACQ}})$			ns
$t_{\text{w4}}$	Pulse duration, BUSY signal high			630	ns
$t_{\text{h1}}$	Hold time, First data bus data transition ( $\overline{\text{RD}}$ low, or $\overline{\text{CS}}$ low for read cycle, or BYTE input changes) after $\overline{\text{CONVST}}$ low	40			ns
$t_{\text{d1}}$	Delay time, $\overline{\text{CS}}$ low to $\overline{\text{RD}}$ low	0			ns
$t_{\text{su2}}$	Setup time, $\overline{\text{RD}}$ high to $\overline{\text{CS}}$ high	0			ns
$t_{\text{w5}}$	Pulse duration, $\overline{\text{RD}}$ low time	50			ns
$t_{\text{en}}$	Enable time, $\overline{\text{RD}}$ low (or $\overline{\text{CS}}$ low for read cycle) to data valid			20	ns
$t_{\text{d2}}$	Delay time, data hold from $\overline{\text{RD}}$ high	0			ns
$t_{\text{d3}}$	Delay time, BYTE rising edge or falling edge to data valid	2		20	ns
$t_{\text{w6}}$	$\overline{\text{RD}}$ high	20			ns
$t_{\text{h2}}$	Hold time, last $\overline{\text{RD}}$ (or $\overline{\text{CS}}$ for read cycle) rising edge to $\overline{\text{CONVST}}$ falling edge	50			ns
$t_{\text{pd4}}$	Propagation delay time, BUSY falling edge to next $\overline{\text{RD}}$ (or $\overline{\text{CS}}$ for read cycle) falling edge	$\text{Max}(t_{\text{d5}})$			ns
$t_{\text{su3}}$	Setup time, BYTE rising edge to $\overline{\text{RD}}$ falling edge	0			ns
$t_{\text{h3}}$	Hold time, BYTE falling edge to $\overline{\text{RD}}$ falling edge	0			ns
$t_{\text{dis}}$	Disable time, $\overline{\text{RD}}$ High ( $\overline{\text{CS}}$ high for read cycle) to 3-stated data bus			20	ns
$t_{\text{d5}}$	Delay time, BUSY low to MSB data valid			0	ns

(1) All input signals are specified with  $t_r = t_f = 5\text{ ns}$  (10% to 90% of  $+V_{BD}$ ) and timed from a voltage level of  $(V_{\text{IL}} + V_{\text{IH}})/2$ .

(2) See timing diagrams.

(3) All timings are measured with 20 pF equivalent loads on all data bits and BUSY pins.

## TIMING CHARACTERISTICS

All specifications typical at  $-40^{\circ}\text{C}$  to  $85^{\circ}\text{C}$ ,  $+V_A = 5\text{ V}$ ,  $+V_{BD} = 3\text{ V}$  (see Notes 1, 2, and 3)

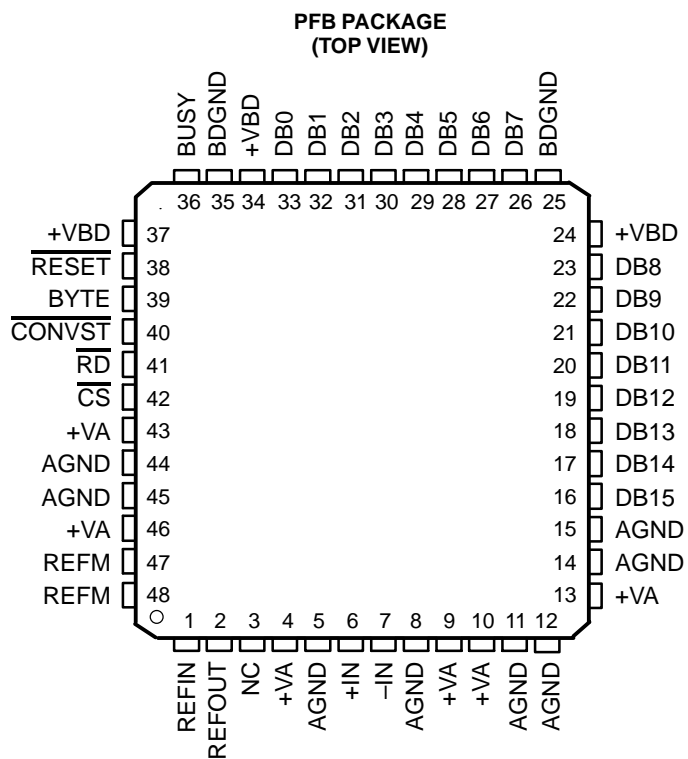
PARAMETER		MIN	TYP	MAX	UNIT
$t_{\text{CONV}}$	Conversion time		600	610	ns
$t_{\text{ACQ}}$	Acquisition time	150			ns
$t_{\text{pd1}}$	$\overline{\text{CONVST}}$ low to conversion started (BUSY high)			40	ns
$t_{\text{pd2}}$	Propagation delay time, end of conversion to BUSY low			20	ns
$t_{\text{w1}}$	Pulse duration, $\overline{\text{CONVST}}$ low	20			ns
$t_{\text{su1}}$	Setup time, $\overline{\text{CS}}$ low to $\overline{\text{CONVST}}$ low	0			ns
$t_{\text{w2}}$	Pulse duration, $\overline{\text{CONVST}}$ high	20			ns
	$\overline{\text{CONVST}}$ falling edge jitter			10	ps
$t_{\text{w3}}$	Pulse duration, BUSY signal low	$\text{Min}(t_{\text{ACQ}})$			ns
$t_{\text{w4}}$	Pulse duration, BUSY signal high			630	ns
$t_{\text{h1}}$	Hold time, first data bus transition ( $\overline{\text{RD}}$ low, or $\overline{\text{CS}}$ low for read cycle, or BYTE or BUS 16/16 input changes) after $\overline{\text{CONVST}}$ low	40			ns
$t_{\text{d1}}$	Delay time, $\overline{\text{CS}}$ low to $\overline{\text{RD}}$ low	0			ns
$t_{\text{su2}}$	Setup time, $\overline{\text{RD}}$ high to $\overline{\text{CS}}$ high	0			ns
$t_{\text{w5}}$	Pulse duration, $\overline{\text{RD}}$ low	50			ns
$t_{\text{en}}$	Enable time, $\overline{\text{RD}}$ low (or $\overline{\text{CS}}$ low for read cycle) to data valid			30	ns
$t_{\text{d2}}$	Delay time, data hold from $\overline{\text{RD}}$ high	0			ns
$t_{\text{d3}}$	Delay time, BUS 16/16 or BYTE rising edge or falling edge to data valid	2		30	ns
$t_{\text{w6}}$	Pulse duration, $\overline{\text{RD}}$ high time	20			ns
$t_{\text{h2}}$	Hold time, last $\overline{\text{RD}}$ (or $\overline{\text{CS}}$ for read cycle) rising edge to $\overline{\text{CONVST}}$ falling edge	50			ns
$t_{\text{pd4}}$	Propagation delay time, BUSY falling edge to next $\overline{\text{RD}}$ (or $\overline{\text{CS}}$ for read cycle) falling edge	$\text{Max}(t_{\text{d5}})$			ns
$t_{\text{su3}}$	Setup time, BYTE rising edge to $\overline{\text{RD}}$ falling edge	0			ns
$t_{\text{h3}}$	Hold time, BYTE falling edge to $\overline{\text{RD}}$ falling edge	0			ns
$t_{\text{dis}}$	Disable time, $\overline{\text{RD}}$ High ( $\overline{\text{CS}}$ high for read cycle) to 3-stated data bus			30	ns
$t_{\text{d5}}$	Delay time, BUSY low to MSB data valid delay time			0	ns

(1) All input signals are specified with  $t_r = t_f = 5\text{ ns}$  (10% to 90% of  $+V_{BD}$ ) and timed from a voltage level of  $(V_{IL} + V_{IH})/2$ .

(2) See timing diagrams.

(3) All timings are measured with 10 pF equivalent loads on all data bits and BUSY pins.

## PIN ASSIGNMENTS



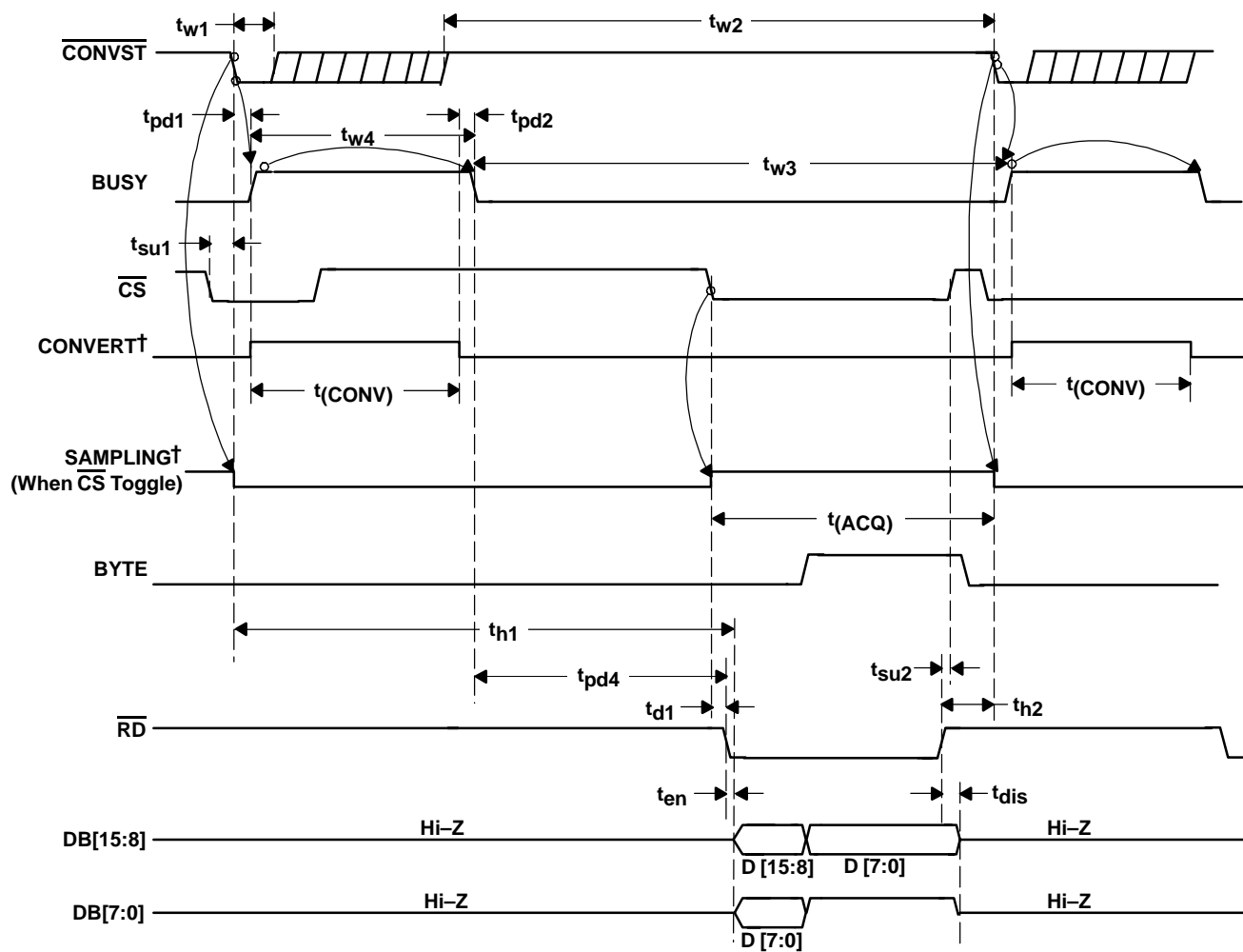
NC – No connection

## TERMINAL FUNCTIONS

NAME	NO.	I/O	DESCRIPTION		
AGND	5, 8, 11, 12, 14, 15, 44, 45	–	Analog ground		
BDGND	25, 35	–	Digital ground for bus interface digital supply		
BUSY	36	O	Status output. High when a conversion is in progress.		
BYTE	39	I	Byte select input. Used for 8-bit bus reading. 0: No fold back 1: Low byte D[7:0] of the 16 most significant bits is folded back to high byte of the 16 most significant pins DB[15:8].		
CONVST	40	I	Convert start		
CS	42	I	Chip select		
Data Bus			8-Bit Bus		16-Bit Bus
			BYTE = 0	BYTE = 1	BYTE = 0
DB15	16	O	D15 (MSB)	D7	D15 (MSB)
DB14	17	O	D14	D6	D14
DB13	18	O	D13	D5	D13
DB12	19	O	D12	D4	D12
DB11	20	O	D11	D3	D11
DB10	21	O	D10	D2	D10
DB9	22	O	D9	D1	D9
DB8	23	O	D8	D0 (LSB)	D8
DB7	26	O	D7	All ones	D7
DB6	27	O	D6	All ones	D6
DB5	28	O	D5	All ones	D5
DB4	29	O	D4	All ones	D4
DB3	30	O	D3	All ones	D3
DB2	31	O	D2	All ones	D2
DB1	32	O	D1	All ones	D1
DB0	33	O	D0 (LSB)	All ones	D0 (LSB)
–IN	7	I	Inverting input channel		
+IN	6	I	Non inverting input channel		
NC	3	–	No connection		
REFIN	1	I	Reference input		
REFM	47, 48	I	Reference ground		
REFOUT	2	O	Reference output. Add 1 $\mu$ F capacitor between the REFOUT pin and REFM pin when internal reference is used.		
RESET	38	I	Current conversion is aborted and output latches are cleared (set to zeros) when this pin is asserted low. RESET works independantly of CS.		
RD	41	I	Synchronization pulse for the parallel output.		
+VA	4, 9, 10, 13, 43, 46	–	Analog power supplies, 5-V dc		
+VBD	24, 34, 37	–	Digital power supply for bus		

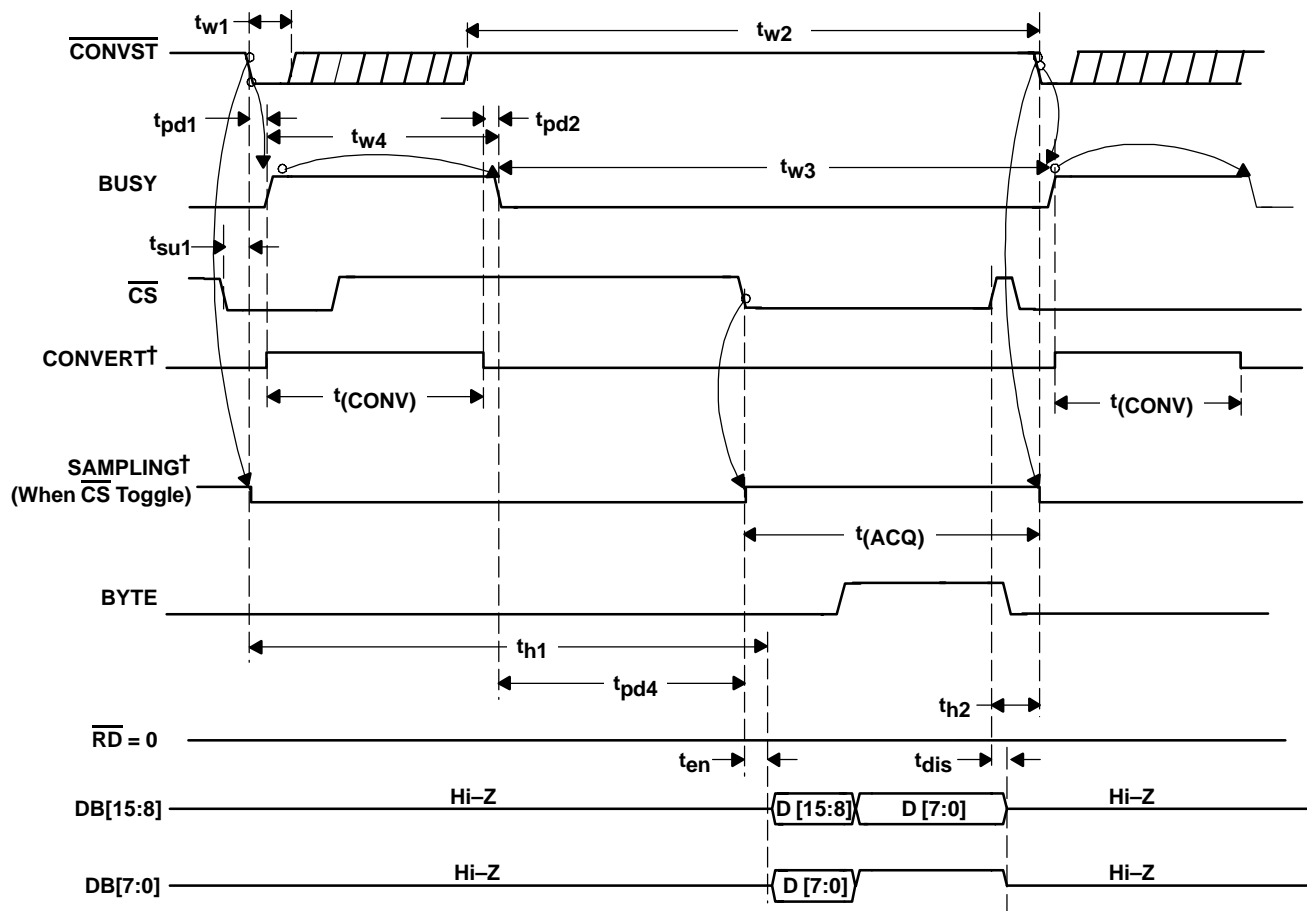


## TIMING DIAGRAMS



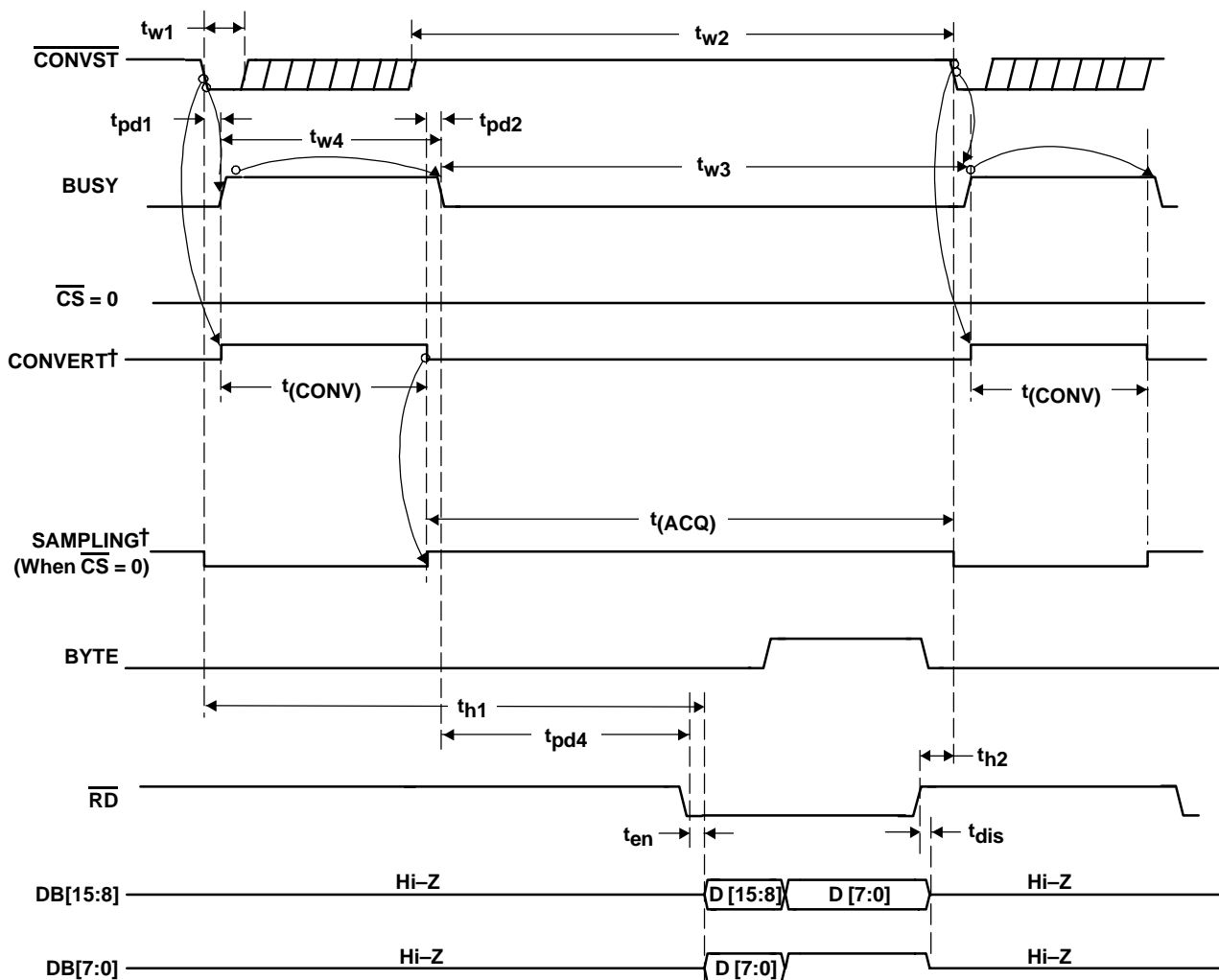
†Signal internal to device

Figure 1. Timing for Conversion and Acquisition Cycles With  $\overline{CS}$  and  $\overline{RD}$  Toggling



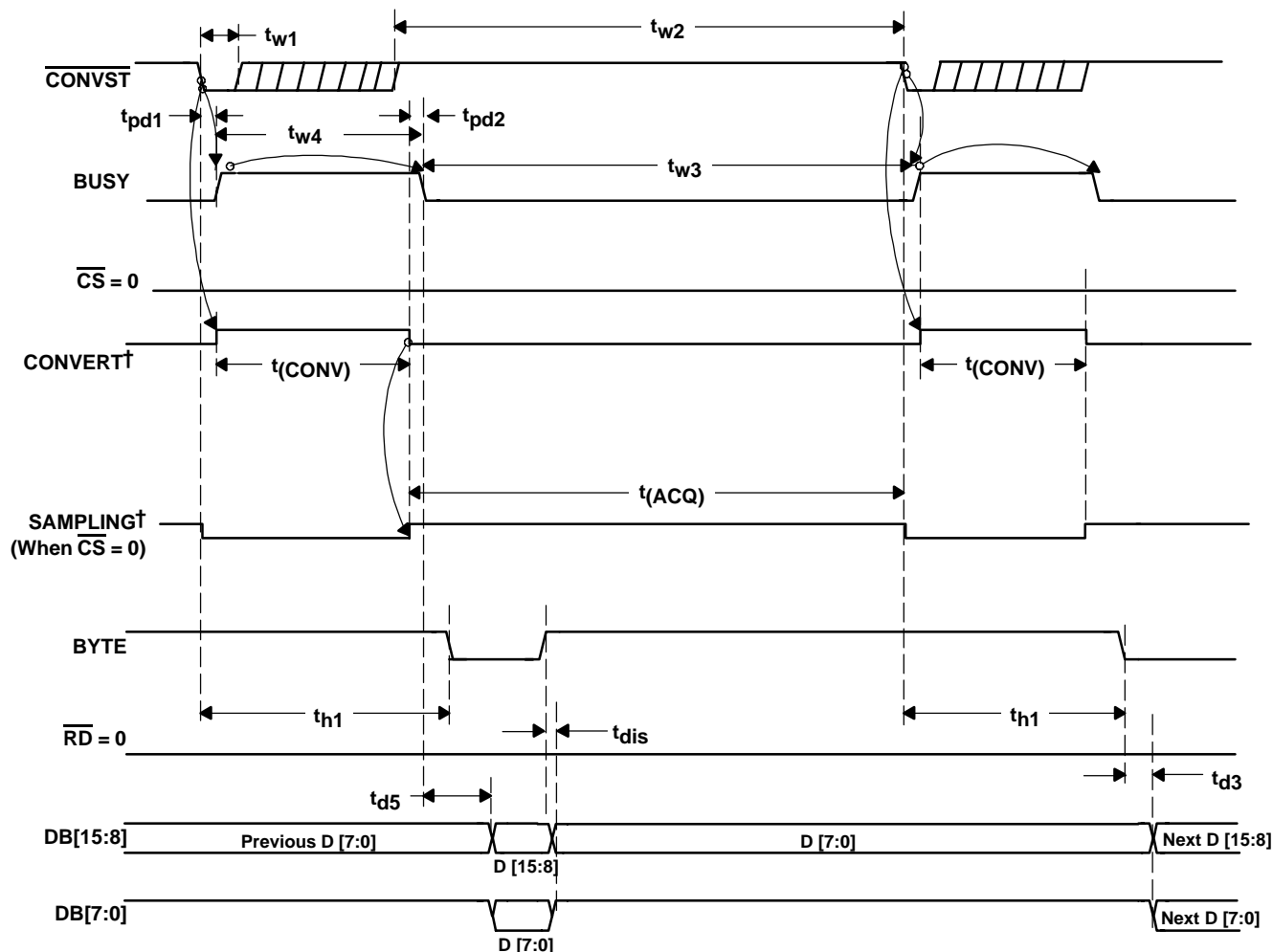
$^\dagger$ Signal internal to device

Figure 2. Timing for Conversion and Acquisition Cycles With  $\overline{\text{CS}}$  Toggling,  $\overline{\text{RD}}$  Tied to BDGND



†Signal internal to device

Figure 3. Timing for Conversion and Acquisition Cycles With  $\overline{CS}$  Tied to BDGND,  $\overline{RD}$  Toggling



$^\dagger$ Signal internal to device

Figure 4. Timing for Conversion and Acquisition Cycles With  $\overline{\text{CS}}$  and  $\overline{\text{RD}}$  Tied to BDGND—Auto Read

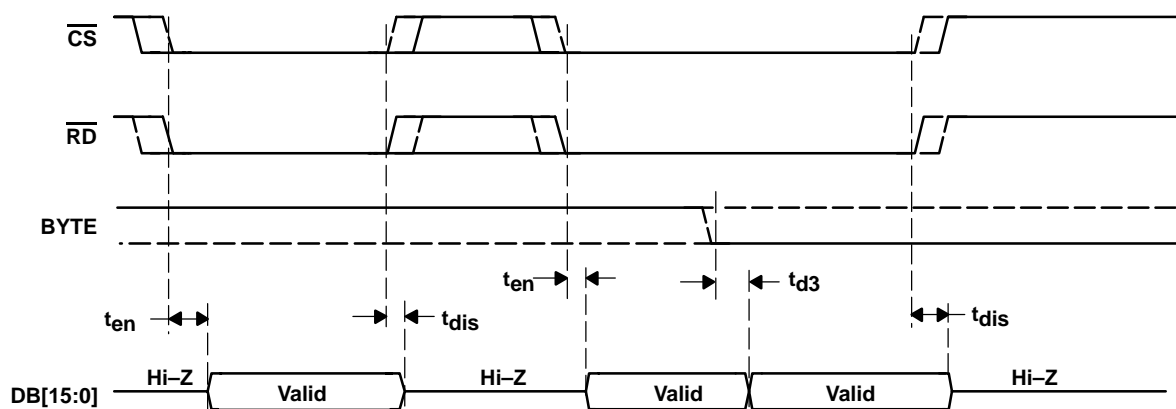


Figure 5. Detailed Timing for Read Cycles

# TYPICAL CHARACTERISTICS†

**HISTOGRAM (DC Code Spread)  
NEAR POSITIVE FULL SCALE  
196608 CONVERSIONS**

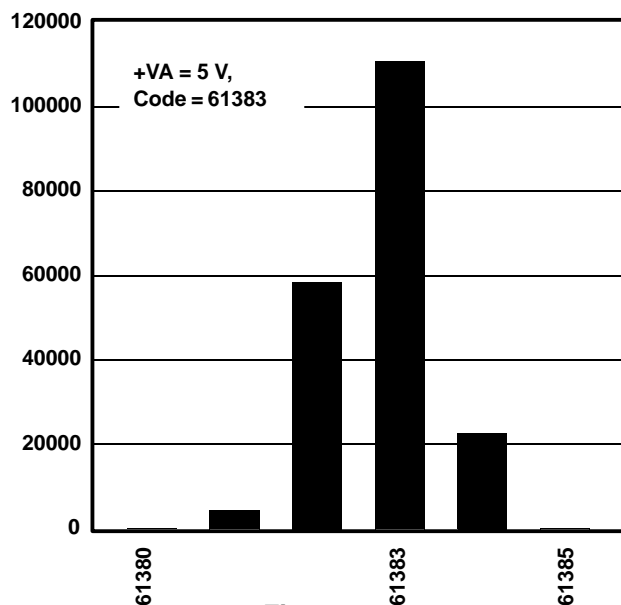


Figure 6

**SIGNAL-TO-NOISE RATIO  
vs  
FREE-AIR TEMPERATURE**

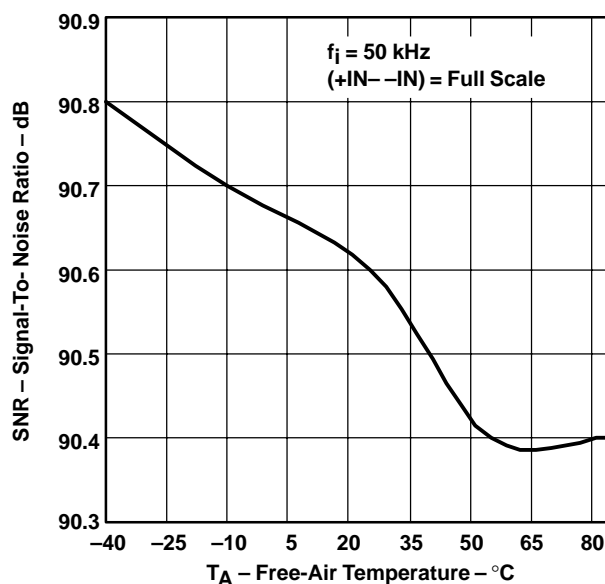


Figure 7

**SIGNAL-TO-NOISE PLUS DISTORTION  
vs  
FREE-AIR TEMPERATURE**

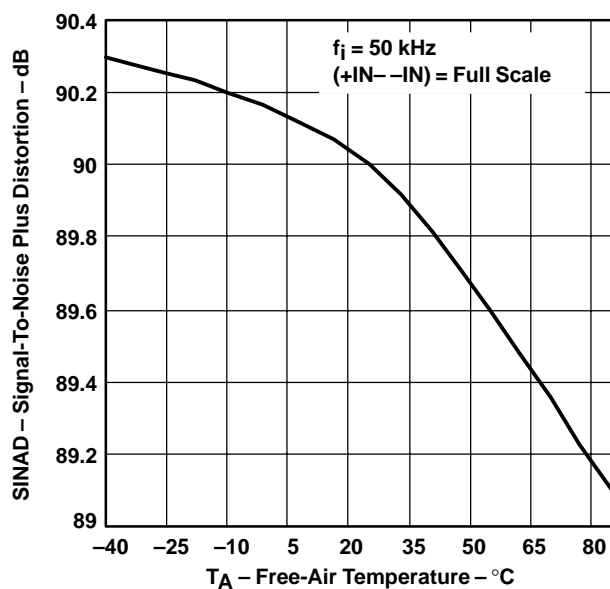


Figure 8

**SPURIOUS FREE-DYNAMIC RANGE  
vs  
FREE-AIR TEMPERATURE**

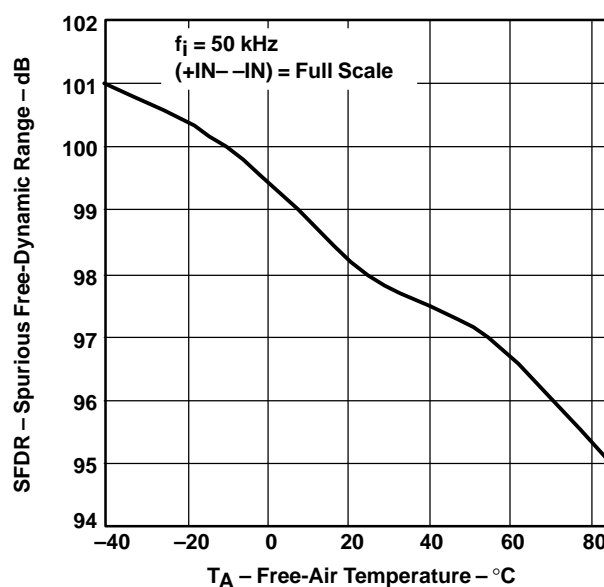


Figure 9

† At –40°C to 85°C, +VA = 5 V, +VBD = 5 V, REFIN = 4.096 V (internal reference used) and  $f_{\text{sample}} = 1.25 \text{ MHz}$  (unless otherwise noted)

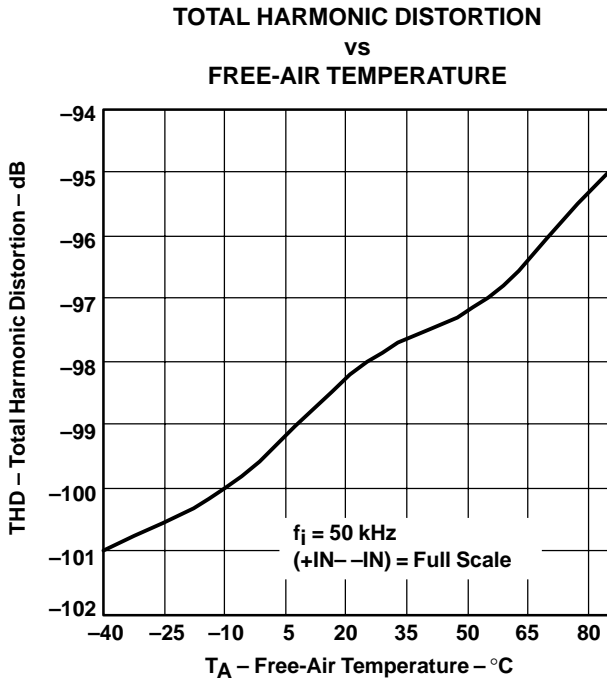


Figure 10

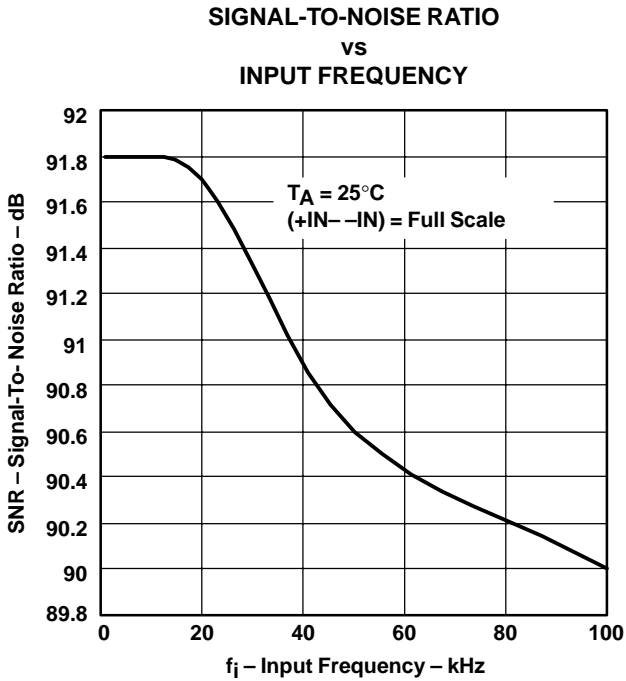


Figure 11

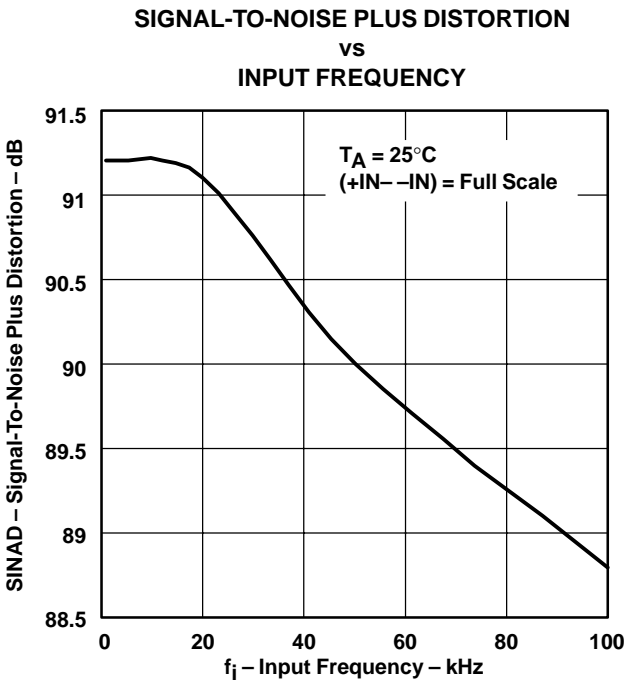


Figure 12

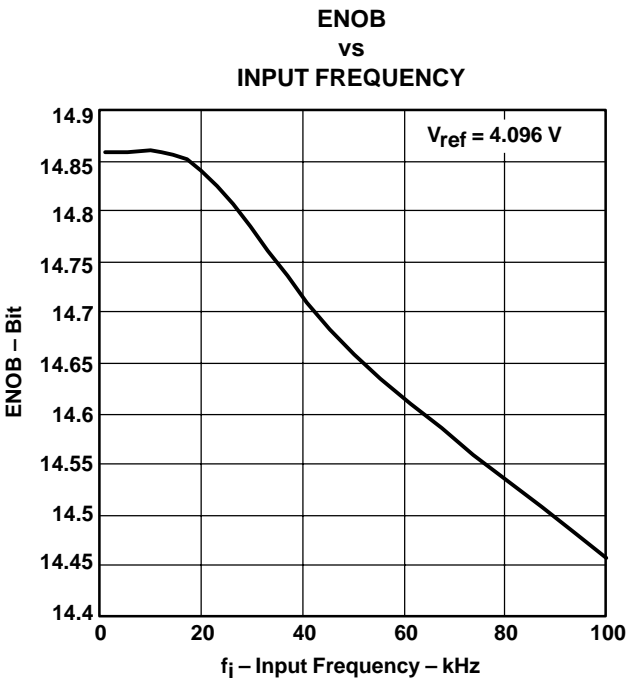


Figure 13

† At -40°C to 85°C, +VA = 5 V, +VBD = 5 V, REFIN = 4.096 V (internal reference used) and  $f_{\text{sample}} = 1.25 \text{ MHz}$  (unless otherwise noted)

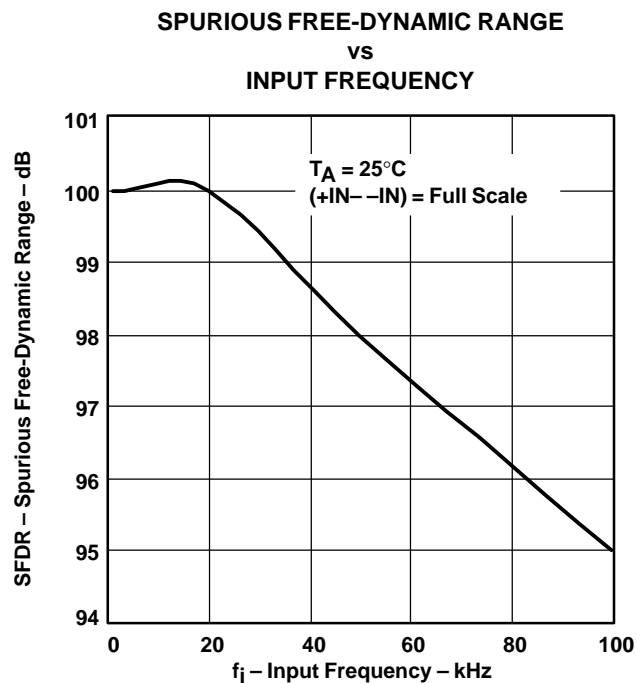


Figure 14

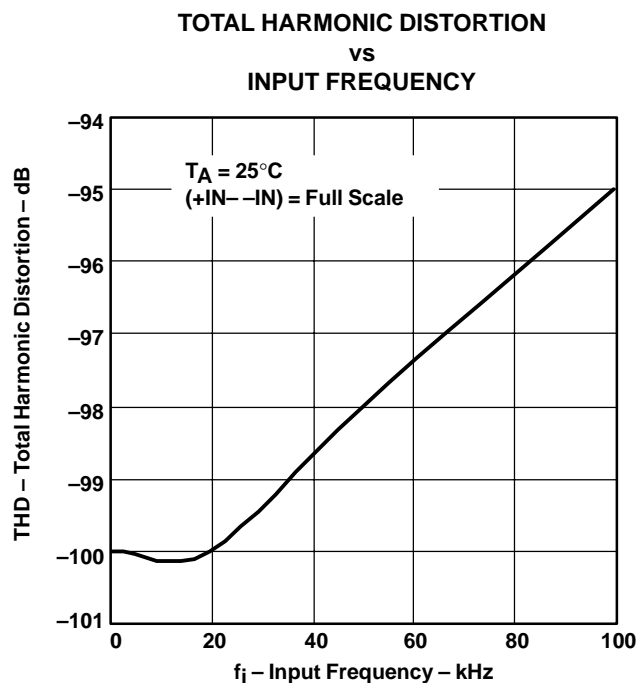


Figure 15

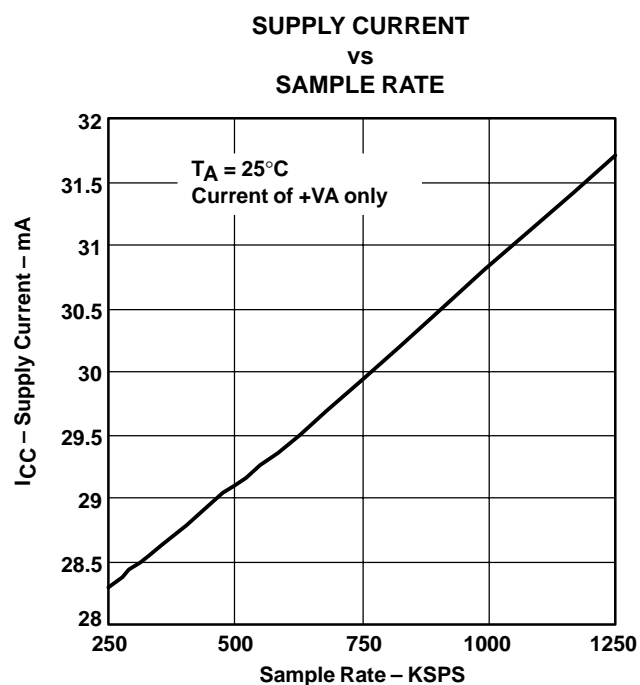


Figure 16

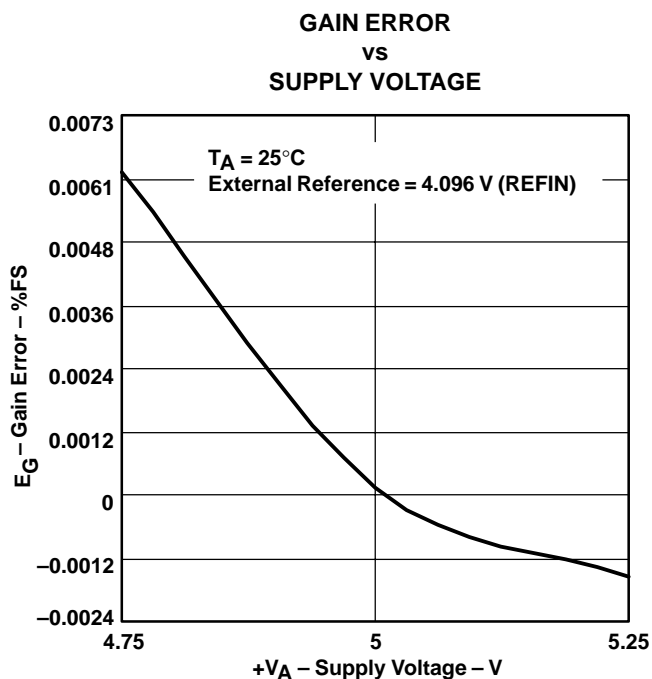


Figure 17

† At  $-40^\circ\text{C}$  to  $85^\circ\text{C}$ ,  $+V_A = 5\text{ V}$ ,  $+V_{BD} = 5\text{ V}$ ,  $\text{REFIN} = 4.096\text{ V}$  (internal reference used) and  $f_{\text{sample}} = 1.25\text{ MHz}$  (unless otherwise noted)

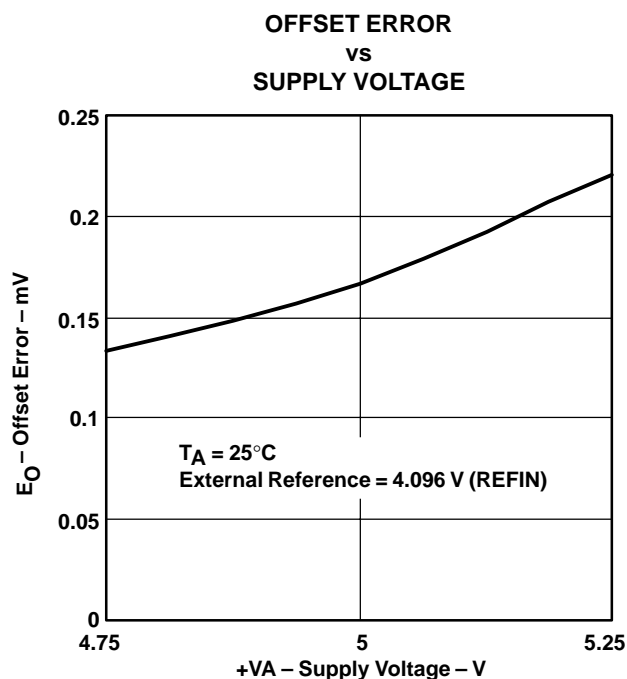


Figure 18

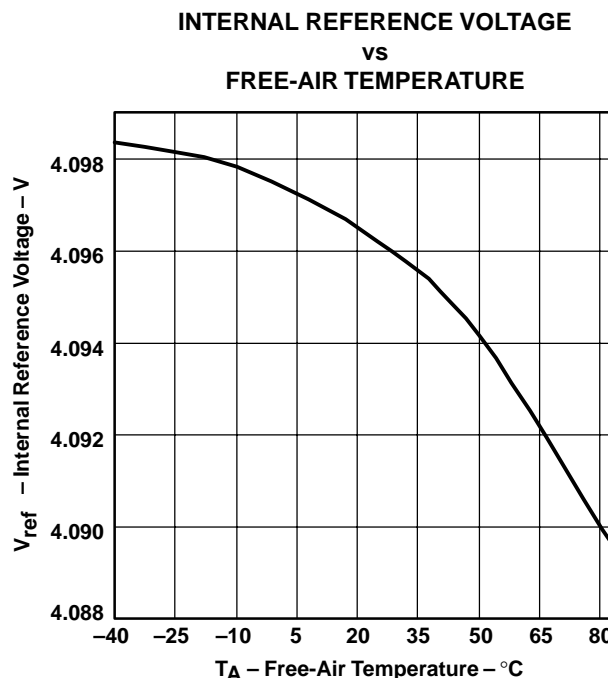


Figure 19

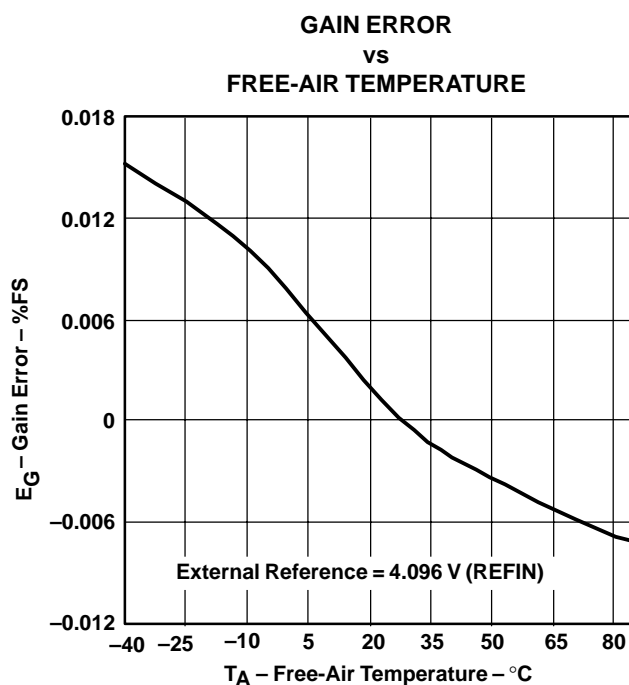


Figure 20

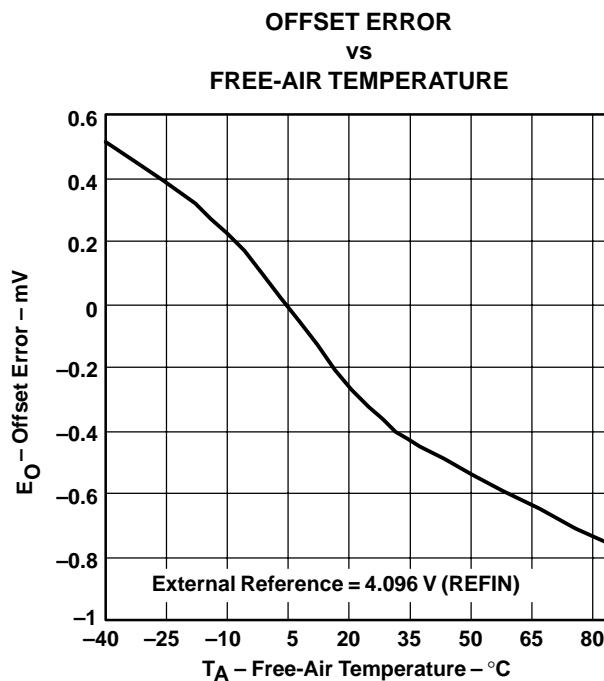


Figure 21

† At  $-40^\circ\text{C}$  to  $85^\circ\text{C}$ ,  $+VA = 5\text{ V}$ ,  $+VBD = 5\text{ V}$ ,  $REFIN = 4.096\text{ V}$  (internal reference used) and  $f_{\text{sample}} = 1.25\text{ MHz}$  (unless otherwise noted)



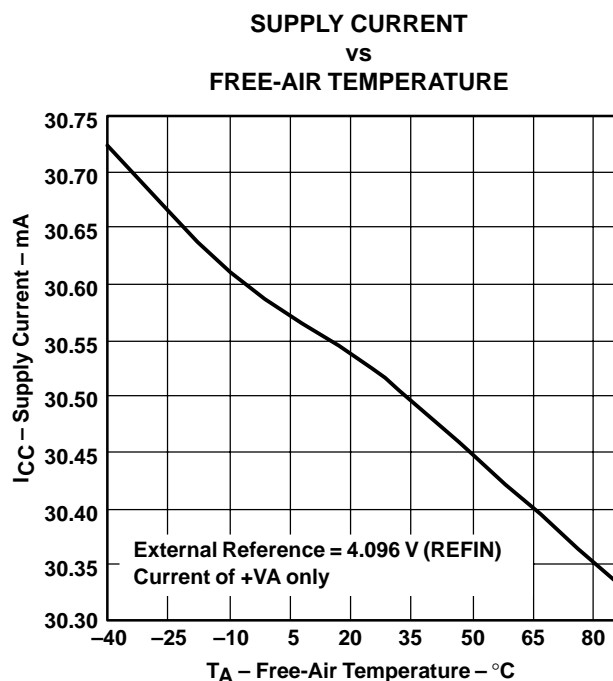


Figure 22

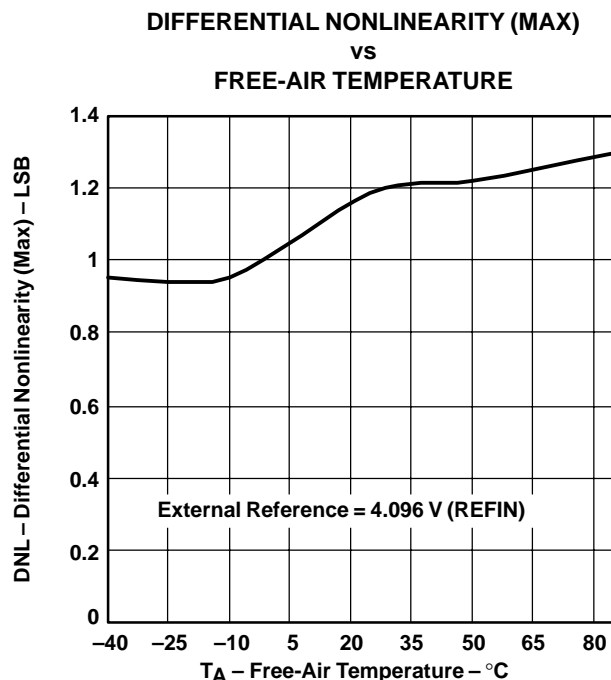


Figure 23

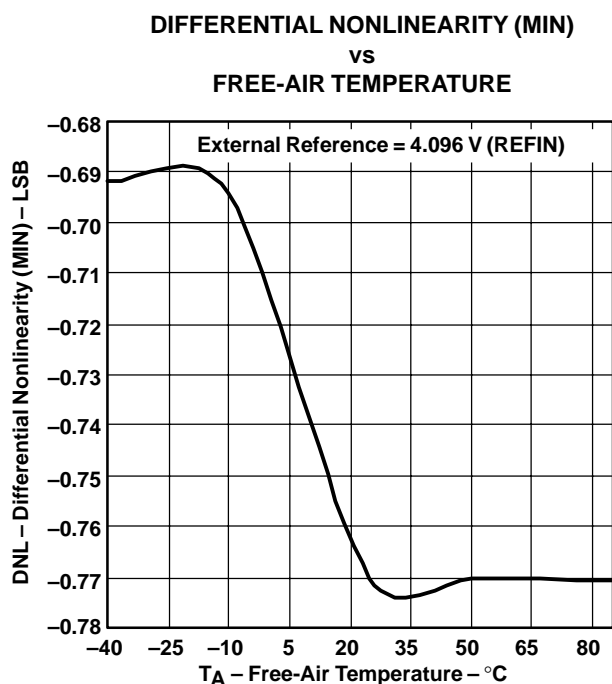


Figure 24

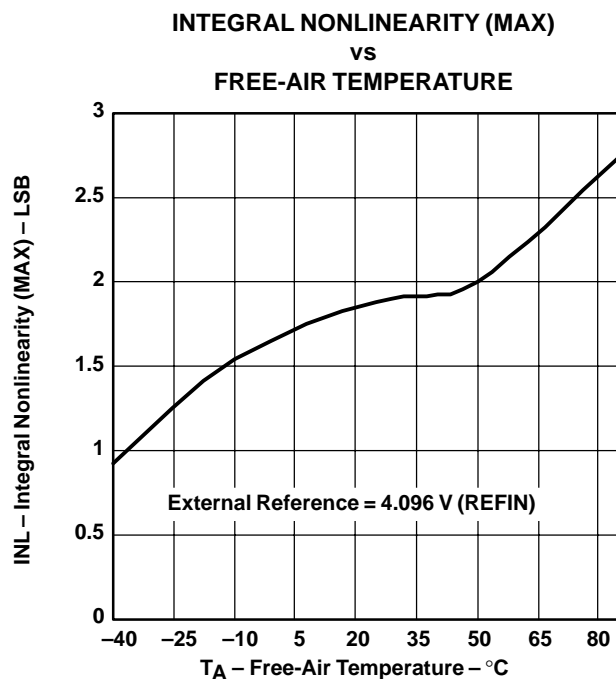


Figure 25

† At –40°C to 85°C, +VA = 5 V, +VBD = 5 V, REFIN = 4.096 V (internal reference used) and  $f_{\text{sample}} = 1.25$  MHz (unless otherwise noted)

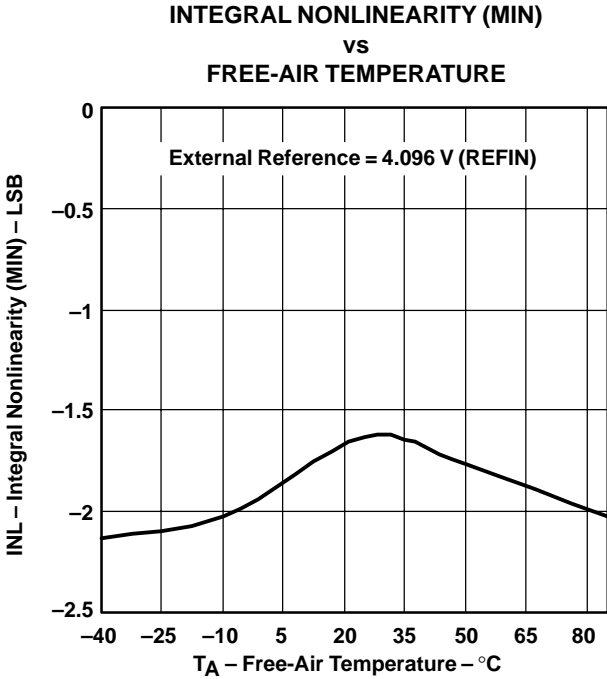


Figure 26

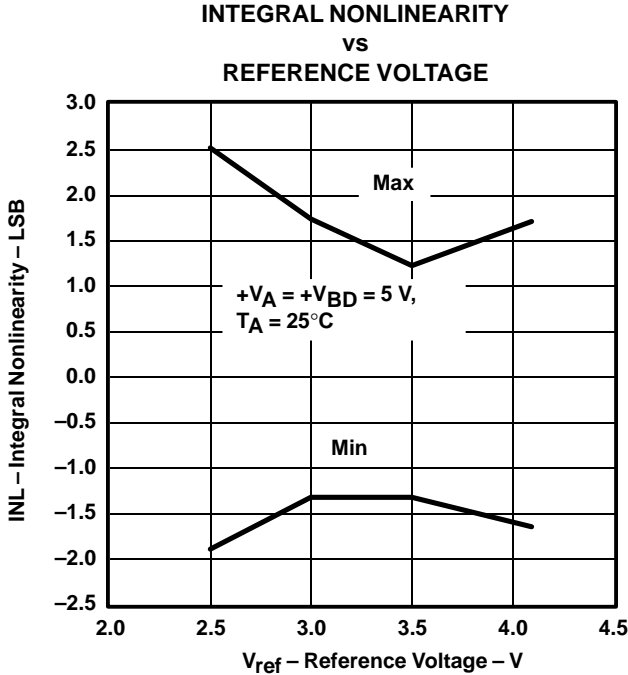


Figure 27

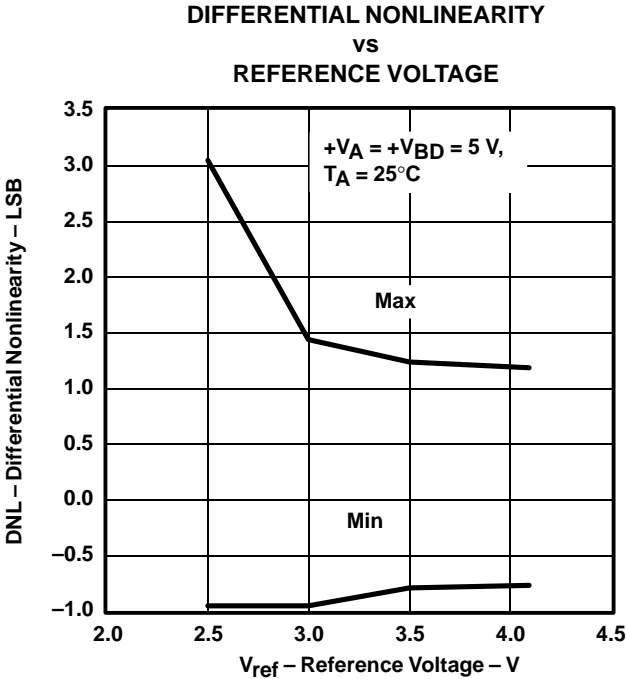
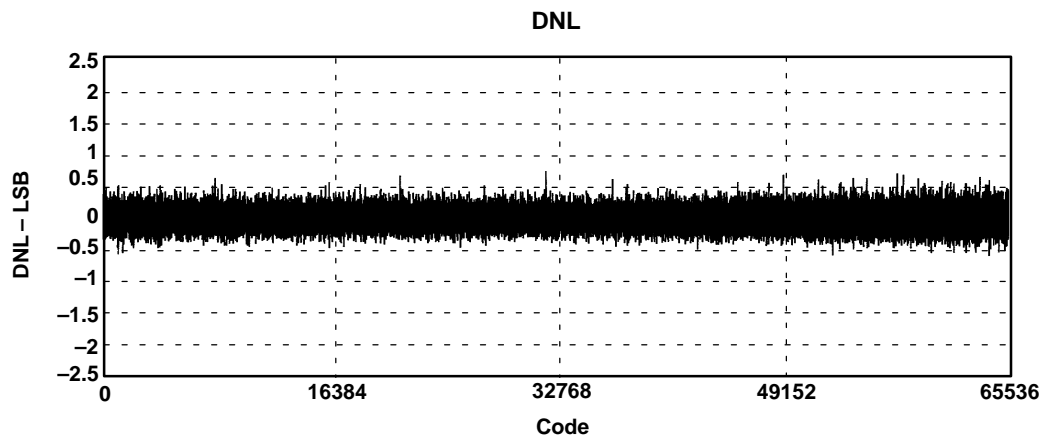


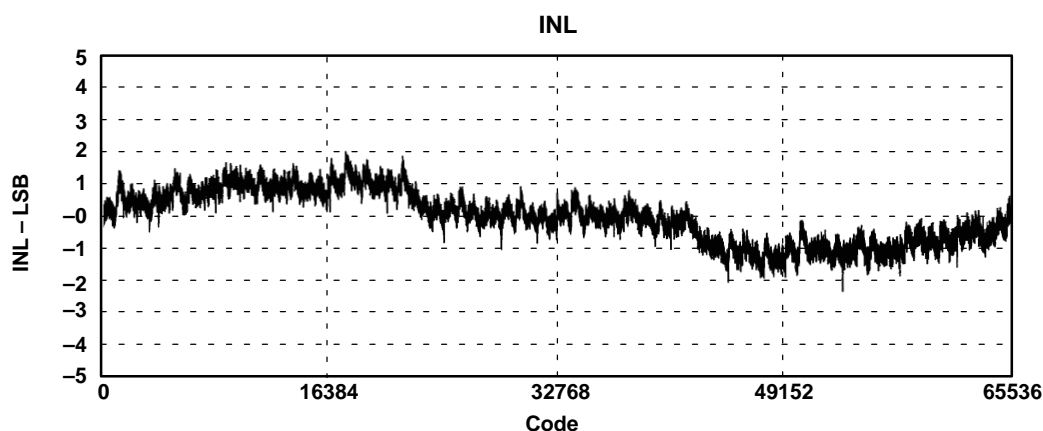
Figure 28

† At -40°C to 85°C, +VA = 5 V, +VBD = 5 V, REFIN = 4.096 V (internal reference used) and f<sub>sample</sub> = 1.25 MHz (unless otherwise noted)



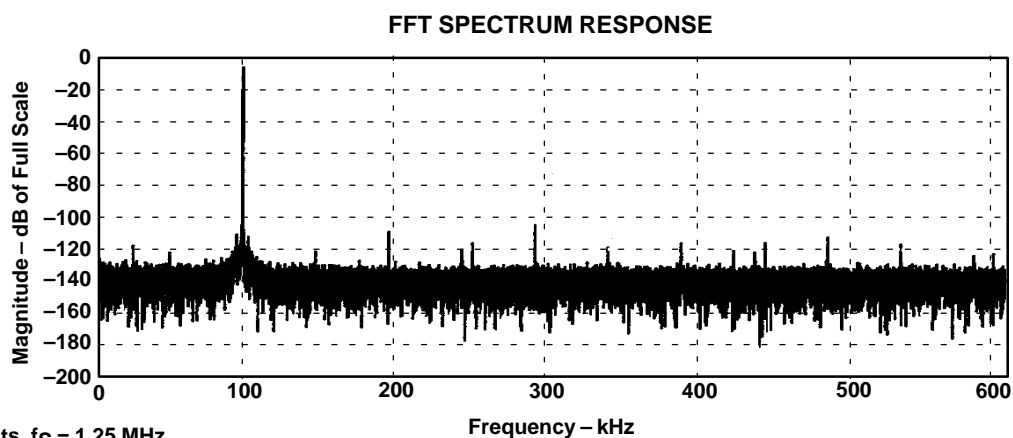
$T_A = 25^\circ\text{C}$ , External Reference = 4.096 V (REFIN)

Figure 29



$T_A = 25^\circ\text{C}$ , External Reference = 4.096 V (REFIN)

Figure 30



32768 Points,  $f_S = 1.25\text{ MHz}$ ,  
Internal Reference = 4.096 V (REFIN),  
 $T_A = 25^\circ\text{C}$ ,  $f_i = 100\text{ kHz}$ , (+IN – –IN) = Full Scale

Figure 31

† At  $-40^\circ\text{C}$  to  $85^\circ\text{C}$ ,  $+V_A = 5\text{ V}$ ,  $+V_{BD} = 5\text{ V}$ , REFIN = 4.096 V (internal reference used) and  $f_{\text{sample}} = 1.25\text{ MHz}$  (unless otherwise noted)

## APPLICATION INFORMATION

### MICROCONTROLLER INTERFACING

#### ADS8402 to 8-Bit Microcontroller Interface

Figure 32 shows a parallel interface between the ADS8402 and a typical microcontroller using the 8-bit data bus.

The BUSY signal is used as a falling-edge interrupt to the microcontroller.

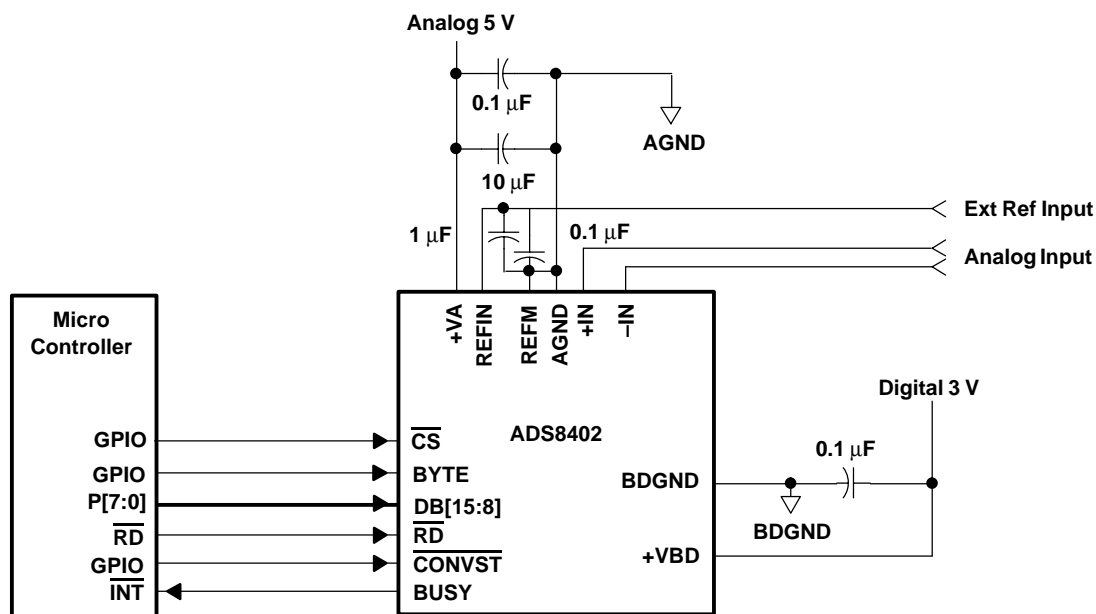


Figure 32. ADS8402 Application Circuitry (using external reference)

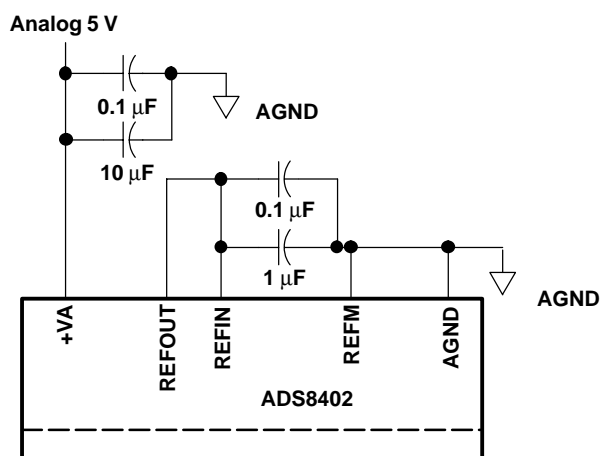


Figure 33. Use Internal Reference

## PRINCIPLES OF OPERATION

The ADS8402 is a high-speed successive approximation register (SAR) analog-to-digital converter (ADC). The architecture is based on charge redistribution, which inherently includes a sample/hold function. See Figure 32 for the application circuit for the ADS8402.

The conversion clock is generated internally. The conversion time of 610 ns is capable of sustaining a 1.25-MHz throughput.

The analog input is provided to two input pins: +IN and –IN. When a conversion is initiated, the differential input on these pins is sampled on the internal capacitor array. While a conversion is in progress, both inputs are disconnected from any internal function.

## REFERENCE

The ADS8402 can operate with an external reference with a range from 2.5 V to 4.2 V. A 4.096-V internal reference is included. When internal reference is used, pin 2 (REFOUT) should be connected to pin 1 (REFIN) with an 0.1  $\mu$ F decoupling capacitor and 1  $\mu$ F storage capacitor between pin 2 (REFOUT) and pins 47 and 48 (REFM) (see Figure 33). The internal reference of the converter is double buffered. If an external reference is used, the second buffer provides isolation between the external reference and the CDAC. This buffer is also used to recharge all of the capacitors of the CDAC during conversion. Pin 2 (REFOUT) can be left unconnected (floating) if external reference is used.

## ANALOG INPUT

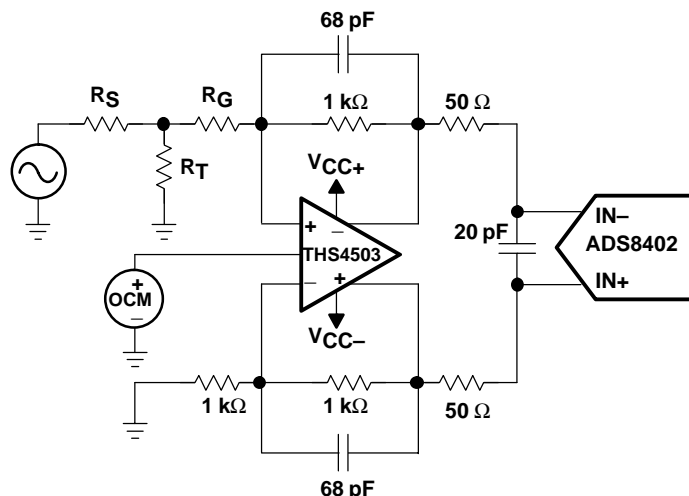
When the converter enters the hold mode, the voltage difference between the +IN and –IN inputs is captured on the internal capacitor array. Both +IN and –IN input has a range of  $-0.2$  V to  $V_{\text{ref}} + 0.2$  V. The input span (+IN – (–IN)) is limited to  $-V_{\text{ref}}$  to  $V_{\text{ref}}$ .

The input current on the analog inputs depends upon a number of factors: sample rate, input voltage, and source impedance. Essentially, the current into the ADS8402 charges the internal capacitor array during the sample period. After this capacitance has been fully charged, there is no further input current. The source of the analog input voltage must be able to charge the input capacitance (25 pF) to an 16-bit settling level within the acquisition time (150 ns) of the device. When the converter goes into the hold mode, the input impedance is greater than 1 G $\Omega$ .

Care must be taken regarding the absolute analog input voltage. To maintain the linearity of the converter, the +IN and –IN inputs and the span (+IN – (–IN)) should be within the limits specified. Outside of these ranges, the converter's linearity may not meet specifications. To minimize noise, low bandwidth input signals with low-pass filters should be used.

Care should be taken to ensure that the output impedance of the sources driving +IN and –IN inputs are matched. If this is not observed, the two inputs could have different settling time. This may result in offset error, gain error and linearity error which varies with temperature and input voltage.

A typical input circuit using TI's THS4503 is shown in Figure 34. Input from a single-ended source may be converted into differential signal for ADS8402 as shown in the figure. In case the source itself is differential then THS4503 may be used in differential input and differential output mode.



$R_G$ ,  $R_S$ , and  $R_T$  should be chosen such that  
 $R_G + R_S \parallel R_T = 1 \text{ k}\Omega$   
 $V_{OCM} = 2 \text{ V}$ ,  $V_{CC} = 7 \text{ V}$ , and  $-V_{CC} = -7 \text{ V}$

Figure 34. Using THS4503 With ADS8402

## DIGITAL INTERFACE

### Timing and Control

See the timing diagrams in the specifications section for detailed information on timing signals and their requirements.

The ADS8402 uses an internal oscillator generated clock which controls the conversion rate and in turn the throughput of the converter. No external clock input is required.

Conversions are initiated by bringing the  $\overline{\text{CONVST}}$  pin low for a minimum of 20 ns (after the 20 ns minimum requirement has been met, the  $\overline{\text{CONVST}}$  pin can be brought high), while  $\overline{\text{CS}}$  is low. The ADS8402 switches from the sample to the hold mode on the falling edge of the  $\overline{\text{CONVST}}$  command. A clean and low jitter falling edge of this signal is important to the performance of the converter. The BUSY output is brought high after  $\overline{\text{CONVST}}$  goes low. BUSY stays high throughout the conversion process and returns low when the conversion has ended.

Sampling starts with the falling edge of the BUSY signal when  $\overline{\text{CS}}$  is tied low or starts with the falling edge of  $\overline{\text{CS}}$  when BUSY is low.

Both  $\overline{\text{RD}}$  and  $\overline{\text{CS}}$  can be high during and before a conversion with one exception ( $\overline{\text{CS}}$  must be low when  $\overline{\text{CONVST}}$  goes low to initiate a conversion). Both the  $\overline{\text{RD}}$  and  $\overline{\text{CS}}$  pins are brought low in order to enable the parallel output bus with the conversion.

### Reading Data

The ADS8402 outputs full parallel data in two's complement format as shown in Table 1. The parallel output is active when  $\overline{\text{CS}}$  and  $\overline{\text{RD}}$  are both low. There is a minimal quiet zone requirement around the falling edge of  $\overline{\text{CONVST}}$ . This is 100 ns prior to the falling edge of  $\overline{\text{CONVST}}$  and 40 ns after the falling edge. No data read should be attempted within this zone. Any other combination of  $\overline{\text{CS}}$  and  $\overline{\text{RD}}$  sets the parallel output to 3-state. BYTE is used for multiword read operations. BYTE is used whenever lower bits of the conversion result are output on the higher byte of the bus. Refer to Table 1 for ideal output codes.

**Table 1. Ideal Input Voltages and Output Codes**

DESCRIPTION	ANALOG VALUE	DIGITAL OUTPUT TWOS COMPLEMENT	
FULL SCALE RANGE	$2V_{ref}$		
Least significant bit (LSB)	$2V_{ref}/65536$	BINARY CODE	HEX CODE
Full scale	$V_{ref}$	0111 1111 1111 1111	7FFF
Midscale	0	0000 0000 0000 0000	0000
Zero	$-V_{ref}$	1000 0000 0000 0000	8000

The output data is a full 16-bit word (D15–D0) on DB15–DB0 pins (MSB–LSB) if BYTE is low.

The result may also be read on an 8-bit bus for convenience. This is done by using only pins DB15–DB8. In this case two reads are necessary: the first as before, leaving BYTE low and reading the 8 most significant bits on pins DB15–DB8, then bringing BYTE high, the low bits (D7–D0) appears on pins DB15–D8.

These multiword read operations can be done with multiple active  $\overline{RD}$  (toggling) or with  $\overline{RD}$  tied low for simplicity.

BYTE	DATA READ OUT	
	DB15–DB8	DB7–DB0
High	D7–D0	All one's
Low	D15–D8	D7–D0

## RESET

$\overline{RESET}$  is an asynchronous active low input signal (that works independantly of  $\overline{CS}$ ). Minimum  $\overline{RESET}$  low time is 20 ns. Current conversion will be aborted no later than 50 ns after the converter is in the reset mode. In addition, all output latches are cleared (set to zero's) after  $\overline{RESET}$ . The converter goes back to normal operation mode no later than 20 ns after  $\overline{RESET}$  input is brought high.

The converter starts the first sampling period 20 ns after the rising edge of  $\overline{RESET}$ . Any sampling period except for the one immediately after a  $\overline{RESET}$  is started with the falling edge of the previous BUSY signal or the falling edge of CS, whichever is later.

## POWER-ON INITIALIZATION

One  $\overline{RESET}$  pulse followed by three conversion cycles must be given to the converter after powerup to ensure proper operation. The next pulse can be issued once both +VA and +VBD reach 95% of the minimum required value.

## LAYOUT

For optimum performance, care should be taken with the physical layout of the ADS8402 circuitry.

As the ADS8402 offers single-supply operation, it is often used in close proximity with digital logic, microcontrollers, microprocessors, and digital signal processors. The more digital logic present in the design and the higher the switching speed, the more difficult it is to achieve good performance from the converter.

The basic SAR architecture is sensitive to glitches or sudden changes on the power supply, reference, ground connections and digital inputs that occur just prior to latching the output of the analog comparator. Thus, driving any single conversion for an n-bit SAR converter, there are at least n *windows* in which large external transient voltages can affect the conversion result. Such glitches might originate from switching power supplies, nearby digital logic, or high power devices.

The degree of error in the digital output depends on the reference voltage, layout, and the exact timing of the external event.

On average, the ADS8402 draws very little current from an external reference, as the reference voltage is internally buffered. If the reference voltage is external and originates from an op amp, make sure that it can drive the bypass capacitor or capacitors without oscillation. A 0.1- $\mu$ F bypass capacitor and 1- $\mu$ F storage capacitor are recommended from pin 1 (REFIN) directly to pin 48 (REFM). REFM and AGND should be shorted on the same ground plane under the device.

The AGND and BDGND pins should be connected to a clean ground point. In all cases, this should be the analog ground. Avoid connections which are close to the grounding point of a microcontroller or digital signal processor. If required, run a ground trace directly from the converter to the power supply entry point. The ideal layout consists of an analog ground plane dedicated to the converter and associated analog circuitry.

As with the AGND connections, +VA should be connected to a 5-V power supply plane or trace that is separate from the connection for digital logic until they are connected at the power entry point. Power to the ADS8402 should be clean and well bypassed. A 0.1- $\mu$ F ceramic bypass capacitor should be placed as close to the device as possible. See Table 2 for the placement of the capacitor. In addition, a 1- $\mu$ F to 10- $\mu$ F capacitor is recommended. In some situations, additional bypassing may be required, such as a 100- $\mu$ F electrolytic capacitor or even a Pi filter made up of inductors and capacitors—all designed to essentially low-pass filter the 5-V supply, removing the high frequency noise.

**Table 2. Power Supply Decoupling Capacitor Placement**

POWER SUPPLY PLANE SUPPLY PINS	CONVERTER ANALOG SIDE	CONVERTER DIGITAL SIDE
Pin pairs that require shortest path to decoupling capacitors	(4,5), (8,9), (10,11), (13,15), (43,44), (45,46)	(24,25), (34, 35)
Pins that require no decoupling	12, 14	37



## PACKAGING INFORMATION

Orderable Device	Status (1)	Package Type	Package Drawing	Pins	Package Qty	Eco Plan (2)	Lead/Ball Finish	MSL Peak Temp (3)	Op Temp (°C)	Device Marking (4/5)	Samples
ADS8402IBPFBT	OBSOLETE	TQFP	PFB	48		TBD	Call TI	Call TI	-40 to 85		
ADS8402IBPFBTG4	OBSOLETE	TQFP	PFB	48		TBD	Call TI	Call TI	-40 to 85		
ADS8402IPFBT	OBSOLETE	TQFP	PFB	48		TBD	Call TI	Call TI	-40 to 85		
ADS8402IPFBTG4	OBSOLETE	TQFP	PFB	48		TBD	Call TI	Call TI	-40 to 85		

(1) The marketing status values are defined as follows:

**ACTIVE:** Product device recommended for new designs.

**LIFEBUY:** TI has announced that the device will be discontinued, and a lifetime-buy period is in effect.

**NRND:** Not recommended for new designs. Device is in production to support existing customers, but TI does not recommend using this part in a new design.

**PREVIEW:** Device has been announced but is not in production. Samples may or may not be available.

**OBSOLETE:** TI has discontinued the production of the device.

(2) Eco Plan - The planned eco-friendly classification: Pb-Free (RoHS), Pb-Free (RoHS Exempt), or Green (RoHS & no Sb/Br) - please check <http://www.ti.com/productcontent> for the latest availability information and additional product content details.

**TBD:** The Pb-Free/Green conversion plan has not been defined.

**Pb-Free (RoHS):** TI's terms "Lead-Free" or "Pb-Free" mean semiconductor products that are compatible with the current RoHS requirements for all 6 substances, including the requirement that lead not exceed 0.1% by weight in homogeneous materials. Where designed to be soldered at high temperatures, TI Pb-Free products are suitable for use in specified lead-free processes.

**Pb-Free (RoHS Exempt):** This component has a RoHS exemption for either 1) lead-based flip-chip solder bumps used between the die and package, or 2) lead-based die adhesive used between the die and leadframe. The component is otherwise considered Pb-Free (RoHS compatible) as defined above.

**Green (RoHS & no Sb/Br):** TI defines "Green" to mean Pb-Free (RoHS compatible), and free of Bromine (Br) and Antimony (Sb) based flame retardants (Br or Sb do not exceed 0.1% by weight in homogeneous material)

(3) MSL, Peak Temp. -- The Moisture Sensitivity Level rating according to the JEDEC industry standard classifications, and peak solder temperature.

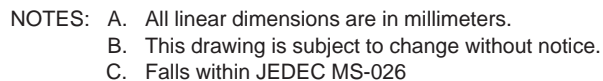
(4) There may be additional marking, which relates to the logo, the lot trace code information, or the environmental category on the device.

(5) Multiple Device Markings will be inside parentheses. Only one Device Marking contained in parentheses and separated by a "~" will appear on a device. If a line is indented then it is a continuation of the previous line and the two combined represent the entire Device Marking for that device.

**Important Information and Disclaimer:** The information provided on this page represents TI's knowledge and belief as of the date that it is provided. TI bases its knowledge and belief on information provided by third parties, and makes no representation or warranty as to the accuracy of such information. Efforts are underway to better integrate information from third parties. TI has taken and continues to take reasonable steps to provide representative and accurate information but may not have conducted destructive testing or chemical analysis on incoming materials and chemicals. TI and TI suppliers consider certain information to be proprietary, and thus CAS numbers and other limited information may not be available for release.

In no event shall TI's liability arising out of such information exceed the total purchase price of the TI part(s) at issue in this document sold by TI to Customer on an annual basis.

## PLASTIC QUAD FLATPACK



## IMPORTANT NOTICE

Texas Instruments Incorporated and its subsidiaries (TI) reserve the right to make corrections, enhancements, improvements and other changes to its semiconductor products and services per JESD46, latest issue, and to discontinue any product or service per JESD48, latest issue. Buyers should obtain the latest relevant information before placing orders and should verify that such information is current and complete. All semiconductor products (also referred to herein as "components") are sold subject to TI's terms and conditions of sale supplied at the time of order acknowledgment.

TI warrants performance of its components to the specifications applicable at the time of sale, in accordance with the warranty in TI's terms and conditions of sale of semiconductor products. Testing and other quality control techniques are used to the extent TI deems necessary to support this warranty. Except where mandated by applicable law, testing of all parameters of each component is not necessarily performed.

TI assumes no liability for applications assistance or the design of Buyers' products. Buyers are responsible for their products and applications using TI components. To minimize the risks associated with Buyers' products and applications, Buyers should provide adequate design and operating safeguards.

TI does not warrant or represent that any license, either express or implied, is granted under any patent right, copyright, mask work right, or other intellectual property right relating to any combination, machine, or process in which TI components or services are used. Information published by TI regarding third-party products or services does not constitute a license to use such products or services or a warranty or endorsement thereof. Use of such information may require a license from a third party under the patents or other intellectual property of the third party, or a license from TI under the patents or other intellectual property of TI.

Reproduction of significant portions of TI information in TI data books or data sheets is permissible only if reproduction is without alteration and is accompanied by all associated warranties, conditions, limitations, and notices. TI is not responsible or liable for such altered documentation. Information of third parties may be subject to additional restrictions.

Resale of TI components or services with statements different from or beyond the parameters stated by TI for that component or service voids all express and any implied warranties for the associated TI component or service and is an unfair and deceptive business practice. TI is not responsible or liable for any such statements.

Buyer acknowledges and agrees that it is solely responsible for compliance with all legal, regulatory and safety-related requirements concerning its products, and any use of TI components in its applications, notwithstanding any applications-related information or support that may be provided by TI. Buyer represents and agrees that it has all the necessary expertise to create and implement safeguards which anticipate dangerous consequences of failures, monitor failures and their consequences, lessen the likelihood of failures that might cause harm and take appropriate remedial actions. Buyer will fully indemnify TI and its representatives against any damages arising out of the use of any TI components in safety-critical applications.

In some cases, TI components may be promoted specifically to facilitate safety-related applications. With such components, TI's goal is to help enable customers to design and create their own end-product solutions that meet applicable functional safety standards and requirements. Nonetheless, such components are subject to these terms.

No TI components are authorized for use in FDA Class III (or similar life-critical medical equipment) unless authorized officers of the parties have executed a special agreement specifically governing such use.

Only those TI components which TI has specifically designated as military grade or "enhanced plastic" are designed and intended for use in military/aerospace applications or environments. Buyer acknowledges and agrees that any military or aerospace use of TI components which have **not** been so designated is solely at the Buyer's risk, and that Buyer is solely responsible for compliance with all legal and regulatory requirements in connection with such use.

TI has specifically designated certain components as meeting ISO/TS16949 requirements, mainly for automotive use. In any case of use of non-designated products, TI will not be responsible for any failure to meet ISO/TS16949.

### Products

Audio	<a href="http://www.ti.com/audio">www.ti.com/audio</a>
Amplifiers	<a href="http://amplifier.ti.com">amplifier.ti.com</a>
Data Converters	<a href="http://dataconverter.ti.com">dataconverter.ti.com</a>
DLP® Products	<a href="http://www.dlp.com">www.dlp.com</a>
DSP	<a href="http://dsp.ti.com">dsp.ti.com</a>
Clocks and Timers	<a href="http://www.ti.com/clocks">www.ti.com/clocks</a>
Interface	<a href="http://interface.ti.com">interface.ti.com</a>
Logic	<a href="http://logic.ti.com">logic.ti.com</a>
Power Mgmt	<a href="http://power.ti.com">power.ti.com</a>
Microcontrollers	<a href="http://microcontroller.ti.com">microcontroller.ti.com</a>
RFID	<a href="http://www.ti-rfid.com">www.ti-rfid.com</a>
OMAP Applications Processors	<a href="http://www.ti.com/omap">www.ti.com/omap</a>
Wireless Connectivity	<a href="http://www.ti.com/wirelessconnectivity">www.ti.com/wirelessconnectivity</a>

### Applications

Automotive and Transportation	<a href="http://www.ti.com/automotive">www.ti.com/automotive</a>
Communications and Telecom	<a href="http://www.ti.com/communications">www.ti.com/communications</a>
Computers and Peripherals	<a href="http://www.ti.com/computers">www.ti.com/computers</a>
Consumer Electronics	<a href="http://www.ti.com/consumer-apps">www.ti.com/consumer-apps</a>
Energy and Lighting	<a href="http://www.ti.com/energy">www.ti.com/energy</a>
Industrial	<a href="http://www.ti.com/industrial">www.ti.com/industrial</a>
Medical	<a href="http://www.ti.com/medical">www.ti.com/medical</a>
Security	<a href="http://www.ti.com/security">www.ti.com/security</a>
Space, Avionics and Defense	<a href="http://www.ti.com/space-avionics-defense">www.ti.com/space-avionics-defense</a>
Video and Imaging	<a href="http://www.ti.com/video">www.ti.com/video</a>

### TI E2E Community

[e2e.ti.com](http://e2e.ti.com)