

# ADS5294

SLAS776C-NOVEMBER 2011-REVISED SEPTEMBER 2013

# Octal-Channel 14-Bit 80-MSPS High-SNR and Low-Power ADC

Check for Samples: ADS5294

# **FEATURES**

- Maximum Sample Rate: 80 MSPS/14-Bit
- High Signal-to-Noise Ratio
  - 75.5-dBFS SNR at 5 MHz / 80 MSPS
  - 78.2-dBFS SNR at 5 MHz / 80 MSPS and Decimation Filter Enabled
  - 84-dBc SFDR at 5 MHz / 80 MSPS
- Low Power Consumption
  - 58 mW/CH at 50 MSPS
  - 77 mW/CH at 80 MSPS (2-LVDS Wire Per Channel)
- Digital Processing Block
  - Programmable FIR Decimation Filter and Oversampling to Minimize Harmonic Interference
  - Programmable IIR High-Pass Filter to Minimize DC Offset
  - Programmable Digital Gain: 0 dB to 12 dB
  - 2-Channel or 4-Channel Averaging
- Flexible Serialized LVDS Outputs:
  - One or Two Wires of LVDS Output Lines per Channel Depending on ADC Sampling Rate
  - Programmable Mapping Between ADC Input Channels and LVDS Output Pins-Eases Board Design
  - Variety of Test Patterns to Verify Data Capture by FPGA/Receiver
- Internal and External References
- 1.8-V Operation for Low Power Consumption
- Low-Frequency Noise Suppression
- Recovery From 6-dB Overload Within 1 Clock
  Cycle
- Package: 12-mm × 12-mm 80-Pin QFP

# APPLICATIONS

- Ultrasound Imaging
- Communication Applications
- Multi-channel Data Acquisition

# DESCRIPTION

The ADS5294 is a low-power 80-MSPS 8-Channel ADC that uses CMOS process technology and innovative circuit techniques. Low power consumption, high SNR, low SFDR, and consistent overload recovery allow users to design high performance systems.

The digital processing block of the ADS5294 integrates several commonly used digital functions for improving system performance. The device includes a digital filter module that has built-in decimation filters (with low-pass, high-pass and band-pass characteristics). The decimation rate is also programmable (by 2, by 4, or by 8). This rate is useful for narrow-band applications, where the filters are used to conveniently improve SNR and knock-off harmonics, while at the same time reducing the output data rate. The device includes an averaging mode where two channels (or even four channels) are averaged to improve SNR.

Serial LVDS outputs reduce the number of interface lines and enable the highest system integration. The digital data from each channel ADC is output over one or two wires of LVDS output lines depending on the ADC sampling rate. This 2-wire interface maintains a low serial-data rate, allowing low-cost FPGA-based receivers to be used even at a high sample rate. The ADC resolution is programmed to 12 bit or 14 bit through registers. A unique feature is the programmable-mapping module that allows flexible mapping between the input channels and the LVDS output pins. This module greatly reduces the complexity of LVDS-output routing, and by reducing the number of PCB layers, potentially results in cheaper system boards.

The device integrates an internal reference trimmed to accurately match across devices. Internal reference mode achieves the best performance. External references can also drive the device.

The device is available in a 12-mm  $\times$  12-mm 80-pin QFP package. The device is specified over a -40°C to 85°C operating temperature range. ADS5294 is completely pin-to-pin and register compatible to ADS5292.



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**ISTRUMENTS** 

**EXAS** 



This integrated circuit can be damaged by ESD. Texas Instruments recommends that all integrated circuits be handled with appropriate precautions. Failure to observe proper handling and installation procedures can cause damage.

ESD damage can range from subtle performance degradation to complete device failure. Precision integrated circuits may be more susceptible to damage because very small parametric changes could cause the device not to meet its published specifications.

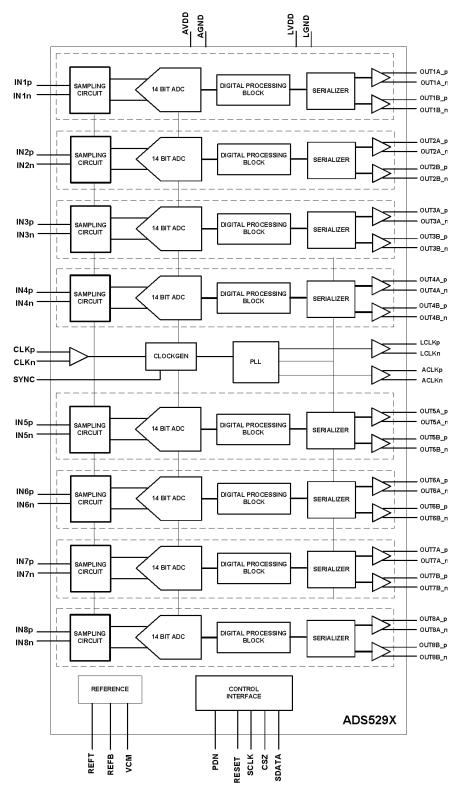
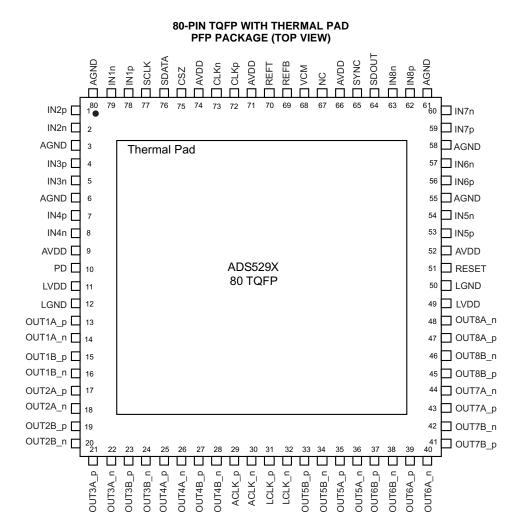


Figure 1. Block Diagram



#### **PIN CONFIGURATION**



#### **PIN FUNCTIONS**

NUMBER	Pl	N	DESCRIPTION
OF PINS	NAME	NUMBER	DESCRIPTION
5	AVDD	9, 52, 66, 71, 74	Analog power supply, 1.8 V
6	AGND	3, 6, 55, 58, 61, 80	Analog ground
1	VCM	68	Common-mode output pin, 0.95-V output. This pin can be configured as the external reference voltage (1.5 V) input pin as well. See Reg 0x42 and External Reference Mode of Operation .
1	CLKN	73	Negative differential clock –Tie CLKN to GND for single-ended clock
1	CLKP	72	Positive differential clock
2	IN1P, IN1N	78, 79	Differential input signal, Channel 1
2	IN2P, IN2N	1, 2	Differential input signal, Channel 2
2	IN3P, IN3N	4, 5	Differential input signal, Channel 3
2	IN4P, IN4N	7, 8	Differential input signal, Channel 4
2	IN5P, IN5N	53, 54	Differential input signal, Channel 5
2	IN6P, IN6N	56, 57	Differential input signal, Channel 6
2	IN7P, IN7N	59, 60	Differential input signal, Channel 7
2	IN8P, IN8N	62, 63	Differential input signal, Channel 8
2	LCLKP, LCLKN	31, 32	Differential LVDS bit clock (7X)
2	ACLKP, ACLKN	29, 30	Differential LVDS frame clock (1X)
2	OUT1A_P, OUT1A_N	13, 14	Differential LVDS data output, wire 1, channel 1

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# **PIN FUNCTIONS (continued)**

NUMBER	PIN	1	DESCRIPTION
OF PINS	NAME	NUMBER	DESCRIPTION
2	OUT1B_P, OUT1B_N	15, 16	Differential LVDS data output, wire 2, channel 1
2	OUT2A_P, OUT2A_N	17, 18	Differential LVDS data output, wire 1, channel 2
2	OUT2B_P, OUT2B_N	19, 20	Differential LVDS data output, wire 2, channel 2
2	OUT3A_P, OUT3A_N	21, 22	Differential LVDS data output, wire 1, channel 3
2	OUT3B_P, OUT3B_N	23, 24	Differential LVDS data output, wire 2, channel 3
2	OUT4A_P, OUT4A_N	25, 26	Differential LVDS data output, wire 1, channel 4
2	OUT4B_P, OUT4B_N	27, 28	Differential LVDS data output, wire 2, channel 4
2	OUT5A_P, OUT5A_N	35, 36	Differential LVDS data output, wire 1, channel 5
2	OUT5B_P, OUT5B_N	33, 34	Differential LVDS data output, wire 2, channel 5
2	OUT6A_P, OUT6A_N	39, 40	Differential LVDS data output, wire 1, channel 6
2	OUT6B_P, OUT6B_N	37, 38	Differential LVDS data output, wire 2, channel 6
2	OUT7A_P, OUT7A_N	43, 44	Differential LVDS data output, wire 1, channel 7
2	OUT7B_P, OUT7B_N	41, 42	Differential LVDS data output, wire 2, channel 7
2	OUT8A_P, OUT8A_N	47, 48	Differential LVDS data output, wire 1, channel 8
2	OUT8B_P, OUT8B_N	45, 46	Differential LVDS data output, wire 2, channel 8
1	PD	10	Power down control input. Active High. The pin has an internal 220-k $\Omega$ pulldown resistor.
1	REFB	69	Negative reference input and output. Internal reference mode: Reference bottom voltage (0.45 V) is output on this pin. A decoupling capacitor is not required on this pin. External reference mode: Reference bottom voltage (0.45 V) must be externally applied to this pin. Please see External Reference Mode of Operation.
1	REFT	70	Positive reference input and output. Internal reference mode: Reference top voltage (1.45 V) is output on this pin. A decoupling capacitor is not required on this pin. External reference mode: Reference top voltage (1.45 V) must be externally applied to this pin. Please see External Reference Mode of Operation.
1	RESET	51	Active HIGH RESET input. The pin has an internal 220-k $\Omega$ pulldown resistor.
1	SCLK	77	Serial clock input. The pin has an internal 220-k $\Omega$ pulldown resistor.
1	SDATA	76	Serial data input. The pin has an internal 220-kΩ pulldown resistor.
1	SDOUT	64	Serial data readout. This pin is in the high-impedance state after reset. When the <readout> bit is set, the SDOUT pin becomes active. SDOUT is a CMOS digital output running from the AVDD supply.</readout>
1	CSZ	75	Serial enable chip select – active-low digital input
1	SYNC	65	Input signal to synchronize channels and chips when used with reduced output data rates. If it is not used, add a $\leq$ 10-K $\Omega$ pulldown resistor.
2	LVDD	11, 49	Digital and I/O power supply, 1.8 V
2	LGND	12, 50	Digital ground
1	NC	67	No Connection. Must leave floated



#### **ABSOLUTE MAXIMUM RATINGS<sup>(1)</sup>**

over operating free-air temperature range (unless otherwise noted)

			VALUE	UNIT
		MIN	MAX	
Supply voltage	AVDD	-0.3	2.2	V
	LVDD	MIN         MAX           -0.3         2.2           -0.3         2.2           -0.3         2.2           -0.3         0.3           -0.3         0.3           -0.3         min[2.2, AVDD+0.3]	V	
	Between AGND and LGND	-0.3	0.3	V
Voltage	At analog inputs	-0.3	min[2.2, AVDD+0.3]	V
	At digital inputs, RESET, SCLK, SDATA, SYNC, PD, CSZ	-0.3	3.6	V
	At CLKN, CLKP <sup>(2)</sup> ,	-0.3	min[2.2, AVDD+0.3]	V
	At digital outputs	-0.3	min[2.2, LVDD+0.3]	V
Maximum juncti	on temperature (T <sub>J</sub> ), any condition		105	°C
Storage tempera	ature range	-55	150	°C
Operating temp	erature range	-40	85	°C
	Human Body Model (HBM)		2000	V
ESD Ratings	Charged Device Model (CDM)		500	V

(1) Stresses above those listed under absolute maximum ratings may cause permanent damage to the device. These are stress ratings only and functional operation of the device at these or any other conditions beyond those indicated under *recommended operating conditions* is not implied. Exposure to absolute maximum rated conditions for extended periods may degrade device reliability.

conditions is not implied. Exposure to absolute maximum rated conditions for extended periods may degrade device reliability.
 When AVDD is turned off, TI recommends to switch off the input clock (or ensure the voltage on CLKP, CLKN is < |0.3V|). This prevents the ESD protection diodes at the clock input pins from turning on.</li>

#### THERMAL INFORMATION

	THERMAL METRIC <sup>(1)</sup>	ADS5294	UNITS
		PFP (80 PINS)	UNITS
$\theta_{JA}$	Junction-to-ambient thermal resistance	30.8	
$\theta_{JCtop}$	Junction-to-case (top) thermal resistance	6.3	
$\theta_{JB}$	Junction-to-board thermal resistance	8.3	°C/W
Ψ <sub>JT</sub>	Junction-to-top characterization parameter	0.2	C/VV
$\Psi_{JB}$	Junction-to-board characterization parameter	8.2	
$\theta_{\text{JCbot}}$	Junction-to-case (bottom) thermal resistance	0.3	

(1) For more information about traditional and new thermal metrics, see the IC Package Thermal Metrics application report, SPRA953.

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### **RECOMMENDED OPERATING CONDITIONS**

			MIN	TYP	MAX	UNIT	
SUPPL	JES		·		·		
AVDD	Analog supply voltage		1.7	1.8	1.9	V	
LVDD	Digital supply voltage		1.7	1.8	1.9	V	
ANALO	DG INPUTS/OUTPUTS						
	Differential input voltage range			2		V <sub>PP</sub>	
	Input common-mode voltage			0.95±0.05		V	
$REF_{T}$	External reference mode			1.45		V	
$REF_B$	External reference mode			0.45		V	
VCM	Common-mode voltage output			0.95		V	
	External Reference mode Input			1.5		V	
	Maximum Input Frequency (1)	2 V <sub>PP</sub> amplitude		80		MHz	
CLOCI	K INPUTS						
	ADC Clock input sample rate		10		80	MSPS	
		Sine wave, AC-coupled	0.2	1.5			
	Input Clock amplitude differential (V <sub>(CLKP)</sub> – V <sub>(CLKN)</sub> ) peak-to-peak	LVPECL, AC-coupled	0.2	1.6		V <sub>PP</sub>	
	(CLKN)) peak to peak	LVDS, AC-coupled	0.2	0.7			
V <sub>IL</sub>		•		<0.3		V	
V <sub>IH</sub>	Input Clock CMOS single-ended (V <sub>(CLKP)</sub> )			>1.5		V	
	Input clock duty cycle		35%	50%	65%		
DIGITA	AL OUTPUTS						
	ACLKP and ACLKN outputs (LVDS), 1-wire	interface		1x (sample rate)		MSPS	
	LCLKP and LCLKN outputs (LVDS), 1-wire in	nterface		7x (sample rate)		MSPS	
	ACLKP and ACLKN outputs (LVDS), 2-wire	interface	0.	.5x (sample rate)		MSPS	
	LCLKP and LCLKN outputs (LVDS), 2-wire in	LCLKP and LCLKN outputs (LVDS), 2-wire interface				MSPS	
	Maximum data rate, 2-wire interface			560		Mbps	
	Maximum data rate, 1-wire interface			700		Mbps	
$C_{LOAD}$	Maximum external capacitance from each ou	utput pin to LGND		5		pF	
$R_{LOAD}$	Differential load resistance between the LVD	S output pairs		100		Ω	
T <sub>A</sub>	Operating free-air temperature		-40		85	°C	

(1) See the Large and Small Signal Input Bandwidth section.



#### ELECTRICAL CHARACTERISTICS DYNAMIC PERFORMANCE

Typical values are at 25°C, AVDD = 1.8 V, LVDD = 1.8 V, 50% clock duty cycle, -1 dBFS differential analog input, Sample rate = 80 MSPS, ADC is configured in internal reference mode (unless otherwise noted). MIN and MAX values are across the full temperature range  $T_{MIN} = -40^{\circ}$ C to  $T_{MAX} = 85^{\circ}$ C, AVDD = 1.8 V, LVDD = 1.8 V.

	PARAMETERS	CONDITIONS		MIN	TYP	MAX	UNITS
AC PERF	ORMANCE						
		f <sub>in</sub> = 10 MHz, 65 MSPS			75.6		dBFS
		$f_{in} = 5 \text{ MHz}, T_A = 25^{\circ}\text{C}$	$f_{in} = 5 \text{ MHz}, T_A = 25^{\circ}\text{C}$				
		f <sub>in</sub> = 5 MHz, Across temperatures	71.8			dBFS	
SNR	Signal-to-noise ratio	f <sub>in</sub> = 5 MHz, -60 dBFS Input signal amplitud	le		77.3		dBFS
		$f_{in}$ = 5 MHz, Decimation by two enabled			78.2		dBFS
		f <sub>in</sub> = 30 MHz			74.2		dBFS
		f <sub>in</sub> = 65 MHz			71.7		dBFS
		f <sub>in</sub> = 5 MHz			74.8		dBFS
SINAD Signal-to-noise and distortion ratio		f <sub>in</sub> = 30 MHz			73.4		dBFS
		f <sub>in</sub> = 65 MHz			70		dBFS
ENOB	Effective number of bits	f <sub>in</sub> = 5 MHz			12.2		Bits
DNL	Differential nonlinearity	f <sub>in</sub> = 5 MHz		-0.96	±0.5	1.7	LSB
INL	Integral nonlinearity	f <sub>in</sub> = 5 MHz	72	2.2 84	5.5	LSB	
			f <sub>in</sub> = 5 MHz				
SFDR	Spurious-free dynamic range	f <sub>in</sub> = 30 MHz			81		dBc
		f <sub>in</sub> = 65 MHz			74		dBc
		f <sub>in</sub> = 5 MHz	70.5	82		dBc	
THD	Total harmonic distortion	f <sub>in</sub> = 30 MHz			80		dBc
		f <sub>in</sub> = 65 MHz			73.5		dBc
		f <sub>in</sub> = 5 MHz		73	93		dBc
HD2	Second-harmonic distortion	f <sub>in</sub> = 30 MHz			88		dBc
		f <sub>in</sub> = 65 MHz			85		dBc
		f <sub>in</sub> = 5 MHz		72	84		dBc
HD3	Third-harmonic distortion	f <sub>in</sub> = 30 MHz			81		dBc
		f <sub>in</sub> = 65 MHz			74		dBc
		f <sub>in</sub> = 5 MHz		91		dBc dBc	
	Worse spur excluding HD2, HD3	f <sub>in</sub> = 30 MHz	f <sub>in</sub> = 30 MHz				
		f <sub>in</sub> = 65 MHz			76		dBc
IMD3	Intermodualtion distortion	$f_{in} = 8 \text{ MHz at } -7 \text{ dBFS}, f_2 = 10 \text{ MHz at } -7$			84.5		dBc
	Overload recovery	Recovery to within 1% of full-scale for 6-dE sine wave input	3 overload with		1		Clock Cycle
VTALK		$f_{in} = 10 \text{ MHz}, -1 \text{-}dBFS \text{ signal applied on}$	far channel		90		dBc
XTALK	Cross-talk	aggressor channel no signal applied on victim channel	near channel		85		dBc
	Phase noise	5 MHz, 1-kHz off carrier			-138		dBc/Hz
ANALOG	INPUT / OUTPUT			1			I
	Differential input voltage range (0-dB gain)				2		V <sub>PP</sub>
R <sub>IN</sub>	Differential Input Resistance	At DC			2		kΩ
CIN	Differential Input Capacitance	At DC			3.2		pF
	Analog input bandwidth	With a 50-Ω source impedance			550		MHz
	Analog input common-mode current (per input pin)				1.6		µA/MSPS
	VCM common-mode output voltage				0.95		V
	VCM output current capability				5		mA

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# ELECTRICAL CHARACTERISTICS DYNAMIC PERFORMANCE (continued)

Typical values are at 25°C, AVDD = 1.8 V, LVDD = 1.8 V, 50% clock duty cycle, -1 dBFS differential analog input, Sample rate = 80 MSPS, ADC is configured in internal reference mode (unless otherwise noted). MIN and MAX values are across the full temperature range  $T_{MIN} = -40^{\circ}$ C to  $T_{MAX} = 85^{\circ}$ C, AVDD = 1.8 V, LVDD = 1.8 V.

	PARAMETERS	CONDITIONS	MIN TYP	MAX	UNITS
DC ACCU	RACY				
	Offset error	Across devices and across channels within a device	-15	15	mV
	Temperature coefficient of offset error		< 0.01		mV/ °C
E <sub>(GREF)</sub>	Gain error due to internal reference inaccuracy alone	Across devices	-2	2	%FS
E <sub>(GCHAN)</sub>	Gain error of channel alone		0.5		%FS
	Temperature coefficient of E(GCHAN)		< 0.01		%FS/ °C
POWER S	SUPPLY				
		80 MSPS, 14 Bit, 2-wire LVDS	77		mW/CH
		50 MSPS, 1 wire LVDS	58		mW/CH
	Power consumption	40 MSPS, 14 Bit, 1-wire LVDS	52		mW/CH
		10 MSPS, 14 Bit, 1-wire LVDS	33		mW/CH
		f <sub>in</sub> = 10 MHz, 80 MSPS, 14 Bit, Decimation filter = 2, 1-wire LVDS	100		mW/CH
		14 Bit, 80 MSPS	230	265	mA
AVDD		14 Bit, 65 MSPS	200		mA
		14 Bit, 40 MSPS	155		mA
		80 MSPS, 14 Bit, 2-wire LVDS	111	122	mA
		50 MSPS, 14 Bit, 1-wire LVDS	80		mA
LVDD		40 MSPS, 14 Bit, 1-wire LVDS	73		mA
		80 MSPS, 1 Bit, Decimation filter = 2, 1-wire LVDS	210		mA
		Partial Power Down (80 MSPS, 2-wire)	175		mW
	Power-down power consumption	Complete Power Down		60	mW
	Power supply modulation ratio	Carrier = 5 MHz, f <sub>(PSRR)</sub> = 10 kHz, 50 mVpp on AVDD	35		dB
	Power supply rejection ratio	AC power supply rejection ratio f = 10 kHz	55		dB

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### DIGITAL CHARACTERISTICS

The DC specifications refer to the condition where the digital outputs are not switching, but are permanently at a valid logic level 0 or 1. AVDD = 1.8V, LVDD = 1.8V

	PARAMETERS	CONDITION	MIN	TYP	MAX	UNITS
DIGITA	L INPUTS/OUTPUTS					
V <sub>IH</sub>	Logic high input voltage	All digital inputs support 1.8-V and 3.3-V CMOS logic levels.	1.3			V
V <sub>IL</sub>	Logic low input voltage				0.4	V
I <sub>IH</sub>	Logic high input current	V <sub>HIGH</sub> = 1.8 V		6		μA
IIL	Logic low input current	$V_{LOW} = 0 V$		< 0.1		μA
V <sub>OH</sub>	Logic high output voltage		A۱	/DD - 0.1		V
V <sub>OL</sub>	Logic low output voltage			0.2		V
LVDS (	OUTPUTS					
V <sub>ODH</sub>	High-level output differential voltage	100-Ω external termination	245	350	405	mV
V <sub>ODL</sub>	Low-level output differential voltage	100-Ω external termination	-245	-350	-405	mV
V <sub>OCM</sub>	Output common-mode voltage		900	1100	1300	mV

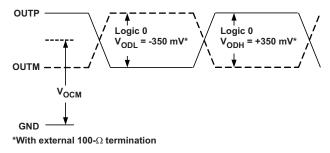


Figure 2. LVDS Output Voltage Levels

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# TIMING REQUIREMENTS<sup>(1)(2)(3)</sup>

Typical values are at 25°C, AVDD = 1.8 V, LVDD = 1.8 V, sampling frequency = 80 MSPS, 14-bit, sine wave input clock = 1.5 Vpp clock amplitude,  $C_{LOAD} = 5 \text{ pF}$ ,  $R_{LOAD} = 100 \Omega$ , unless otherwise noted. MIN and MAX values are across the full temperature range  $T_{MIN} = -40^{\circ}$ C to  $T_{MAX} = 85^{\circ}$ C, AVDD = 1.8 V, LVDD = 1.7 V to 1.9 V

	PARAMETERS	CONDITIONS	MIN	TYP	MAX	UNITS
t <sub>a</sub>	Aperture delay	The delay in time between the rising edge of the input sampling clock and the actual time at which the sampling occurs		4		ns
	Aperture delay variation	Across channels within the same device		±175		ps
		Across devices at the same temperature and LVDD supply		2.5		ns
tj	Aperture jitter RMS			320		fs rms
	Data latanay	1-wire LVDS output interface		11		Clock cycles
t <sub>d</sub> Data latency		2-wire LVDS output interface		15		Clock cycles
t <sub>SU</sub>	Data setup time	80 MSPS, 2-wire LVDS, 7x-serialization	0.34	0.57		ns
t <sub>H</sub>	Data hold time	80 MSPS, 2-wire LVDS, 7x-serialization	0.55	0.8		ns
t <sub>PROP</sub>	Clock propagation delay	Input clock rising edge (zero cross) to frame clock rising edge (zero cross)	See Table 1 and Table 2			
11101	Variation of t <sub>PROP</sub>	Between two devices at same temperature and LVDD supply		±0.75		ns
	LVDS bit clock duty cycle			48%		
t <sub>RISE</sub>	Data rise time	Rise time is from −100 mV to + 100 mV, 10 ≤ Fs ≤ 80 MSPS		0.24		ns
t <sub>FALL</sub>	Data fall time	Fall time is from +100 mV to −100 mV, 10 ≤ Fs ≤ 80 MSPS		0.24		ns
t <sub>CLKRISE</sub>	Output clock rise time	Rise time is from −100 mV to +100 mV, 10 ≤ Fs ≤ 80 MSPS		0.20		ns
t <sub>CLKFALL</sub>	Output clock fall time	Fall time is from +100 mV to −100 mV, 10 ≤ Fs ≤ 80 MSPS		0.20		ns
t <sub>WAKE</sub>	Wake-up Time	Time to valid data after coming out of COMPLETE POWER- DOWN mode		100		μs
		Time to valid data after coming out of PARTIAL POWER- DOWN mode (with clock continuing to run during power- down)		5		μs

(1) Timing parameters are ensured by design and characterization and not tested in production.

(2) Measurements are done with a transmission line of 100-Ω characteristic impedance between the device and the load. Setup and hold time specifications take into account the effect of jitter on the output data and clock.

(3) Data valid refers to logic HIGH of 100 mV and logic LOW of -100 mV.



# Table 1. LVDS Timing at Different Sampling Frequencies — 2-Wire Interface, 7x-Serialization, Digital Filter Disabled <sup>(1)</sup>

ADC CLK Frequency (MSPS)	Setu	ıp Time (t <sub>sւ</sub>	"), ns	Hold Time (t <sub>H</sub> ), ns Zero-Crossing of LCLKP to Data Becoming Invalid (both edges)			t <sub>PROG</sub> = (6 / 7) × T + t <sub>delay</sub> , ns <sup>(2)</sup> t <sub>PROG</sub> = delay from Input clock zero-cross rising edge to frame clock zero cross (rising edge)			
Fs = 1 / T	Cros	a Valid to Z ssing of LC both edges	LKP							
	MIN	TYP	MAX	MIN	ТҮР	MAX	MIN	TYP	MAX	
80	0.34	0.57		0.55	0.8		8	9.5	11	
65	0.35	0.64		0.8	1.1		8	9.5	11	
50	0.7	0.9		1.2	1.5		8	9.5	11	
40	1	1.3		1.6	1.85		8	9.5	11	
30	1.7	2		2	2.3		8	9.5	11	
20	2.9	3.2		3.2	3.5		8	9.5	11	
10	6.5	6.7		6.7	7		8	9.5	11	

(1) Bit clock and Frame clock jitter has been included in the Setup and hold timing.

(2) Values below correspond to tdelay, NOT t<sub>PROG</sub>

# Table 2. LVDS Timing at Different Sampling Frequencies — 1-Wire Interface, 14x-Serialization, DigitalFilter Disabled <sup>(1)</sup>

ADC CLK Frequency (MSPS)	Setu	Setup Time (t <sub>su</sub> ), ns			Hold Time (t <sub>H</sub> ), ns			$t_{PROG} = (5 / 7) \times T + t_{delay}, ns^{(2)}$			
Fs = 1 / T	Data Valid to Zero- Crossing of LCLKP (both edges)			Zero-Crossing of LCLKP to Data Becoming Invalid (both edges)			t <sub>PROG</sub> = delay from Input clock zero-cross rising edge to frame clock zero cross (rising edge)				
	MIN	ТҮР	MAX	MIN	TYP	MAX	MIN	ТҮР	MAX		
50	0.28	0.48		0.28	0.6		7.5	9	10.5		
40	0.5	0.68		0.54	0.8		7.5	9	10.5		
30	0.62	0.8		1	1.25		7.5	9	10.5		
20	1.2	1.4		1.6	1.9		7.5	9	10.5		
10	3.1	3.3		3.3	3.5		7.5	9	10.5		

(1) Bit clock and Frame clock jitter has been included in the Setup and hold timing.

(2) Values below correspond to tdelay, NOT tPROG

#### NOTE

The LVDS timing specification is only valid when digital decimation filters are disabled. When digital filters are enabled, the setup time decreases as the corresponding hold time increases as shown in Table 3 to Table 5. The change on LVDS timing also depends on the internal PLL setting of the ADS5294. See PLL Operation Versus LVDS Timing for more information.

At the highest sampling frequency, 80-MSPS, and decimation of 2 (for example: effective data rate = 560 Mbps in 1-wire mode), the setup time is reduced by 70 ps, (for example: setup time, min = 0.43 ns; hold time, min = 0.54 ns). scenario assumes that the recommended PLL settings are configured as shown in PLL Operation Versus LVDS Timing

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# Table 3. LVDS Timing at Different Sampling Frequencies — 1-Wire Interface, 14x-Serialization, Decimation by 2 Filter Enabled (1)(2)(3)

ADC CLK Frequency (MSPS)	Setu	p Time (t <sub>s</sub>	<sub>su</sub> ), ns	Но	Hold Time (t <sub>H</sub> ), ns			$t_{PROG} = (6 / 7) \times T + t_{delay}, ns^{(4)}$			
Fs = 1 / T	Data Valid to Zero- Crossing of LCLKP (both edges)			Crossing of LCLKP Data Becoming Invalid		of LCLKP Data Becoming Invalid rising edge to		ay from input clo to frame clock ze edge)			
	MIN	TYP	MAX	MIN	TYP	MAX	MIN	ТҮР	MAX		
80	0.43			0.54			7.5	9	10.5		
60	0.54			0.9			7.5	9	10.5		
40	1.1			1.45			7.5	9	10.5		

(1) Bit clock and Frame clock jitter has been included in the Setup and hold timing.

(2) The LVDS timing depends on the state of the internal PLL. Use Table 13 to configure the PLL when decimation by two is enabled.
(3) For any given ADC input clock frequency, TI recommends to use the highest PLL state to get the best setup time. The timing numbers are specified under this condition. For example, for a 40-MSPS input clock frequency, use PLL state 3 to get setup time ≥1.1ns. PLL state 2 can also be used at 40 MSPS, however, the setup time degrades by 100 to 200 ps (while the hold time improves by a similar amount).

(4) Values below correspond to tdelay, NOT tPROG

# Table 4. LVDS Timing at Different Sampling Frequencies — 1-Wire Interface, 14x-Serialization, Decimation by 4 Filter Enabled <sup>(1)(2)(3)</sup>

ADC CLK Frequency (MSPS)	Setu	p Time (t <sub>s</sub>	<sub>u</sub> ), ns	Но	ld Time (t <sub>H</sub> ),	ns	t <sub>PROG</sub>	<sub>6</sub> = (8 / 7) × T + t <sub>de</sub>	<sub>lay</sub> , ns <sup>(4)</sup>
Fs = 1 / T	Cros	Valid to a sing of Lo	CLKP	Data	ossing of L0 Becoming Ir (both edges)	nvalid		ay from input clo to frame clock ze edge)	
	MIN	TYP	MAX	MIN	TYP	MAX	MIN	ТҮР	MAX
80	1			1.5			7.5	9	10.5
60	1.7			1.7			7.5	9	10.5

(1) Bit clock and Frame clock jitter has been included in the Setup and hold timing.

(2) The LVDS timing depends on the state of the internal PLL. Use Table 14 to configure the PLL when decimation by 4 is enabled

(3) For any given ADC input clock frequency, TI recommends to use the highest PLL state to get best setup time. The timing numbers are specified under this condition.

(4) Values below correspond to tdelay, NOT tPROG

# Table 5. LVDS Timing at Different Sampling Frequencies — 1-Wire Interface, 14x-Serialization, Decimation by 8 Filter Enabled (1)(2)(3)

ADC CLK Frequency (MSPS)	Setu	p Time (t <sub>s</sub>	<sub>u</sub> ), ns	Но	ld Time (t <sub>H</sub> ),	ns	t <sub>PROC</sub>	<sub>3</sub> = (5 / 7) × T + t <sub>de</sub>	<sub>lay</sub> , ns <sup>(4)</sup>
Fs = 1 / T	Cros	Valid to a sing of Lopoth edge	CLKP	Data	ossing of L( Becoming lı (both edges	nvalid		lay from Input clo to frame clock ze edge)	
	MIN	TYP	MAX	MIN	TYP	MAX	MIN	ТҮР	MAX
80	2.9			3.2			7.5	9	10.5

(1) Bit clock and Frame clock jitter has been included in the Setup and hold timing.

(2) The LVDS timing depends on the state of the internal PLL. Use Table 15 to configure the PLL when decimation by 8 is enabled

(3) For any given ADC input clock frequency, TI recommends using the highest PLL state to get best setup time. The timing numbers are specified under this condition.

(4) Values below correspond to tdelay, NOT tPROG



# LVDS TIMING DIAGRAM

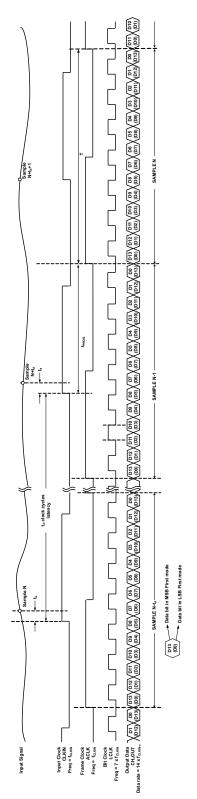


Figure 3. 14-Bit 1-Wire LVDS Timing Diagram

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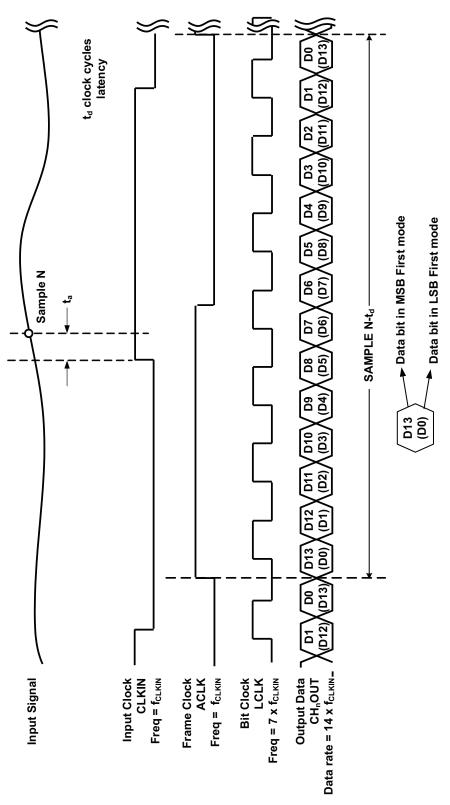


Figure 4. Enlarged 1-Wire LVDS Timing Diagram (14 bit)



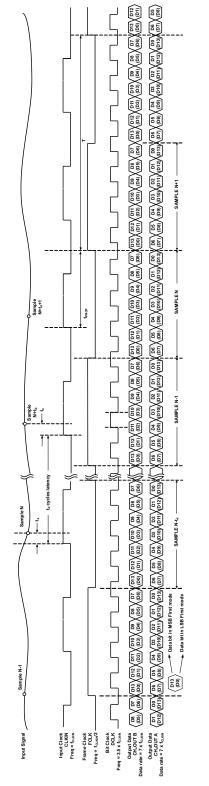


Figure 5. 14-Bit 2-Wire LVDS Timing Diagram



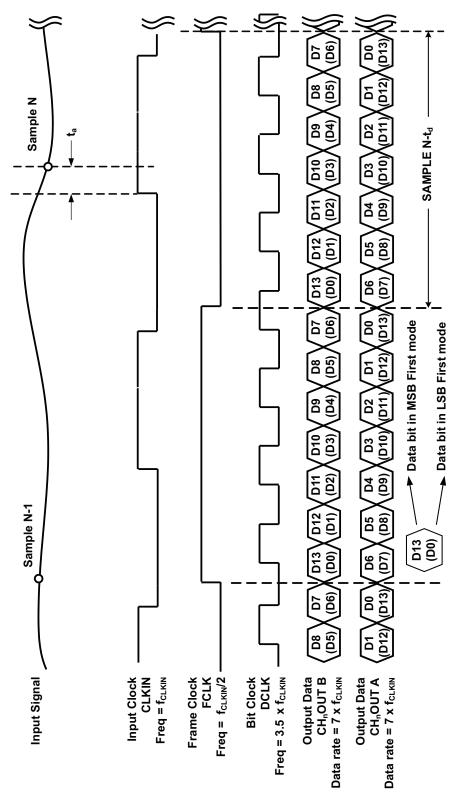


Figure 6. Enlarged 2-Wire LVDS Timing Diagram (14 bit)



t<sub>SU1</sub>

t<sub>H1</sub>

Figure 7. Definition of Setup and Hold Times  $t_{SU} = min(t_{SU1}, t_{SU2}); t_H = min(t_{H1}, t_{H2})$ 

t<sub>H2</sub>

t<sub>SU2</sub>

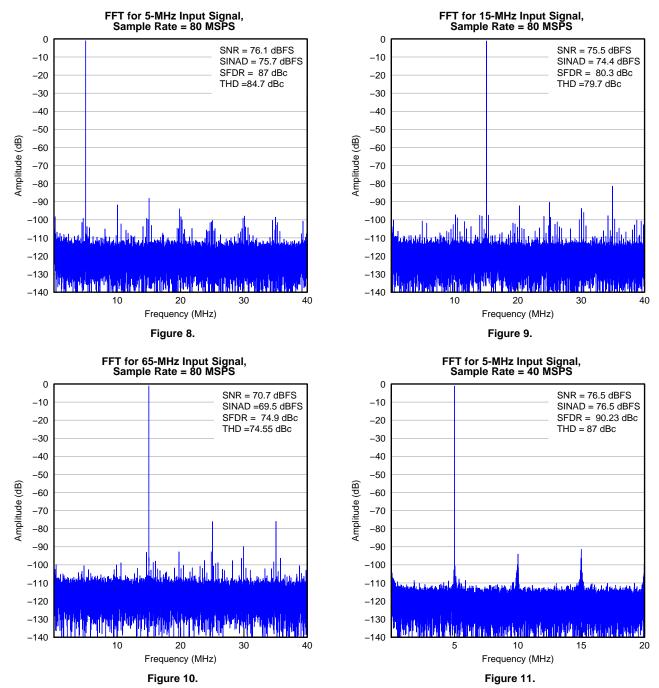
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# TYPICAL CHARACTERISTICS

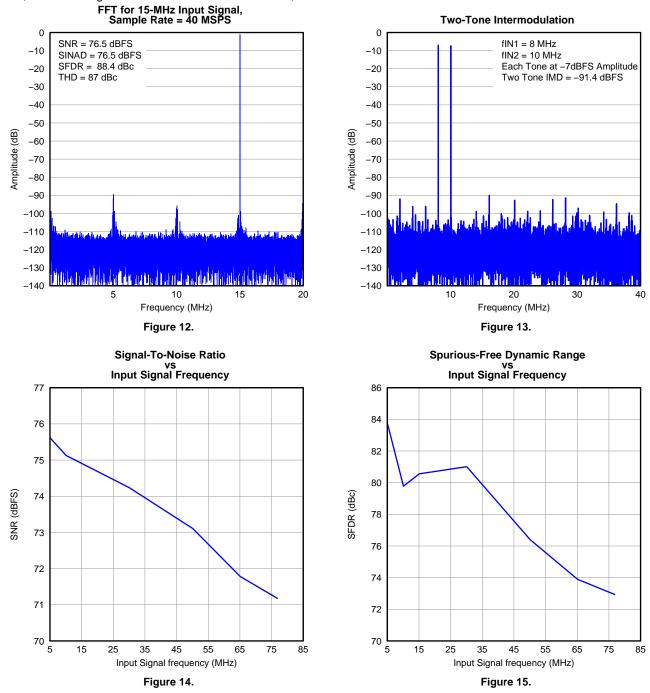




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#### **TYPICAL CHARACTERISTICS (continued)**



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#### Typical values are at 25°C, AVDD = 1.8 V, LVDD = 1.8 V, 50% clock duty cycle, -1-dBFS differential analog input, 14 Bit/ 80 SFDR SNR vs Digital Gain vs Digital Gain 80 90 Input frequency = 10 MHz Input frequency = 10 MHz Input frequency = 70 MHz Input frequency = 70 MHz 76 86 72 82 SNR (dBFS) SFDR (dBc) 68 78 64 74 60 70 6 0 1 2 3 4 5 6 7 8 9 10 11 0 1 2 3 4 5 7 8 9 10 11 12 12 Digital gain (dB) Digital gain (dB) G001 G001 Figure 16. Figure 17. Performance Performance vs Input Amplitude vs Clock Input Amplitudes 120 80 88 78 SFDR 110 79.5 SNR 100 79 87 77 90 78.5 76 80 78 86 SFDR (dBFS,dBc) 77.5 (982) 77 (982) 8NK (982) 70 SNR (dBFS) SFDR (dBc) 60 85 75 50 40 76 74 84 30 75.5 20 75 83 73 SNR SFDR(dBc) 10 74.5 SFDR(dBFS) 82 0.2 0.4 0 74 -76 -66 -56 -46 -36 -26 0.6 0.8 1.2 1.4 1.6 1.8 2 2.2 , -96 -86 -16 -6 0 1 Input amplitude (dBFS) Input Clock Amplitude, differential (Vp-p) Figure 18. Figure 19.

### **TYPICAL CHARACTERISTICS (continued)**

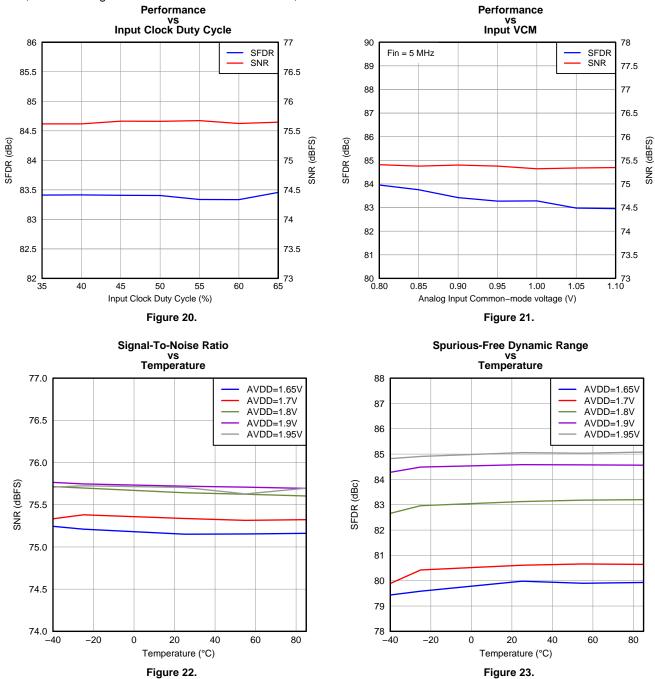
MSPS, ADC is configured in the internal reference mode, unless otherwise noted.



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**TYPICAL CHARACTERISTICS (continued)** 



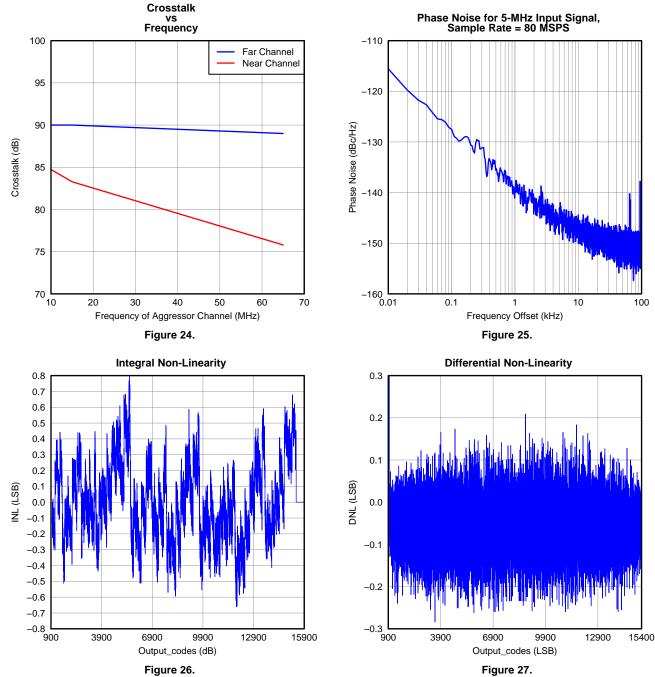
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### **TYPICAL CHARACTERISTICS (continued)**

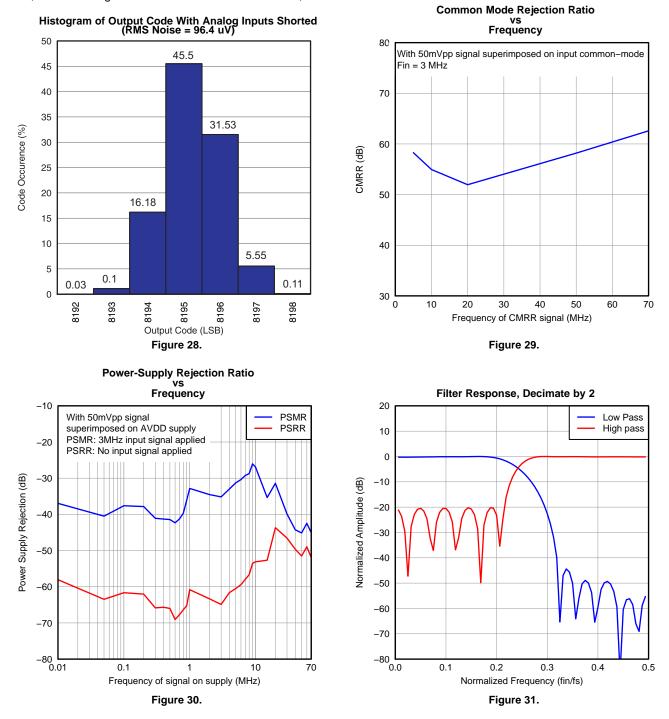




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#### **TYPICAL CHARACTERISTICS (continued)**



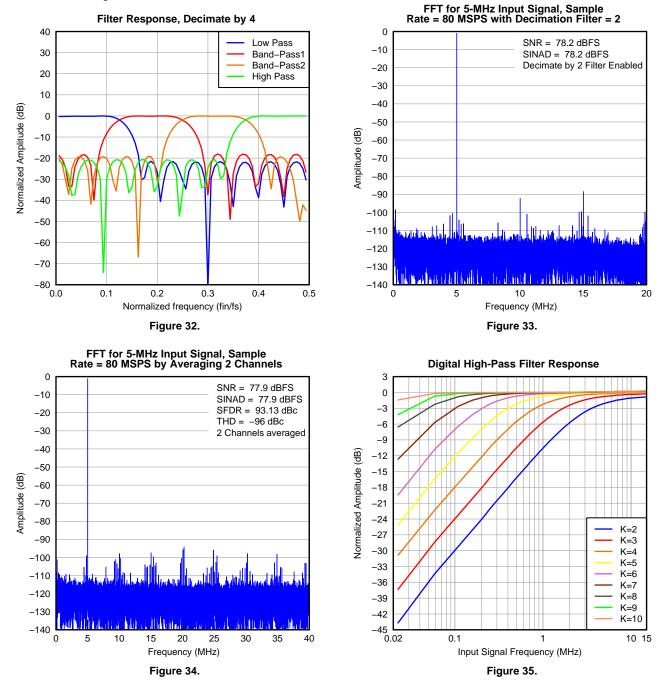
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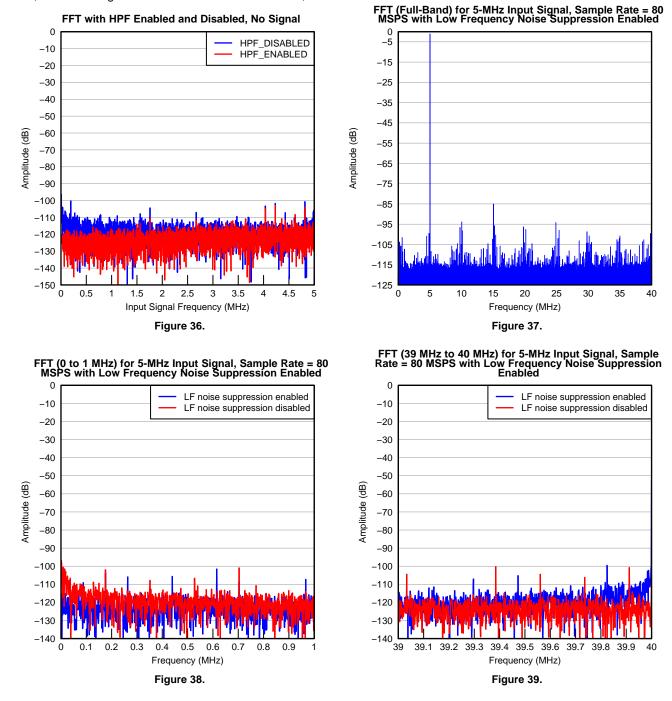




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#### **TYPICAL CHARACTERISTICS (continued)**



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#### Typical values are at 25°C, AVDD = 1.8 V, LVDD = 1.8 V, 50% clock duty cycle, -1-dBFS differential analog input, 14 Bit/ 80 MSPS, ADC is configured in the internal reference mode, unless otherwise noted. Power Consumption on Analog Supply Power Consumption on Digital Supply 2-wire 1-wire 1-wire Decimate by 2 Analog Power (mW) Digital Power (mW) 15 20 25 30 35 40 45 50 55 60 65 70 75 80 Sampling Frequency (MSPS) Sampling Frequency (MSPS) Figure 40. Figure 41. Supply Current on Analog Supply Supply Current on Digital Supply 2-wire 1-wire 1-wire Decimate by 2 Analog Current (mA) Digital Current (mA) Sampling Frequency (MSPS) Sampling Frequency (MSPS) Figure 42. Figure 43.

# **TYPICAL CHARACTERISTICS (continued)**

#### EXAS **NSTRUMENTS**



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#### SERIAL INTERFACE

ADS5294 has a set of internal registers that can be accessed by the serial interface formed by pins CSZ (Serial interface Enable – Active Low), SCLK (Serial Interface Clock), and SDATA (Serial Interface Data).

When CSZ is low,

- Serial shift of bits into the device is enabled
- Serial data (SDATA) is latched at every rising edge of SCLK
- SDATA is loaded into the register at every 24<sup>th</sup> SCLK rising edge.

If the word length exceeds a multiple of 24 bits, the excess bits are ignored. Data can be loaded in multiples of 24-bit words within a single active CSZ pulse. The first eight bits form the register address and the remaining 16 bits form the register data. The interface works with SCLK frequencies from 15 MHz down to very low speeds (a few Hertz) and also with non-50% SCLK duty cycle.

#### **Register Initialization**

After power-up, initialize the internal registers to the respective default values. Initialization occurs in one of two ways:

- 1. Through a hardware reset, by applying a high pulse on the RESET pin.
- Through a software reset: using the serial interface, set the RST bit high. Setting this bit initializes the internal registers to the respective default values and then self-resets the bit low. In this case, the RESET pin stays low (inactive).

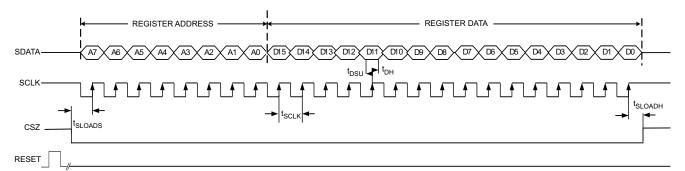


Figure 44. Serial Interface Timing

#### SERIAL INTERFACE TIMING CHARACTERISTICS

The table shows typical values at 25°C. MIN and MAX values are across the full temperature range  $T_{MIN} = -40$ °C to  $T_{MAX} = 85$ °C, AVDD = 1.8 V, LVDD = 1.8 V, unless otherwise noted.

	PARAMETER	MIN	TYP	MAX	UNIT
f <sub>SCLK</sub>	SCLK frequency (= 1 / t <sub>SCLK</sub> )	> DC		15	MHz
t <sub>SLOADS</sub>	CS to SCLK setup time	33			ns
t <sub>SLOADH</sub>	SCLK to $\overline{CS}$ hold time	33			ns
t <sub>DS</sub>	SDATA setup time	33			ns
t <sub>DH</sub>	SDATA hold time	33			ns

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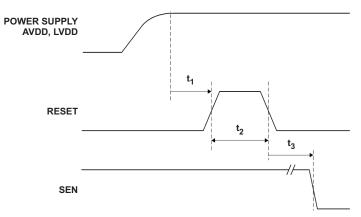


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# **RESET TIMING**

The table shows typical values at 25°C. MIN and MAX values are across the full temperature range  $T_{MIN} = -40$ °C to  $T_{MAX} = 85$ °C (unless otherwise noted)

	PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
t <sub>1</sub>	Power-on delay	Delay from power up of AVDD and LVDD to RESET pulse active		1		ms
t <sub>2</sub>	Reset pulse duration	Pulse duration of active RESET signal	50			ns
t <sub>3</sub>	Register write delay	Delay from RESET disable to CSZ active		100		ns



NOTE: A high-going pulse on RESET pin is required in serial interface mode in case of initialization through hardware reset. Tie RESET permanently HIGH for parallel interface operation.

#### Figure 45. Reset Timing Diagram



#### **Serial Register Readout**

The device includes a mode where the contents of the internal registers can be read back on the SDOUT pin. This mode is useful as a diagnostic check to verify the serial interface communication between the external controller and the ADC.

By default, after power up and device reset, the SDOUT pin is in the high-impedance state. When the readout mode is enabled using the register bit <READOUT>, SDOUT outputs the contents of the selected register serially, described as follows.

• Set register bit <READOUT> = 1 to put the device in serial readout mode. This setting disables any further writes into the internal registers, EXCEPT the register at address 1.

- Note that the <READOUT> bit itself is also located in register 1.

The device can exit readout mode by writing <READOUT> to 0.

Only the contents of register at address 1 cannot be read in the register readout mode.

- Initiate a serial interface cycle specifying the address of the register (A7–A0) whose content is to be read.
- The device serially outputs the contents (D15–D0) of the selected register on the SDOUT pin.
- The external controller can latch the contents at the rising edge of SCLK.
- To exit the serial readout mode, reset register bit <READOUT> = 0, which enables writes into all registers of the device. At this point, the SDOUT pin enters the high-impedance state.

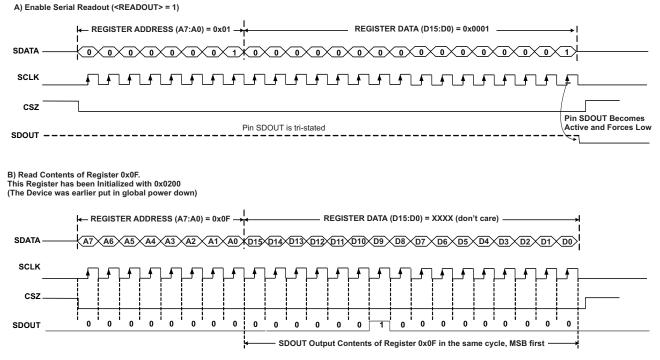


Figure 46. Serial Readout Timing



# **DEFAULT STATES AFTER RESET**

- Device is in normal operation mode with 14-bit ADC enabled for all channels
- Output interface is 1-wire, 14x-serialization with 7x-bit clock and 1x-frame clock frequency
- Serial readout is disabled
- PDN pin is configured as global power-down pin
- Digital gain is set to 0 dB
- Digital modes such as LFNS and digital filters are disabled

# **Register Map**

# Table 6. Summary of Functions Supported by Serial Interface <sup>(1)(2)(3)(4)</sup>

ADDR. (HEX)	D15	D14	D13	D12	D11	D10	D9	D8	D7	D6	D5	D4	D3	D2	D1	D0	NAME	DESCRIPTION
00																х	RST	1: Self-clearing software RESET; . After reset, this bit is set to 0 0: Normal operation.
																Х	EN_READOUT	1: READOUT of registers mode;0: Normal operation
01												х					EN_HIGH_ADDRS	0 – Disable access to register at address 0xF0 1 – Enable access to register at address 0xF0
02			х														EN_SYNC	1:Enable SYNC feature to synchronize the test patterns; 0: Normal operation, SYNC feature is disabled for the test patterns. Note: this bit needs to be set as 1 when software or hardware SYNC feature is used. see Reg.0x25[8] and 0x25[15]
0A	Х	Х	Х	Х	Х	Х	Х	Х	Х	Х	Х	Х	Х	Х	Х	Х	RAMP_PAT_RESET_VAL	Ramp pattern reset value
									х	х	х	х	х	х	х	х	PDN_CH<8:1>	1:Channel-specific ADC power-down mode; 0: Normal operation
0F								х									PDN_PARTIAL	1:Partial power-down mode - fast recovery from power-down; 0: Normal operation
UF							х										PDN_COMPLETE	1:Register mode for complete power-down - slower recovery; 0: Normal operation
						х											PDN_PIN_CFG	1:Configures PD pin for partial power-down mode; 0:Configures PD pin for complete power-down mode
14									х	х	х	х	х	х	х	х	LFNS_CH<8:1>	1: Channel-specific low-frequency noise suppression mode enable; 0: LFNS disabled
1C		х															EN_FRAME_PAT	1: Enables output frame clock to be programmed through a pattern; 0: Normal operation on frame clock
			Х	Х	Х	Х	Х	Х	Х	Х	х	Х	Х	Х	Х	Х	ADCLKOUT<13:0>	14-bit pattern for frame clock on ADCLKP and ADCLKN pins
23	Х	Х	Х	Х	Х	Х	Х	Х	Х	Х	Х	Х	Х	Х	Х	Х	PRBS_SEED<15:0>	PRBS pattern starting seed value lower 16 bits
24									х	х	х	х	х	х	х	х	INVERT_CH<8:1>	1: Swaps the polarity of the analog input pins electrically; 0: Normal configuration
	Х	Х	Х	Х	х	х	Х										PRBS_SEED<22:16>	PRBS seed starting value upper 7 bits

(1) The unused bits in each register (identified as blank table cells) must be programmed as '0'.

(2) X = Register bit referenced by the corresponding name and description

(3) Bits marked as '0' should be forced to 0, and bits marked as '1' should be forced to 1 when the particular register is programmed.

(4) Multiple functions in a register can be programmed in a single write operation.

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ADDR. (HEX)	D15	D14	D13	D12	D11	D10	D9	D8	D7	D6	D5	D4	D3	D2	D1	D0	NAME	DESCRIPTION
. ,										x	0	0					EN_RAMP	1: Enables a repeating full-scale ramp pattern on the outputs; 0: Normal operation
										0	х	0					DUALCUSTOM_PAT	1:Enables mode wherein output toggles between two defined codes; 0: Normal operation
										0	0	х					SINGLE_CUSTOM_PAT	1: Enables mode wherein output is a constant specified code; 0: Normal operation
															х	х	BITS_CUSTOM1<13:12>	2 MSBs for single custom pattern (and for the first code of the dual custom patterns)
													Х	х			BITS_CUSTOM2<13:12>	2 MSBs for second code of the dual custom patterns
25								x									TP_SOFT_SYNC	1: Software sync bit for test patterns on all 8 CHs; 0: No sync. Note: in order to synchronize the digital filters using the SYNC pin, this bit must be set as 0.
				х													PRBS_TP_EN	1: PRBS test pattern enable bit; 0: PRBS test pattern disabled
			Х														PRBS_MODE_2	PRBS 9 bit LFSR (23bit LFSR is default)
		х															PRBS_SEED_FROM_REG	1: Enable PRBS seed to be chosen from register 0x23 and 0x24; 0: Disabled
	x																TP_HARD_SYNC	1: Enable the external SYNC feature for syncing test patterns. 0: Inactive. Note: in order to synchronize the digital filters using the SYNC pin, this bit must be set as 0.
26	х	х	х	х	х	х	х	х	х	х	х	х					BITS_CUSTOM1<11:0>	12 lower bits for single custom pattern (and for the first code of the dual custom pattern).
27	х	Х	Х	х	Х	Х	Х	Х	Х	Х	Х	Х					BITS_CUSTOM2<11:0>	12 lower bits for second code of the dual custom pattern
	х																EN_BITORDER	Enables the bit order output. 0 = byte-wise, 1 = word-wise
28	0							x									BIT_WISE	Selects between byte-wise and bit-wise 1: bit-wise, odd bits come out on one wire and even bits come out on other wire 0: byte-wise, upper bits on one wire and lower bits on other wire Note: D15 must be set to '0' for this mode
	1								x	x	х	х	x	x	x	х	EN_WORDWISEBY_CH<7:0>	<ol> <li>Output format is one sample on one LVDS wire and next sample on other LVDS wire.</li> <li>Data comes out in 2-wire mode with upper set of bits on one channel and lower set of bits on the other.</li> <li>Note: D15 must set to '1' for this mode.</li> </ol>
															х		GLOBAL_EN_FILTER	1: Enables filter blocks - global control; 0: Inactive
29																х	EN_CHANNEL_AVG	1: Enables channel averaging mode; 0: Inactive
													Х	Х	Х	Х	GAIN_CH1<3:0>	Programmable gain - Channel 1
									Х	Х	Х	Х					GAIN_CH2<3:0>	Programmable gain - Channel 2
2A					х	Х	Х	Х									GAIN_CH3<3:0>	Programmable gain - Channel 3
	х	Х	Х	Х													GAIN CH4<3:0>	Programmable gain - Channel 4



ADDR. (HEX)	D15	D14	D13	D12	D11	D10	D9	D8	D7	D6	D5	D4	D3	D2	D1	D0	NAME	DESCRIPTION
	х	Х	х	Х													GAIN_CH5<3:0>	Programmable gain - Channel 5
2B					Х	Х	Х	Х									GAIN_CH6<3:0>	Programmable gain - Channel 6
28									Х	Х	Х	Х					GAIN_CH7<3:0>	Programmable gain - Channel 7
													Х	Х	Х	Х	GAIN_CH8<3:0>	Programmable gain - Channel 8
						Х	Х										AVG_CTRL4<1:0>	Averaging control for what comes out on LVDS output OUT4
2C									Х	Х							AVG_CTRL3<1:0>	Averaging control for what comes out on LVDS output OUT3
20												Х	Х				AVG_CTRL2<1:0>	Averaging control for what comes out on LVDS output OUT2
															Х	Х	AVG_CTRL1<1:0>	Averaging control for what comes out on LVDS output OUT1
						х	х										AVG_CTRL8<1:0>	Averaging control for what comes out on LVDS output OUT8
2D									Х	Х							AVG_CTRL7<1:0>	Averaging control for what comes out on LVDS output OUT7
20												Х	Х				AVG_CTRL6<1:0>	Averaging control for what comes out on LVDS output OUT6
															Х	Х	AVG_CTRL5<1:0>	Averaging control for what comes out on LVDS output OUT5
							Х	Х	Х								FILTER1_COEFF_SET<2:0>	Select stored coefficient set for filter 1
										Х	х	х					FILTER1_RATE<2:0>	Set decimation factor for filter 1
														Х			ODD_TAP1	Use odd tap filter 1
2E																х	USE_FILTER1	1: Enables filter for channel 1; 0: Disables
			Х	Х	Х	Х											HPF_CORNER _CH1	HPF corner in values k from 2 to 10
		х															HPF_EN_CH1	1: HPF filter enable for the channel; 0: Disables
							Х	Х	Х								FILTER2_COEFF_SET<2:0>	Select stored coefficient set for filter 2
										Х	х	Х					FILTER2_RATE<2:0>	Set decimation factor for filter 2
														Х			ODD_TAP2	Use odd tap filter 2
2F																х	USE_FILTER2	1: Enables filter for channel 2; 0: Disables
			Х	Х	Х	Х											HPF_CORNER _CH2	HPF corner in values k from 2 to 10
		х															HPF_EN_CH2	1: HPF filter enabled for the channel; 0: Disabled
							х	Х	Х								FILTER3_COEFF_SET<2:0>	Select stored coefficient set for filter 3
										х	Х	х					FILTER3_RATE<2:0>	Set decimation factor for filter 3
														Х			ODD_TAP3	Use odd tap filter 3
30																х	USE_FILTER3	1: Enables filter for channel 3; 0: Disables
			Х	Х	Х	Х											HPF_CORNER _CH3	HPF corner in values k from 2 to 10
		х															HPF_EN_CH3	1: HPF filter enabled for the channel; 0: Disabled



ADDR. (HEX)	D15	D14	D13	D12	D11	D10	D9	D8	D7	D6	D5	D4	D3	D2	D1	D0	NAME	DESCRIPTION
							Х	Х	Х								FILTER4_COEFF_SET<2:0>	Select stored coefficient set for filter 4
										Х	Х	Х					FILTER4_RATE<2:0>	Set decimation factor for filter 4
														Х			ODD_TAP4	Use odd tap filter 4
31																х	USE_FILTER4	1: Enables filter for channel 4; 0: Disables
			х	х	х	Х											HPF_CORNER _CH4	HPF corner in values k from 2 to 10
		х															HPF_EN_CH4	1: HPF filter enabled for the channel; 0: Disabled
							х	Х	Х								FILTER5_COEFF_SET<2:0>	Select stored coefficient set for filter 5
										Х	Х	х					FILTER5_RATE<2:0>	Set decimation factor for filter 5
														Х			ODD_TAP5	Use odd tap filter 5
32																х	USE_FILTER5	1: Enables filter for channel 5; 0: Disables
			х	х	х	Х											HPF_CORNER _CH5	HPF corner in values k from 2 to 10
		х															HPF_EN_CH5	1: HPF filter enabled for the channel; 0: Disabled
							Х	Х	Х								FILTER_TYPE6<2:0>	Select stored coefficient set for filter 6
										Х							DECBY8_6	Enables decimate by 8 filter 6
											Х	Х					FILTER_MODE6<1:0>	Set decimation factor for filter 6
33														Х			ODD_TAP6	Use odd tap filter 6
																х	USE_FILTER6	Enables filter for channel 6
			х	Х	Х	Х											HPF_CORNER _CH6	HPF corner in values k from 2 to 10
		Х															HPF_EN_CH6	HPF filter enable for the channel
							Х	Х	Х								FILTER_TYPE7<2:0>	Select stored coefficient set for filter 7
										Х							DECBY8_7	Enables decimate by 8 filter 7
											Х	Х					FILTER_MODE7<1:0>	Set decimation factor for filter 7
34														Х			ODD_TAP7	Use odd tap filter 7
																Х	USE_FILTER7	Enables filter for channel 7
			Х	Х	Х	Х											HPF_CORNER _CH7	HPF corner in values k from 2 to 10
		Х															HPF_EN_CH7	HPF filter enable for the channel
							Х	Х	Х								FILTER_TYPE8<2:0>	Select stored coefficient set for filter 8
										Х							DECBY8_8	Enables decimate by 8 filter 8
											Х	х					FILTER_MODE8<1:0>	Set decimation factor for filter 8
65														Х			ODD_TAP8	Use odd tap filter 8
35																х	USE_FILTER8	1: Enables filter for channel 8; 0: Disables
			х	Х	х	х											HPF_CORNER_CH8	HPF corner in values k from 2 to 10
		х															HPF_EN_CH8	1: HPF filter enable for the channel; 0: Disables
38															х	х	DATA_RATE<1:0>	Select output frame clock rate. Please see OUTPUT DATA RATE CONTROL.



ADDR. (HEX)	D15	D14	D13	D12	D11	D10	D9	D8	D7	D6	D5	D4	D3	D2	D1	D0	NAME	DESCRIPTION
42	x												x				EXT_REF_VCM	Drive external reference mode through: D15 = D3 = 1: the VCM pin; D15 = D3 = 0: REFT and REFB pins. Note: 0xF0[15] should be set as '1' to enable the external reference mode.
										Х	х						PHASE_DDR<1:0>	Controls phase of LCLK output relative to data
45															0	х	PAT_DESKEW	1: Enable deskew pattern mode; 0: Inactive
40															х	0	PAT_SYNC	1: Enable sync pattern mode; 0: Inactive
	1															х	EN_2WIRE	1: 2-wire LVDS output; 0: 1-wire LVDS output
	1													х			BTC_MODE	1: 2s complement; (ADC data output format) 0: Binary Offset (ADC data output format)
	1												х				MSB_FIRST	1: MSB First; 0: LSB First
46	1											х					EN_SDR	1:SDR Bit Clock; 0: DDR Bit Clock
	1				x	x	x	x									EN_BIT_SER	Output serialization mode. 0001: 10 bit (EN_10BIT) 0010: 12 bit (EN_12BIT) 0100: 14 bit (EN_14BIT) 1000: 16 bit (EN_16BIT)
	1		х														FALL_SDR	1: Controls LCLK rising or falling edge comes in the middle of data window when operating in SDR output mode; 0: At the edge of data window.
50	1												Х	Х	Х	Х	MAP_Ch1234_to_OUT1A	OUT1A Pin pair to channel data mapping selection
	1								Х	Х	Х	Х					MAP_Ch1234_to_OUT1B	OUT1B Pin pair to channel data mapping selection
	1				Х	Х	Х	Х									MAP_Ch1234_to_OUT2A	OUT2A Pin pair to channel data mapping selection
51	1												Х	Х	Х	Х	MAP_Ch1234_to_OUT2B	OUT2B Pin pair to channel data mapping selection
	1								Х	Х	х	Х					MAP_Ch1234_to_OUT3A	OUT3A Pin pair to channel data mapping selection
	1				Х	Х	Х	Х									MAP_Ch1234_to_OUT3B	OUT3B Pin pair to channel data mapping selection
50	1												Х	Х	Х	Х	MAP_Ch1234_to_OUT4A	OUT4A Pin pair to channel data mapping selection
52	1								Х	Х	Х	Х					MAP_Ch1234_to_OUT4B	OUT4B Pin pair to channel data mapping selection
	1												Х	Х	Х	Х	MAP_Ch5678_to_OUT5B	OUT5B Pin pair to channel data mapping selection
53	1								Х	Х	Х	Х					MAP_Ch5678_to_OUT5A	OUT5A Pin pair to channel data mapping selection
	1				Х	Х	Х	Х									MAP_Ch5678_to_OUT6B	OUT6B Pin pair to channel data mapping selection
	1												Х	Х	Х	Х	MAP_Ch5678_to_OUT6A	OUT6A Pin pair to channel data mapping selection
54	1								х	Х	х	Х					MAP_Ch5678_to_OUT7B	OUT7B Pin pair to channel data mapping selection
	1				х	х	Х	Х									MAP_Ch5678_to_OUT7A	OUT7A Pin pair to channel data mapping selection
	1												Х	х	х	Х	MAP_Ch5678_to_OUT8B	OUT8B Pin pair to channel data mapping selection
55	1								Х	Х	х	Х					MAP_Ch5678_to_OUT8A	OUT8A Pin pair to channel data mapping selection
F0	x																EN_EXT_REF	1: Enable external reference mode, the voltage reference can be applied on either REFP and REFB pins or VCM pin. 0: Default: internal reference mode.



### **DESCRIPTION OF SERIAL REGISTERS**

#### **POWER-DOWN MODES**

ADDR. (HEX)	D15	D14	D13	D12	D11	D10	D9	D8	D7	D6	D5	D4	D3	D2	D1	D0	NAME
0F									Х	Х	Х	Х	Х	Х	Х	Х	PDN_CH<8:1>
								Х									PDN_PARTIAL
							Х										PDN_COMPLETE
						Х											PDN_PIN_CFG

Each of the eight channels can be individually powered down. PDN\_CH<N> controls the power-down mode for ADC channel <N>. In addition to channel-specific power-down, the ADS5294 also has two global power-down modes:

- 1. The partial power-down mode partially powers down the chip. Recovery time from the partial power-down mode is about 10 µs provided that the clock has been running for at least 50 µs before exiting this mode.
- 2. The complete power-down mode completely powers down the chip This mode involves a much longer recovery time 100 µs.

In addition to programming the chip in either of these two power-down modes (through either the PDN\_PARTIAL or PDN\_COMPLETE bits), the PD pin itself can be configured as either a partial power-down pin or a complete power-down pin control. For example, if PDN\_PIN\_CFG=0 (default), when the PD pin is high, the device enters complete power-down mode. However, if PDN\_PIN\_CFG=1, when the PD pin is high, the device enters partial power-down mode.

#### LOW FREQUENCY NOISE SUPPRESSION MODE

ADDR. (HEX)	D15	D14	D13	D12	D11	D10	D9	D8	D7	D6	D5	D4	D3	D2	D1	D0	NAME
14									Х	Х	Х	Х	Х	Х	Х	Х	LFNS_CH<8:1>

The low-frequency noise suppression mode is useful in applications where good noise performance is desired in the frequency band of 0 to 1 MHz (around DC). Setting this mode shifts the low-frequency noise of the ADS5294 to approximately Fs / 2, thereby, moving the noise floor around DC to a much lower value. LFNS\_CH<8:1> enables this mode individually for each channel. See Figure 38 and Figure 39.

#### ANALOG INPUT INVERT

ADDR. (HEX)	D15	D14	D13	D12	D11	D10	D9	D8	D7	D6	D5	D4	D3	D2	D1	D0	NAME
24									Х	Х	Х	Х	Х	Х	Х	Х	INVERT_CH<8:1>



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Generally,  $IN_P$  pin represents the positive analog input pin, and INN represents the complementary negative input. Setting the bits marked INVERT\_CH<8:1> (individual control for each channel) causes the inputs to be swapped.  $IN_N$  now represents the positive input, and  $IN_P$  the negative input.

# LVDS TEST PATTERNS

ADDR. (HEX)	D15	D14	D13	D12	D11	D10	D9	D8	D7	D6	D5	D4	D3	D2	D1	D0	NAME
23	Х	Х	Х	Х	Х	Х	Х	Х	Х	Х	Х	Х	Х	Х	Х	Х	PRBS_SEED<15:0>
24	Х	Х	Х	Х	Х	Х	Х										PRBS_SEED<22:16>
25										Х	0	0					EN_RAMP
										0	Х	0					DUALCUSTOM_PAT
										0	0	Х					SINGLE_CUSTOM_PAT
															Х	Х	BITS_CUSTOM1<13:12>
													Х	Х			BITS_CUSTOM2<13:12>
								Х									TP_SOFT_SYNC
				Х													PRBS_TP_EN
			Х														PRBS_MODE_2
		Х															PRBS_SEED_FROM_REG
	Х																TP_HARD_SYNC
26	Х	Х	Х	Х	Х	Х	Х	Х	Х	Х	Х	Х					BITS_CUSTOM1<11:0>
27	Х	Х	Х	Х	Х	Х	Х	Х	Х	Х	Х	Х					BITS_CUSTOM2<11:0>
45															0	Х	PAT_DESKEW
															Х	0	PAT_SYNC

The ADS5294 can output a variety of test patterns on the LVDS outputs. These test patterns replace the normal ADC data output. All these patterns can be synchronized across devices by the sync function either through the hardware SYNC pin or the software sync bit TP\_SOFT\_SYNC bit in register 0x25. When set, the TP\_HARD\_SYNC bit enables the test patterns to be synchronized by the hardware SYNC Pin. When the software sync bit TP\_SOFT\_SYNC is set, special timing is needed.

- Setting EN\_RAMP to '1' causes all the channels to output a repeating full-scale ramp pattern. The ramp increments from zero code to full-scale code in steps of 1 LSB every clock cycle. After hitting the full-scale code, it returns back to zero code and ramps again.
- The device can also be programmed to output a constant code by setting SINGLE\_CUSTOM\_PAT to '1', and programming the desired code in BITS\_CUSTOM1<13:0>. In this mode, BITS\_CUSTOM1<13:0> take the place of the 14-bit ADC data at the output, and are controlled by LSB-first and MSB-first modes the same way as normal ADC data are controlled.
- The device can also toggle between two consecutive codes, by programming DUAL\_CUSTOM\_PAT to '1'. The two codes are represented by the contents of BITS\_CUSTOM1<13:0> and BITS\_CUSTOM2<13:0>.
- In addition to custom patterns, the device may also be made to output two preset patterns:
  - Deskew patten Set using PAT\_DESKEW, this mode replaces the 14-bit ADC output D<13:0> with the 010101010101010101 word.
  - Sync pattern Set using PAT\_SYNC, the normal ADC word is replaced by a fixed 11111110000000 word.
  - PRBS patterns The device can give 9-bit or 23-bit LFSR Pseudo random pattern on the channel outputs that are controlled by the register 0x25. To enable the PRBS pattern PRBS\_TP\_EN bit in the register 0x25 needs to be set. The default is the 23-bit LFSR. To select the 9-bit LFSR, set the PRBS\_MODE\_2 bit. The seed value for the PRBS patterns can be chosen by enabling the PRBS\_SEED\_FROM\_REG bit to 1 and the value written to the PRBS\_SEED registers in 0x24 and 0x23.

Note that only one of these patterns should be active at any given instant.



#### **BIT-BYTE-WORD WISE OUTPUT**

ADDR. (HEX)	D15	D14	D13	D12	D11	D10	D9	D8	D7	D6	D5	D4	D3	D2	D1	D0	NAME
	х																EN_BITORDER
28	0							х									BIT_WISE
20	1								Х	Х	Х	Х	Х	х	Х	Х	EN_WORDWISE_B Y_CH<7:>

Register 0x28 selects the LVDS ADC output as bit-wise, byte-wise, or word-wise in the 2-wire mode. Figure 47 and Figure 48 illustrate the details.

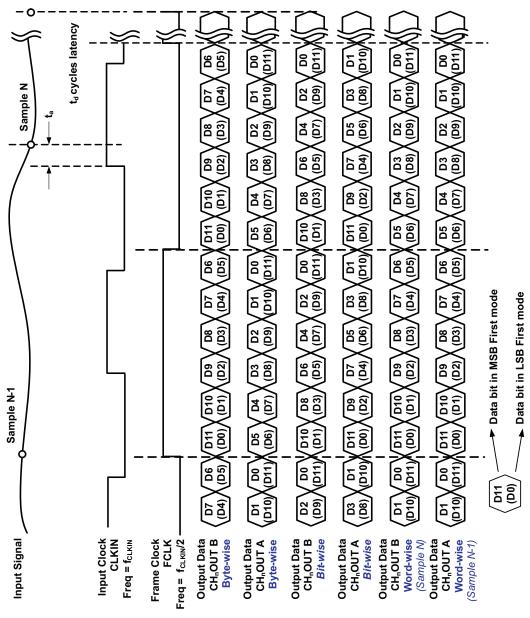


Figure 47. 12-Bit Word Wise



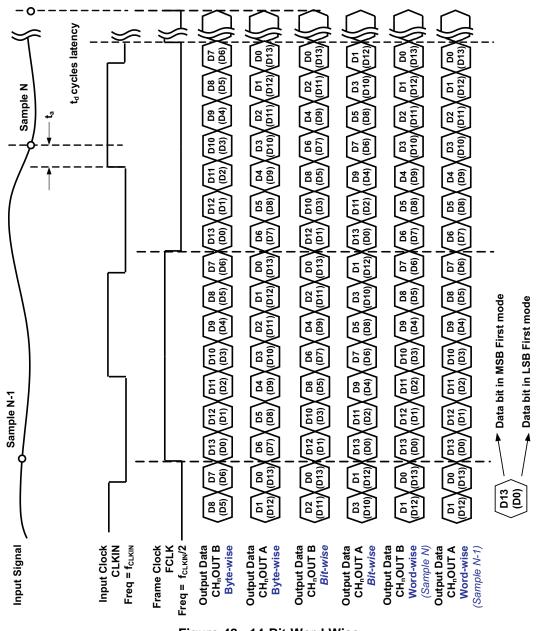


Figure 48. 14-Bit Word Wise

## DIGITAL PROCESSING BLOCKS

The ADS5294 integrates a set of commonly-used digital functions to ease system design. These functions are shown in the digital block diagram of Figure 49 and described in the following sections.



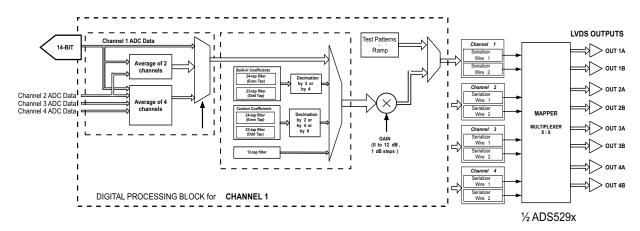


Figure 49. Digital Processing Block Diagram

ADDR. (HEX)	D15	D14	D13	D12	D11	D10	D9	D8	D7	D6	D5	D4	D3	D2	D1	D0	NAME
2A													Х	Х	Х	Х	GAIN_CH1<3:0>
									Х	Х	Х	Х					GAIN_CH2<3:0>
					Х	Х	Х	Х									GAIN_CH3<3:0>
	Х	Х	Х	Х													GAIN_CH4<3:0>
2B	Х	Х	Х	Х													GAIN_CH5<3:0>
					Х	Х	Х	Х									GAIN_CH6<3:0>
									Х	Х	Х	Х					GAIN_CH7<3:0>
													Х	Х	Х	Х	GAIN_CH8<3:0>

#### **PROGRAMMABLE DIGITAL GAIN**

In applications where the full-scale swing of the analog input signal is much less than the 2  $V_{PP}$  range supported by the ADS5294, a programmable gain is set to achieve the full-scale output code even with a lower analog input swing. The programmable gain for each channel is set individually using a set of four bits, indicated as GAIN\_CHN<3:0> for Channel N. The gain setting is coded in binary from 0 to 12 dB as shown in Table 7.

			-	CHANNEL N CAIN SETTING
GAIN_CHN<3>	GAIN_CHN<2>	GAIN_CHN<1>	GAIN_CHN<0>	CHANNEL N GAIN SETTING
0	0	0	0	0 dB
0	0	0	1	1 dB
0	0	1	0	2 dB
0	0	1	1	3 dB
0	1	0	0	4 dB
0	1	0	1	5 dB
0	1	1	0	6 dB
0	1	1	1	7 dB
1	0	0	0	8 dB
1	0	0	1	9 dB
1	0	1	0	10 dB
1	0	1	1	11 dB
1	1	0	0	12 dB
1	1	0	1	Do not use
1	1	1	0	Do not use
1	1	1	1	Do not use

#### Table 7. Gain Setting for Channel N

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#### CHANNEL AVERAGING

ADDR. (HEX)	D15	D14	D13	D12	D11	D10	D9	D8	D7	D6	D5	D4	D3	D2	D1	D0	NAME
29																Х	EN_CHANNEL_AVG
2C						Х	Х										AVG_CTRL4<1:0>
									Х	Х							AVG_CTRL3<1:0>
												Х	Х				AVG_CTRL2<1:0>
															Х	Х	AVG_CTRL1<1:0>
2D						Х	Х										AVG_CTRL8<1:0>
									Х	Х							AVG_CTRL7<1:0>
												Х	Х				AVG_CTRL6<1:0>
															Х	Х	AVG_CTRL5<1:0>

In the default mode of operation, the LVDS outputs <8..1> contain the data of the ADC Channels <8..1>. By setting the EN\_CHANNEL\_AVG bit to '1', the outputs from multiple channels can be averaged. The resulting outputs from the Channel averaging block (which is bypassed in the default mode) are referred to as Bins. The contents of the Bins <8..1> come out on the LVDS outputs <8..1>. The contents of each of the eight Bins are determined by the register bits marked AVG\_CTRL*n*<1:0> where *n* stands for the Bin number. The different settings are shown in the following table:

AVG_CTRL1<1>	AVG_CTRL1<0>	Contents of Bin 1				
0	0	Zero				
0	1	ADC Channel 1				
1	0	Average of ADC Channel 1, 2				
1	1	Average of ADC Channel 1, 2, 3, 4				
AVG_CTRL2<1>	AVG_CTRL2<0>	Contents of Bin 2				
0	0	Zero				
0	1	ADC Channel 2				
1	0	ADC Channel 3				
1	1	Average of ADC Channel 3, 4				
AVG_CTRL3<1>	AVG_CTRL3<0>	Contents of Bin 3				
0	0	Zero				
0	1	ADC Channel 3				
1	0	ADC Channel 2				
1	1	Average of ADC Channel 1, 2				
AVG_CTRL4<1>	AVG_CTRL4<0>	Contents of Bin 4				
0	0	Zero				
0	1	ADC Channel 4				
1	0	Average of ADC Channel 3, 4				
1	1	Average of ADC Channel 1, 2, 3, 4				
AVG_CTRL5<1>	AVG_CTRL5<0>	Contents of Bin 5				
0	0	Zero				
0	1	ADC Channel 5				
1	0	Average of ADC Channel 5, 6				
1	1	Average of ADC Channel 5, 6, 7, 8				
AVG_CTRL6<1>	AVG_CTRL6<0>	Contents of Bin 6				
0	0	Zero				
0	1	ADC Channel 6				
1	0	ADC Channel 7				
1	1	Average of ADC Channel 7, 8				
AVG_CTRL7<1>	AVG_CTRL7<0>	Contents of Bin 7				
0	0	Zero				

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AVG_CTRL1<1>	AVG_CTRL1<0>	Contents of Bin 1				
0	1	ADC Channel 7				
1	0	ADC Channel 6				
1	1	Average of ADC Channel 6, 5				
AVG_CTRL8<1>	AVG_CTRL8<0>	Contents of Bin 8				
0	0	Zero				
0	1	ADC Channel 8				
1	0	Average of ADC Channel 7, 8				
1	1	Average of ADC Channel 5, 6, 7, 8				

When the contents of a particular Bin is set to zero, then the LVDS buffer corresponding to that Bin gets automatically powered down.

#### **DECIMATION FILTER**

ADDR. (HEX)	D15	D14	D13	D12	D11	D10	D9	D8	D7	D6	D5	D4	D3	D2	D1	D0	NAME
29															Х		GLOBAL_EN_FILTER
2E							Х	Х	Х								FILTER1_COEFF_SET<2:0>
										Х	Х	Х					FILTER1_RATE<2:0>
														Х			ODD_TAP1
																Х	USE_FILTER1
2F							Х	Х	Х								FILTER2_COEFF_SET<2:0>
										Х	Х	Х					FILTER2_RATE<2:0>
														Х			ODD_TAP2
																Х	USE_FILTER2
30							Х	Х	Х								FILTER3_COEFF_SET<2:0>
										Х	Х	Х					FILTER3_RATE<2:0>
														Х			ODD_TAP3
																Х	USE_FILTER3
31							Х	Х	Х								FILTER4_COEFF_SET<2:0>
										Х	Х	Х					FILTER4_RATE<2:0>
														Х			ODD_TAP4
																Х	USE_FILTER4
32							Х	Х	Х								FILTER5_COEFF_SET<2:0>
										Х	Х	Х					FILTER5_RATE<2:0>
														Х			ODD_TAP5
																Х	USE_FILTER5
33							Х	Х	Х								FILTER6_COEFF_SET<2:0>
										Х	Х	Х					FILTER6_RATE<2:0>
														Х			ODD_TAP6
																Х	USE_FILTER6
34							Х	Х	Х								FILTER7_COEFF_SET<2:0>
										Х	Х	Х					FILTER7_RATE<2:0>
														Х			ODD_TAP7
																Х	USE_FILTER7
35							Х	Х	Х								FILTER8_COEFF_SET<2:0>
										Х	Х	Х					FILTER8_RATE<2:0>
														Х			ODD_TAP8
																Х	USE_FILTER8

The decimation filter is implemented as 24-tap FIR with symmetrical coefficients (each coefficient is 12-bit signed). The filter equation is:

$$y(n) = \left(\frac{1}{2^{11}}\right) \times \left[(h_0 \times x(n) + h_1 \times x(n-1) + h_2 \times x(n-2) + \dots + h_{11} \times x(n-11) + h_{11} \times x(n-12) \dots + h_1 \times x(n-22) + h_0 \times x(n-23)\right]$$

(1)



By setting the register bit <ODD\_TAPn> = 1, a 23-tap FIR is implemented:

$$y(n) = \left(\frac{1}{2^{11}}\right) \times \left[(h_0 \times x(n) + h_1 \times x(n-1) + h_2 \times x(n-2) + ... + h_{10} \times x(n-10) + h_{11} \times x(n-11) + h_{10} \times x(n-12) ... + h_1 \times x(n-21) + h_0 \times x(n-22)\right]$$
(2)

In Equation 1 and Equation 2, h0,  $h1 \dots h_{11}$  are 12-bit signed representation of the coefficients, x(n) is the input data sequence to the filter and y(n) is the filter output sequence.

A decimation filter can be introduced at the output of each channel. To enable this feature, the GLOBAL\_EN\_FILTER should be set to '1'. Setting this bit to '1' increases the overall latency of each channel to 20 clock cycles irrespective of whether the filter for that particular channel has been chosen or not (using the USE\_FILTER bit). The bits marked FILTER*n*\_COEFF\_SET<2:0>, FILTER*n*\_RATE<2:0>, ODD\_TAP*n* and USE\_FILTER*n* represent the controls for the filter for Channel *n*. Note that these bits are functional only when the GLOBAL\_EN\_FILTER gets set to '1' and USE\_FILTERn bit is set to '1'. For illustration, the controls for channel 1 are listed in Table 8:

The USE\_FILTER1 bit determines whether the filter for Channel 1 is used or not. When this bit is set to '1', the filter for channel 1 is enabled. When this bit is set to '0', the filter for channel 1 is disabled but the channel data passes through a dummy delay so that the overall latency of channel 1 is 20 clock cycles. With the USE\_FILTER1 bit set to '1', the characteristics of the filter can be set by using the other sets of bits.

The ADS5294 has six sets of filter coefficients stored in memory. Each of these sets define a unique pass band in the frequency domain and contain 12 coefficients (each coefficient is 12-bit long). These 12 coefficients are used to implement either a symmetric 24-tap (even-tap) filter, or a symmetric 23-tap (odd-tap) filter. Setting the register bit ODD\_TAP1 to '1' enables the odd-tap configuration (the default is even tap with this bit set to '0') for Channel 1. The bits FILTER1\_COEFF\_SET<2:0> are used to choose the required set of coefficients for Channel 1.

The passbands corresponding to of each of these filter coefficient sets is shown in Figure 50



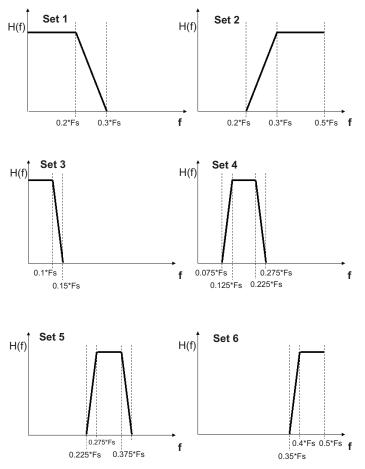


Figure 50. Filter Types

Coefficient Sets 1 and 2 are the most appropriate when decimation by a factor of 2 is required, whereas Coefficient Sets 3, 4, 5, and 6 are appropriate when decimation by a factor of 4 is desired. The computation rate of the filter output is set independently using the bits FILTERn\_RATE<2:0>. The settings are shown in Table 8.

DECIMATION	TYPE OF FILTER	DATA_RAT E>	FILTERn_RA TE	FILTERn_CO EFF_SET	ODD_TAP	USE_FILTE R_CHn	EN_CUSTOM_ FILT
Desirents has 0	Built-in <b>low-pass odd-tap</b> filter (pass band = 0 to $f_S/4$ )	01	000	000	1	1	0
Decimate by 2	Built-in high-pass odd-tap filter (pass band = 0 to $f_S/4$ )	01	000	001	1	1	0
	Built-in <b>low-pass even-tap</b> filter (pass band = 0 to $f_S/8$ )	10	001	010	0	1	0
	Built-in first <b>band pass even tap</b> filter(pass band = $f_S/8$ to $f_S/4$ )	10	001	011	0	1	0
Decimate by 4	Built-in second <b>band pass even tap</b> filter(pass band = $f_S/4$ to 3 $f_S/8)$	10	001	100	0		0
	Built-in high pass odd tap filter (pass band = $3 f_S/8$ to $f_S/2$ )	10	001	101	1	1	0
Decimate by 2	Custom filter (user-programmable coefficients)	01	000	000	0 and 1	1	1
Decimate by 4	Custom filter (user-programmable coefficients)	10	001	000	0 and 1	1	1
Decimate by 8	Custom filter (user-programmable coefficients)	11	100	000	0 and 1	1	1
Bypass decimation	Custom filter (user-programmable coefficients)				0 and 1	1	1
Note: EN_CUSTOM	_FILT is the D15 of register 5A (Hex) to B9 (Hex).		•				

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**EXAS** 

The choice of the odd or even tap setting, filter coefficient set, and the filter rate uniquely determines the filter to be used. In addition to the preset filter coefficients, the coefficients for each of the eight filter channels can be programmed by the user. Each of the eight channels has 12 programmable coefficients, each 12-bit long. The 96 registers with addresses from 5A (Hex) to B9 (Hex) are used to program these eight sets of 12 programmable coefficients. Registers 5A to 65 are used to program the first filter, with the first coefficient occupying the bits D11..D0 of register 5A, the second coefficient occupying the bits D11..D0 of register 5B, and so on. Similarly registers 66 (Hex) to 71 (Hex) are used to program the second filter, and so on.

When programming the filter coefficients, the D15 bit, EN\_CUSTOM\_FILT, of each of the 12 registers corresponding to that filter should be set to '1'. If the D15 bit of these 12 registers is set to '0', then the preset coefficient (as programmed by FILTERn\_COEFF\_SET<2:0>) is used even if the bits D11..D0 get programmed. By setting or not setting the D15 bits of individual filter channels to '1', some filters can be made to operate with preset coefficient sets, and some others can be made to simultaneously operate with programmed coefficient sets.

ADDR. (HEX)	D15	D14	D13	D12	D11	D10	D9	D8	D7	D6	D5	D4	D3	D2	D1	D0	NAME
2E			Х	Х	Х	Х											HPF_corner_CH1
2E		Х															HPF_EN_CH1
2F			Х	Х	Х	Х											HPF_corner_CH2
2F		Х															HPF_EN_CH2
30			Х	Х	Х	Х											HPF_corner_CH3
30		Х															HPF_EN_CH3
31			Х	Х	Х	Х											HPF_corner_CH4
31		Х															HPF_EN_CH4
32			Х	Х	Х	Х											HPF_corner_CH5
32		Х															HPF_EN_CH5
33			Х	Х	Х	Х											HPF_corner_CH6
33		Х															HPF_EN_CH6
34			Х	Х	Х	Х											HPF_corner_CH7
34		Х															HPF_EN_CH7
35			Х	Х	Х	Х											HPF_corner_CH8
35		Х															HPF_EN_CH8

#### **HIGH-PASS FILTER**

This group of registers controls the characteristics of a digital high-pass transfer function applied to the output data, using Equation 3:

$$y(n) = \frac{2^{k}}{2^{k}+1}[x(n)-x(n-1)+y(n-1)]$$

(3)

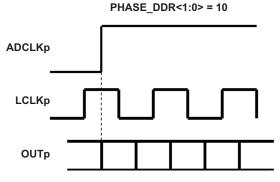
Where k is set as described by the HPF\_corner registers (one for each channel). The HPF\_EN bit in each register must be set to enable the HPF feature for each channel.

#### BIT-CLOCK PROGRAMMABILITY

ADDR. (HEX)	D15	D14	D13	D12	D11	D10	D9	D8	D7	D6	D5	D4	D3	D2	D1	D0	NAME
42										Х	Х						PHASE_DDR<1:0>
46	1											Х					EN_SDR
46	1		Х														FALL_SDR



The output interface of the ADS5294 is normally a DDR interface, with the LCLK rising edge and falling edge transitions in the middle of alternate data windows. This default phase is shown in Figure 51.





The phase of LCLK is programmed relative to the output frame clock and data using bits PHASE\_DDR<1:0>. The LCLK phase modes are shown in Figure 52.

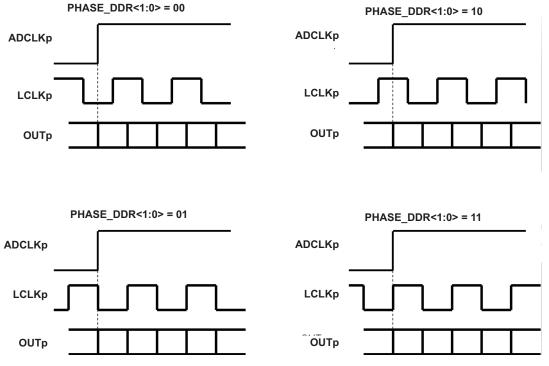


Figure 52. Phase Programmability Modes for LCLK

In addition to programming the phase of the LCLK in the DDR mode, the device also operates in SDR mode by setting bit EN\_SDR to '1'. In SDR mode, the bit clock (LCLK) is output at 14-times the input clock, or twice the rate as in DDR mode. Depending on the state of FALL\_SDR, the LCLK may be output in either of the two manners shown in Figure 53. As can be seen in Figure 53, only the LCLK rising (or falling edge) is used to capture the output data in SDR mode. The SDR mode does not work well beyond 40 MSPS because the LCLK frequency will become very high.



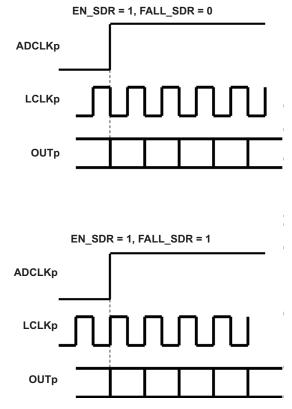


Figure 53. SDR Interface Modes

# **OUTPUT DATA RATE CONTROL**

ADD (HE)	D15	D14	D13	D12	D11	D10	D9	D8	D7	D6	D5	D4	D3	D2	D1	D0
38															DATA_RATE<1>	DATA_RATE<0>

In the default mode of operation, the data rate at the output of the ADS5294 is at the sampling rate of the ADC which is true even when the custom pattern generator is enabled. In addition, both output data rate and sampling rate can be configured to a sub-multiple of the input clock rate.

With the DATA\_RATE<1:0> control, the output data rate is programmed to be a sub-multiple of the ADC sampling rate. This feature is used to lower the output data rate, for example, when the decimation filter is used. Without enabling the decimation filter, the sub-multiple ADC sampling rate feature is used.

The different settings are listed in the following table.

DATA_RATE<1>	DATA_RATE<0>	Output data rate
0	0	Same as ADC sampling rate
0	1	1 / 2 of ADC sampling rate
1	0	1 / 4 of ADC sampling rate
1	1	1 / 8 of ADC sampling rate

#### SYNCHRONIZATION PULSE

ADDR. (HEX)	D15	D14	D13	D12	D11	D10	D9	D8	D7	D6	D5	D4	D3	D2	D1	D0
25	TP_HARD_SYNC															
02			EN_SYNC													



The SYNC pin synchronizes the data output from channels within the same chip or from channels across chips when decimation filters are used with reduced output data rate.

When the decimation filters are used (for example, the decimate-by-two filter is enabled), then, effectively, the device outputs one digital code for every two analog input samples. If the SYNC function is not enabled, then the filters are not synchronized (even within a chip) which means that one channel is sending out codes corresponding to input samples N, N + 1 and so on, while another may be sending out code corresponding to N + 1, N + 2, and so on.

To achieve synchronization, the SYNC pulse must arrive at all the ADS529x chips at the same time instant (as shown in the timing diagram of Figure 54

The ADS5294 generates an internal synchronization signal which is used to reset the internal clock dividers used by the decimation filter.

Using the SYNC signal in this way ensures that all channels will output digital codes corresponding to the same set of input samples.

#### SYNC Timings:

Synchronizing the filters using the SYNC pin is enabled by default. No register bits are required to be written. Even EN\_SYNC bit is not required. It is important for register bit TP\_HARD\_SYNC to be 0 for this mode to work. As shown by Figure 54, the SYNC rising edge can be positioned anywhere within the window. The width of the SYNC must be at least one clock cycle.

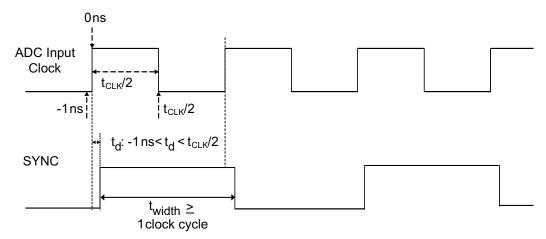


Figure 54. Synchronization Pulse Timing

Note that the SYNC DOES NOT synchronize the sampling instants of the ADC across chips. All channels within a single chip sample their analog inputs simultaneously. The input clock needs to be routed to both chips with identical length to ensure that channels across two chips will sample their analog inputs simultaneously. Taking this step ensures that the input clocks arrive at both of the chips at the same time. This should be handled in the board design and routing. The SYNC pin cannot be used to synchronize the sampling instants.

In addition to the above, the SYNC also synchronizes the RAMP test patterns across channels. In order to synchronize the test patterns, TP\_HARD\_SYNC must be set as '1'. Setting TP\_HARD\_SYNC = 1 actually disables the sync of the filters.

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# **External Reference Mode of Operation**

The ADS5294 supports an external reference mode of operation in one of two ways:

a. By forcing the reference voltages on the REFT and REFB pins.

b. By applying the reference voltage on VCM pin.

This mode can be used to operate multiple ADS5294 chips with the same (externally applied) reference voltage.

Using the REF pins:

For normal operation, the device requires two reference voltages: REFT and REFB. By default, the device generates these two voltages internally. To enable the external reference mode, set the register bits as shown in Table 9 which powers down the internal reference amplifier and the two reference voltages are forced directly on the REFT and REFB pins as VREFT =  $1.45 \text{ V} \pm 50 \text{ mV}$  and VREFB =  $0.45 \text{ V} \pm 50 \text{ mV}$ .

Note that the relation between the ADC full-scale input voltage and the applied reference voltages is

Full-scale input voltage =  $2 \times (VREFT - VREFB)$ 

Using the VCM pin:

In this mode, an external reference voltage VREFIN can be applied to the VCM pin such that

Full-scale input voltage = 2 × VREFIN x (2 / 3)

To enable this mode, set the register bits as shown in Table 9 which changes the function of the VCM pin to an external reference input pin. The voltage applied on VCM must be  $1.5 \text{ V} \pm 50 \text{ mV}$ .

#### Table 9. External reference function

Function	EN_HIGH_ADDRS( 0x1[4])	EN_EXT_REF (0xF0[15])	EXT_REF_VCM (0x42[15,3])
External reference using REFT and REFB pins	1	1	00
External reference using VCM pin	1	1	11

# DATA OUTPUT FORMAT MODES

ADDR. (HEX)	D15	D14	D13	D12	D11	D10	D9	D8	D7	D6	D5	D4	D3	D2	D1	D0	NAME
46	1													Х			BTC_MODE
46	1												Х				MSB_FIRST

By default, the ADC output is in straight-offset binary mode. Programming the BTC\_MODE bit to '1' inverts the MSB, and the output becomes Binary 2s-complement mode. Also by default, the first bit of the frame (following the rising edge of CLKP) is the LSB of the ADC output. Programming the MSB\_FIRST mode inverts the bit order in the word, and the MSB is output as the first bit following CLKP rising edge.

Product Folder Links : ADS5294

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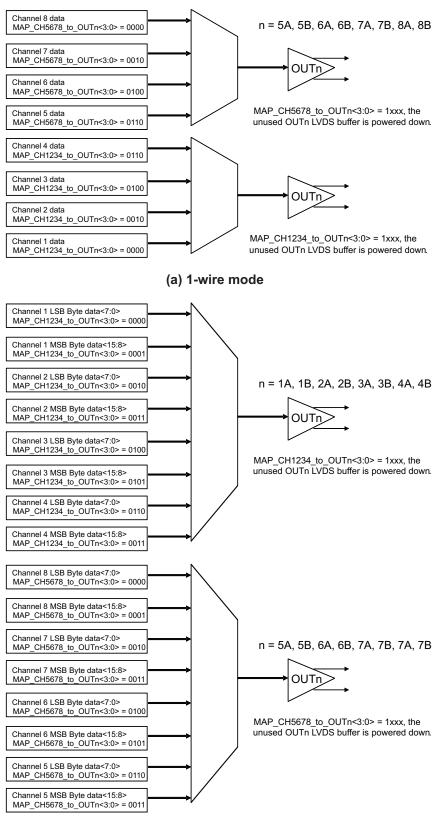
## PROGRAMMABLE MAPPING BETWEEN INPUT CHANNELS AND OUTPUT PINS

ADDR. (HEX)	D15	D14	D13	D12	D11	D10	D9	D8	D7	D6	D5	D4	D3	D2	D1	D0	NAME
50	1												Х	Х	Х	Х	MAP_CH1234_TO_OUT1A
	1								Х	Х	Х	Х					MAP_CH1234_TO_OUT1B
	1				Х	Х	Х	Х									MAP_CH1234_TO_OUT2A
51	1												Х	Х	Х	Х	MAP_CH1234_TO_OUT2B
	1								Х	Х	Х	Х					MAP_CH1234_TO_OUT3A
	1				Х	Х	Х	Х									MAP_CH1234_TO_OUT3B
52	1								Х					Х	Х	Х	MAP_CH1234_TO_OUT4A
	1								Х	Х	Х	Х					MAP_CH1234_TO_OUT4B
53	1												Х	Х	Х	Х	MAP_CH5678_TO_OUT5B
	1								Х	Х	Х	Х					MAP_CH5678_TO_OUT5A
	1				Х	Х	Х	Х									MAP_CH5678_TO_OUT6B
54	1												Х	Х	Х	Х	MAP_CH5678_TO_OUT6A
	1								Х	Х	Х	Х					MAP_CH5678_TO_OUT7B
	1				Х	Х	Х	Х									MAP_CH5678_TO_OUT7A
55	1												Х	Х	Х	Х	MAP_CH5678_TO_OUT8B
	1								Х	Х	Х	Х					MAP_CH5678_TO_OUT8A

The ADS5294 has 16 pairs of LVDS channel outputs. The mapping of ADC channels to LVDS output channels is programmable to allow for flexibility in board layout. The 16 LVDS channel outputs are split into two groups of eight LVDS pairs. Within each group four ADC input channels are multiplexed into the eight LVDS pairs depending on the modes of operation whether it is in 1-wire mode or 2-wire mode.

Input channels 1 to 4 map to any of the LVDS outputs OUT1A or OUT1B to OUT4A or OUT4B (using the MAP\_CH1234\_TO\_OUTnA or OUTnB). Similarly, input channels 5 to 8 can be mapped to any of the LVDS outputs OUT5A or OUT5B to OUT8A or OUT8B (using the MAP\_CH5678\_TO\_OUTnA or OUTnB). The block diagram of the mapping is listed in Figure 55.





(b) 2-wire mode

#### Figure 55. Input and Output Channel Mapping



# Registers 0x50 to 0x55 control the multiplexing options as shown in the following tables

MAP_CH1234_to_OUTn<3:0>	Mapping	Used in 1-wire mode?	Used in 2-wire mode?	
0000	ADC input channel IN1 to OUTn	Y	Y, for LSB byte	
0001	ADC input channel IN1 to OUTn (2- wire only)	Ν	Y, for MSB byte	
0010	ADC input channel IN2 to OUTn	Y	Y, for LSB byte	
0011	ADC input channel IN2 to OUTn (2- wire only)	Ν	Y, for MSB byte	
0100	ADC input channel IN3 to OUTn	Y	Y, for LSB byte	
0101	ADC input channel IN3 to OUTn (2- wire only)	Ν	Y, for MSB byte	
0110	ADC input channel IN4 to OUTn	Y	Y, for LSB byte	
0111	ADC input channel IN4 to OUTn (2- wire only)	Ν	Y, for MSB byte	
1xxx	LVDS output buffer OUTn is powered down			

MAP_CH5678_to_OUTn<3:0>	Mapping	Used in 1-wire mode?	Used in 2-wire mode?
0000	ADC input channel IN8 to OUTn	Y	Y, for LSB byte
0001	ADC input channel IN8 to OUTn (2- wire only)	Ν	Y, for MSB byte
0010	ADC input channel IN7 to OUTn	Y	Y, for LSB byte
0011	ADC input channel IN7 to OUTn (2- wire only)	Ν	Y, for MSB byte
0100	ADC input channel IN6 to OUTn	Y	Y, for LSB byte
0101	ADC input channel IN6 to OUTn (2- wire only)	Ν	Y, for MSB byte
0110	ADC input channel IN5 to OUTn	Y	Y, for LSB byte
0111	ADC input channel IN5 to OUTn (2- wire only)	Ν	Y, for MSB byte
1ххх	LVDS output buffer OUTn is powered down		

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The default mapping for 1-wire and 2-wire modes is shown in Table 10 and Table 11.

rabio roi mapping	
Analog Input channel	LVDS Output
Channel IN1	OUT1A
Channel IN2	OUT2A
Channel IN3	OUT3A
Channel IN4	OUT4A
Channel IN5	OUT5A
Channel IN6	OUT6A
Channel IN7	OUT7A
Channel IN8	OUT8A
Note: In the single wire mode with default register settin	ngs, ADC data is available only on OUTnA.

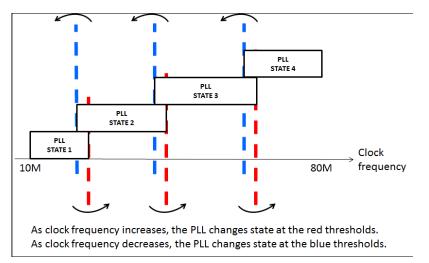
Table 10. N	Mapping f	for 1-wire	Mode
-------------	-----------	------------	------

	Table 11. Mapping for 2-wire mode								
Analog Input channel	LVDS Output								
Channel IN1	OUT1A, OUT1B								
Channel IN2	OUT2A, OUT2B								
Channel IN3	OUT3A, OUT3B								
Channel IN4	OUT4A, OUT4B								
Channel IN5	OUT5A, OUT5B								
Channel IN6	OUT6A, OUT6B								
Channel IN7	OUT7A, OUT7B								
Channel IN8	OUT8A, OUT8B								
Note: In the 2-wire mode, the ADC data is available o	n both OUTnA and OUTnB.								

#### Table 11. Mapping for 2-wire Mode

#### **PLL Operation Versus LVDS Timing**

The ADS5294 uses a PLL that automatically changes configuration to one of four states depending on the sampling clock frequency. The clock frequency detection is automatic and each time the sampling frequency crosses a threshold, the PLL changes configuration to a new state. The PLL remains in the new state for a range of clock frequencies. To prevent unwanted toggling of PLL state around a threshold, the circuit has an built-in hysteresis. The ADS5294 has three thresholds over the sampling clock frequency range from 10 MHz to 80 MHz and can be in one of four states as shown by Figure 56.



#### Figure 56. PLL States Versus ADC Fs



Each threshold shifts by a small amount across temperature. On power-up, depending on the clock frequency, the PLL settles in one of four states. Later, as the system warms up, the PLL changes state once due to the shift in the threshold across temperature.

#### Effect on Output Timings

The PLL state change has an effect on the output LVDS timings. In some settings, the setup time decreases by 100 ps typically with a corresponding increase in the hold time.

In applications where a timing calibration occurs at the system level once after power-up, this subsequent change of the PLL state is undesirable. The ADS5294 has register options to disable the automatic switch of the PLL state based on frequency detected. To prevent this variation in output timing, disable the PLL from switching states.

In addition to disabling the auto-switching, setting the PLL to the correct state is also required, depending on the sample clock frequency used in the system. The following sequence of register writes must be followed exactly:

- Step 1: Enable test-mode access by writing register data = 0x0010 in address 0x01 (for example: enable the access to registers with address higher than 0xF0).
- Step 2: Configure the PLL to the correct state depending on the clock frequency of operation and the decimation factor, as per the following tables.

#### NOTE

For certain sampling frequencies, there are two PLL states possible, both of which are stable. In such cases, the higher PLL state results in a better setup time compared to a lower PLL state. For example, at 80 MSPS, with decimation by 2 enabled, the PLL may be in states 3 or 4. However, the setup time value specified in Table 3 (0.43 ns minimum) is in PLL state 4. In state 3, the setup time is reduced further by 100 ps typically, with a corresponding increase in the hold time.

ADC Fs (MSPS)	Function	Register Address	Register Data
Fs ≤ 12	Disable PLL auto state switch and put PLL in state 1	0xD1	0x0040
9 ≤ Fs ≤ 24	Disable PLL auto state switch and put PLL in state 2	0xD1	0x00C0
18 ≤ Fs ≤ 42	Disable PLL auto state switch and put PLL in state 3	0xD1	0x0140
Fs ≥ 28	Disable PLL auto state switch and put PLL in state 4	0xD1	0x0240

 Table 12. PLL Configuration When Decimation is Disabled

#### Table 13. PLL Configuration When Decimation by 2 is Used

ADC Fs	Function	Register Address	Register Data
Fs ≤ 24	Disable PLL auto state switch and put PLL in state 1	0xD1	0x0040
18 ≤ Fs ≤ 48	Disable PLL auto state switch and put PLL in state 2	0xD1	0x00C0
36 ≤ Fs ≤ 80	Disable PLL auto state switch and put PLL in state 3	0xD1	0x0140
Fs ≥ 56	Disable PLL auto state switch and put PLL in state 4	0xD1	0x0240

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·								
ADC Fs	Function	Register Address	Register Data					
Fs ≤ 48	Disable PLL auto state switch and put PLL in state 1	0xD1	0x0040					
36 ≤ Fs ≤ 80	Disable PLL auto state switch and put PLL in state 2	0xD1	0x00C0					
Fs ≥ 72	Disable PLL auto state switch and put PLL in state 3	0xD1	0x0140					

# Table 14. PLL Configuration When Decimation by 4 is Used

#### Table 15. PLL Configuration When Decimation by 8 is Used

ADC Fs	Function	Register Address	Register Data
Fs ≤ 80	Disable PLL auto state switch and put PLL in state 1	0xD1	0x0040
72 ≤ Fs ≤ 80	Disable PLL auto state switch and put PLL in state 2	0xD1	0x00C0





## **APPLICATION INFORMATION**

#### THEORY OF OPERATION

The ADS5294 is an octal-channel, 14-bit high-speed ADC with a sample rate of up to 80 MSPS that runs off a single 1.8-V supply. All eight channels of the ADS5294 simultaneously sample the respective analog inputs at the rising edge of the input clock. The sampled signal is sequentially converted by a series of small resolution stages, with the outputs combined in a digital correction logic block. At every clock, edge the sample propagates through the pipeline resulting in a data latency of 11 clock cycles.

The 14 data bits of each channel are serialized and sent out in either 1-wire mode (one pair of LVDS pins are used) or 2-wire mode (two pairs of LVDS pins are used), depending on the LVDS output rate. When the data is output in the 2-wire mode, it reduces the serial data rate of the outputs, especially at higher sampling rates. Low-cost FPGAs are used to capture 80 MSPS / 14-bit data. Alternately, at lower sample rates, the 14-bit data is output as a single data stream over one pair of LVDS pins (1-wire mode). The device outputs a bit clock at 7x and frame clock at 1x the sample frequency in the 14-bit mode.

This 14-bit ADC achieves approximately 76-dBFS SNR at 80 MSPS. Its output resolution can be configured as 12 bit and 10 bit, if necessary. When the output resolution of the ADS5294 is 12 bit and 10 bit, SNR of 72 dBFS and 61 dBFS (respectively) is achieved.

## ANALOG INPUT

The analog inputs consist of a switched-capacitor-based differential sample and hold architecture. This differential topology results in good AC performance even for high input frequencies at high sampling rates. The INP and INM pins are internally biased around a common-mode voltage of Vcm (0.95 V). For a full-scale differential input, each input pin (INP and INM) must swing symmetrically between Vcm + 0.5 V and Vcm – 0.5 V, resulting in a 2 V<sub>PP</sub> differential input swing. Figure 57 illustrates the equivalent circuit of the input sampling circuit.

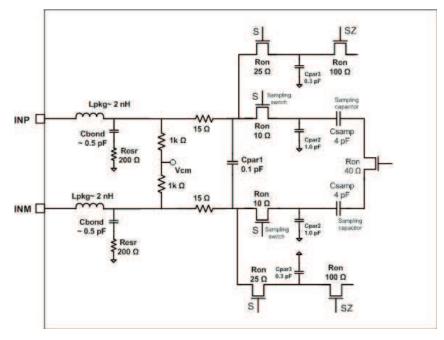


Figure 57. Analog Input Circuit Model

## DRIVE CIRCUIT

For optimum performance, the analog inputs must be driven differentially which improves the common-mode noise immunity and even order harmonic rejection. A  $5-\Omega$  to  $15-\Omega$  resistor in series with each input pin is recommended to damp-out ringing caused by package parasitic.

The drive circuit shows an R-C filter across the analog input pins. The purpose of the filter is to absorb the glitches caused by the opening and closing of the sampling capacitors.



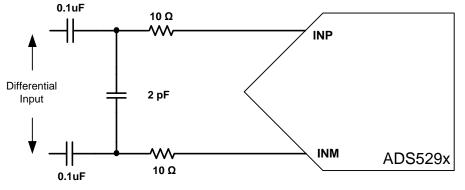


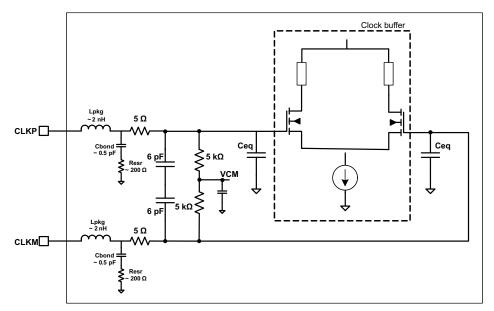
Figure 58. Analog Input Drive Circuit

#### Large and Small Signal Input Bandwidth

The small signal bandwidth of the analog input circuit is high, around 550 MHz. When using an amplifier to drive the ADS5294, consider the total noise of the amplifier up to the small signal bandwidth. The large signal bandwidth of the device depends on the amplitude of the input signal. The ADS5294 supports 2 V<sub>PP</sub> amplitude for input signal frequency up to 80 MHz. For higher frequencies (80 MHz), the amplitude of the input signal must be decreased proportionally. For example, at 160 MHz, the device supports a maximum of 1 V<sub>PP</sub> signal.

## INPUT CLOCK

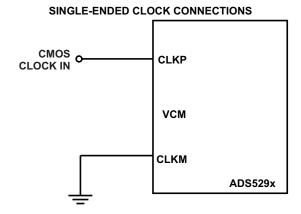
The ADS5294 is configured by default to operate with a single-ended input clock. CLKP is driven by a CMOS clock and CLKM is tied to GND. The device automatically detects a single-ended or differential clock. If CLKM is grounded, the device treats clock as a single-ended clock. Operating with a low-jitter differential clock usually gives better SNR performance, especially at input frequencies greater than 30 MHz. Typical clock termination structures are listed in Figure 59 andFigure 60. Please note that the location of LVDS Rterm depends on the LVDS clock driver. Some clock devices require the Rterm at the left side of AC coupling capacitors.



Ceq is approximately 1 to 3 pF, equivalent input capacitance of clock buffer.

#### Figure 59. Equivalent Circut of the Input Clock Circuit

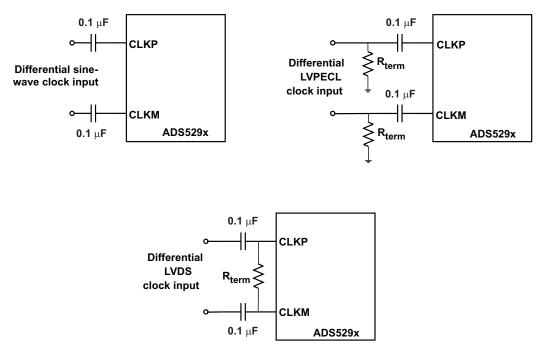






# DIFFERENTIAL CLOCK CONNECTIONS





# ADS5294

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#### **DIGITAL HIGH-PASS IIR FILTER**

DC offset is often observed at ADC input signals. For example, in ultrasound applications, the DC offset from variable-gain amplifier (VGA) varies at different gains. Such a variable offset can introduce artifacts in ultrasound images especially in Doppler modes. Analog filter between ADC and VGA can be used with added noise and power. Digital filter achieves the same performance as analog filters and has more flexibility in fine tuning multiple characteristics.

ADS5294 includes optional first-order digital high-pass (HP) IIR filter. Figure 61 shows the device block diagram and transfer function.

Figure 61. HP Filter Block Diagram

Figure 62 shows the characteristics at k=2 to 10.

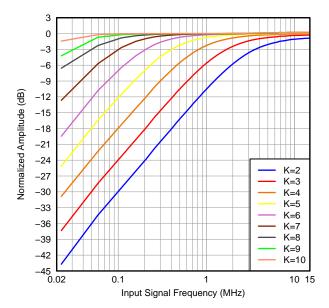


Figure 62. HP Filter Amplitude Response at K = 2 to 10



## **DECIMATION FILTER**

ADS5294 includes an option to decimate the ADC output data using filters. Once the decimation is enabled, the decimation rate, frequency band of the filter can be programmed. In addition, the user can select either the predefined or custom coefficients.

DECIMATION	TYPE OF FILTER	DATA_RAT E	FILTERn_RA TE	FILTERn_CO EFF_SET	ODD_TAP	USE_FILTE R_CHn	EN_CUSTOM_ FILT
De size et a hur 0	Built-in <b>low-pass odd-tap</b> filter (pass band = 0 to $f_S / 4$ )	01	000	000	1	1	0
Decimate by 2	Built-in high-pass odd-tap filter (pass band = 0 to $f_S / 4$ )	01	000	001	1	1	0
	Built-in <b>low-pass even-tap</b> filter (pass band = 0 to $f_S / 8$ )	10	001	010	0	1	0
Decimate by 4	Built-in first <b>band pass even tap</b> filter (pass band = $f_S / 8$ to $f_S / 4$ )	10	001	011	0	1	0
	Built-in second <b>band pass even tap</b> filter (pass band = $f_S$ / 4 to 3 $f_S$ / 8)	10	001	100	0	1	0
	Built-in high pass odd tap filter (pass band = $3 f_S / 8$ to $f_S / 2$ )	10	001	101	1	1	0
Decimate by 2	Custom filter (user-programmable coefficients)	01	000	000	0 and 1	1	1
Decimate by 4	Custom filter (user-programmable coefficients)	10	001	000	0 and 1	1	1
Decimate by 8	Custom filter (user-programmable coefficients)	11	100	000	0 and 1	1	1
Bypass decimation	Custom filter (user-programmable coefficients)				0 and 1	1	1
Note: EN_CUSTOM	FILT is the D15 of register 5A (Hex) to B9 (Hex).	1	1	1	1		

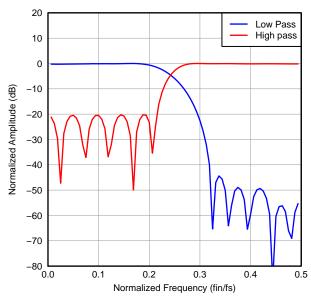
#### Table 16. Digital Filters

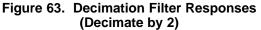
# **DECIMATION FILTER EQUATION**

In the default setting, the decimation filter is implemented as a 24-tap FIR filter with symmetrical coefficients (each coefficient is 12-bit signed). By setting the register bit **ODD\_TAPn** = 1, a 23-tap FIR is implemented

#### **Pre-defined Coefficients**

The built-in filters (low pass, high pass, and band pass) use pre-defined coefficients. The frequency responses of the build-in decimation filters with different decimation factors are shown in Figure 63.





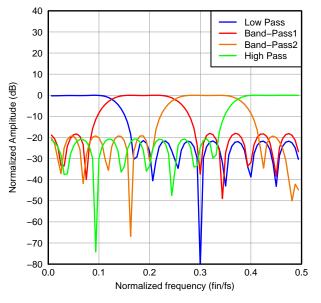


Figure 64. Decimation Filter Responses (Decimate by 4)

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#### **Custom Filter Coefficients**

The filter coefficients are also programmed, or customized, by the user. For custom coefficients, set the register bit **<FILTER COEFF SELECT>** and load the coefficients ( $h_0$  to  $h_{11}$ ) in registers 0x5A to 0xB9, using the serial interface as:

Register content = real coefficient value × 211, 12-bit signed representation of real coefficient.

#### **Board Design Considerations**

#### Grounding

A single ground plane is sufficient to give good performance, provided the analog, digital, and clock sections of the board are cleanly partitioned. See the *ADS5294VM Evaluation Module* (SLAU355) for placement of components, routing, and grounding.

#### Supply Decoupling

Because the ADS5294 already includes internal decoupling, minimal external decoupling can be used without loss in performance. For example, the ADS5294EVM uses a single 0.1-µF decoupling capacitor for each supply, placed close to the device supply pins.

#### Packaging

#### Exposed Pad

The exposed pad at the bottom of the package is the main path for heat dissipation. Solder the pad to a ground plane on the PCB for best thermal performance. The pad must be connected to the ground plane through the optimum number of vias.

See TI's thermal Web site at www.ti.com/thermal for additional information.



#### **DEFINITION OF SPECIFICATIONS**

- Analog Bandwidth The analog input frequency at which the power of the fundamental is reduced by 3 dB with respect to the low-frequency value.
- Aperture Delay The delay in time between the rising edge of the input sampling clock and the actual time at which the sampling occurs. This delay is different across channels. The maximum variation is specified as aperture delay variation (channel-to-channel).
- Aperture Uncertainty (Jitter) The sample-to-sample variation in aperture delay.
- **Clock Pulse Width and Duty Cycle** The duty cycle of a clock signal is the ratio of the time the clock signal remains at a logic high (clock pulse width) to the period of the clock signal. Duty cycle is typically expressed as a percentage. A perfect differential sine-wave clock results in a 50% duty cycle.
- Maximum Conversion Rate The maximum sampling rate at which specified operation is given. All parametric testing is performed at this sampling rate unless otherwise noted.
- Minimum Conversion Rate The minimum sampling rate at which the ADC functions.
- **Differential Non-Linearity (DNL)**An ideal ADC exhibits code transitions at analog input values spaced exactly 1 LSB apart. The DNL is the deviation of any single step from this ideal value, measured in units of LSBs.
- **Integral Nonlinearity (INL)** The INL is the deviation of the ADC transfer function from a best fit line determined by a least squares curve fit of that transfer function, measured in units of LSBs.
- **Gain Error** Gain error is the deviation of the ADC actual input full-scale range from its ideal value. The gain error is given as a percentage of the ideal input full-scale range. Gain error has two components: error as a result of reference inaccuracy and error as a result of the channel. Both errors are specified independently as E<sub>GREF</sub> and E<sub>GCHAN</sub>.

To a first-order approximation, the total gain error is  $E_{TOTAL} \sim E_{GREF} + E_{GCHAN}$ .

For example, if  $E_{TOTAL} = \pm 0.5\%$ , the full-scale input varies from  $(1 - 0.5 / 100) \times FS_{ideal}$  to  $(1 + 0.5 / 100) \times FS_{ideal}$ .

- **Offset Error** The offset error is the difference, given in number of LSBs, between the ADC actual average idle channel output code and the ideal average idle channel output code. This quantity is often mapped into millivolts.
- **Temperature Drift** The temperature drift coefficient (with respect to gain error and offset error) specifies the change per degree Celsius of the parameter from  $T_{MIN}$  to  $T_{MAX}$ . Temperature drift is calculated by dividing the maximum deviation of the parameter across the  $T_{MIN}$  to  $T_{MAX}$  range by the difference  $T_{MAX} T_{MIN}$ .
- **Signal-to-Noise Ratio** SNR is the ratio of the power of the fundamental ( $P_S$ ) to the noise floor power ( $P_N$ ), excluding the power at DC and the first nine harmonics.

SNR = 
$$10 \text{Log}^{10} \frac{\text{P}_{\text{S}}}{\text{P}_{\text{N}}}$$

(7)

SNR is either given in units of dBc (dB to carrier) when the absolute power of the fundamental is used as the reference, or dBFS (dB to full-scale) when the power of the fundamental is extrapolated to the converter full-scale range.

**Signal-to-Noise and Distortion (SINAD)** SINAD is the ratio of the power of the fundamental (P<sub>S</sub>) to the power of all the other spectral components including noise (P<sub>N</sub>) and distortion (P<sub>D</sub>), but excluding DC.

SINAD = 
$$10 \text{Log}^{10} \frac{\text{P}_{\text{S}}}{\text{P}_{\text{N}} + \text{P}_{\text{D}}}$$

(8)

SINAD is either given in units of dBc (dB to carrier) when the absolute power of the fundamental is used as the reference, or dBFS (dB to full-scale) when the power of the fundamental is extrapolated to the converter full-scale range.

Effective Number of Bits (ENOB) ENOB is a measure of the converter performance as compared to the theoretical limit based on quantization noise.

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$$\mathsf{ENOB} = \frac{\mathsf{SINAD} - 1.76}{6.02}$$

**Total Harmonic Distortion (THD)** THD is the ratio of the power of the fundamental (P<sub>S</sub>) to the power of the first nine harmonics (P<sub>D</sub>).

$$THD = 10 \text{Log}^{10} \frac{P_{\text{S}}}{P_{\text{N}}}$$
(10)

THD is typically given in units of dBc (dB to carrier).

- **Spurious-Free Dynamic Range (SFDR)** The ratio of the power of the fundamental to the highest other spectral component (either spur or harmonic). SFDR is typically given in units of dBc (dB to carrier).
- **Two-Tone Intermodulation Distortion** IMD3 is the ratio of the power of the fundamental (at frequencies  $f_1$  and  $f_2$ ) to the power of the worst spectral component at either frequency  $2f_1 f_2$  or  $2f_2 f_1$ . IMD3 is either given in units of dBc (dB to carrier) when the absolute power of the fundamental is used as the reference, or dBFS (dB to full-scale) when the power of the fundamental is extrapolated to the converter full-scale range.
- DC Power-Supply Rejection Ratio (DC PSRR) DC PSSR is the ratio of the change in offset error to a change in analog supply voltage. The DC PSRR is typically given in units of mV/V.
- AC Power-Supply Rejection Ratio (AC PSRR) AC PSRR is the measure of rejection of variations in the supply voltage by the ADC. If  $\Delta V_{SUP}$  is the change in supply voltage and  $\Delta V_{OUT}$  is the resultant change of the ADC output code (referred to the input), then:

PSRR = 20Log<sup>10</sup> 
$$\frac{\Delta V_{OUT}}{\Delta V_{SUP}}$$
 (Expressed in dBc)

- **Voltage Overload Recovery** The number of clock cycles taken to recover to less than 1% error after an overload on the analog inputs. Voltage overload recovery is tested by separately applying a sine wave signal with 6dB positive and negative overload. The deviation of the first few samples after the overload (from the expected values) is noted.
- **Common-Mode Rejection Ratio (CMRR)** CMRR is the measure of rejection of variation in the analog input common-mode by the ADC. If  $\Delta V_{CM_{IN}}$  is the change in the common-mode voltage of the input pins and  $\Delta V_{OUT}$  is the resulting change of the ADC output code (referred to the input), then:

CMRR = 20Log<sup>10</sup> 
$$\frac{\Delta V_{OUT}}{\Delta V_{CM}}$$
 (Expressed in dBc)

**Crosstalk (only for multi-channel ADCs)** Crosstalk is a measure of the internal coupling of a signal from an adjacent channel into the channel of interest. Crosstalk is specified separately for coupling from the immediate neighboring channel (near-channel) and for coupling from channel across the package (farchannel). Crosstalk is usually measured by applying a full-scale signal in the adjacent channel. Crosstalk is the ratio of the power of the coupling signal (as measured at the output of the channel of interest) to the power of the signal applied at the adjacent channel input. Crosstalk is typically expressed in dBc.



(9)

(11)

(12)

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#### **REVISION HISTORY**

Changes from Original (November 2011) to Revision A						
•	Changed From: Product Preview To: Production		1			

#### Changes from Revision A (November 2011) to Revision B

•	Changed the location of OUT A and OUT B in Figure 5 and Figure 6	15
•	Added EN_HIGH_ADDRS to Table 3	30
•	Moved EN_EXT_REF From: 0x0F To: 0xF0 in Table 3	34
•	Added the section BIT-BYTE-WORD WISE OUTPUT. Added Figure 47 and Figure 48	37
•	Added section DIGITAL PROCESSING BLOCKS	38
•	Replaced Table 5 and Table 6 with new Table 8 - Digital Filters	43
•	Changed the SYNCHRONIZATION PULSE section	46
•	Added the External Reference Mode of Operation section	48
•	Added Figure 59	56
•	Replaced Table 9 (Decimation Filter Modes) with new Table 16 - Digital Filters	59
•	Deleted section: Synchronization Pulse	60

#### Changes from Revision B (July 2012) to Revision C

•	Added cross-reference link for VCM pin.	3
•	Added note for REFB pin under INT/EXT reference modes.	4
•	Added note for REFT pin under INT/EXT reference modes.	4
•	Changed the maximum rating of digital input pins RESET, SCLK, SDATA, SYNC, PD, CSZ to 3.6V.	5
•	Added test condition "Digital Filter Disabled" and changed "LVDS output rate" to "ADC CLK Frequency" in Table 1	11
•	Added test condition "Digital Filter Disabled" and changed "LVDS output rate" to "ADC CLK Frequency" in Table 2	11
•	Added note after Table 2 : The above LVDS timing spec is only valid when digital filters are disabled	11
•	Added Table 3.	12
•	Added Table 4.	12
•	Added Table 5.	12
•	Added a note "RMS Noise = 96.4 uV" to Figure 28	23
•	Added a note link to Reg.0x38 .	33
•	Changed 0xF[15] to 0xF0[15] in the description of Reg.0x42.	34
•	Changed the Reg.0x46[11:8] formatting.	34
•	Corrected the EN_RAMP address from 0x24 to 0x25 in the section of LVDS test patterns	36
•	Changed "Note that these bits are functional only when the GLOBAL_EN_FILTER gets set to 1" to " Note that these bits are functional only when the GLOBAL_EN_FILTER gets set to 1 and USE_FILTERn bit is set to 1" in the	
	section of Decimation Filter,	42
•	Added a note related to EN_CUSTOM_FILT and changed formats in the Table 5.	44
•	Changed Equation (5)	48
•	Added register address in Table 9.	48
•	Added PLL Operation Versus LVDS Timing before APPLICATION INFORMATION section	52
•	Revised Figure 58 and moved the 2pF cap to the left hand side of the resistors.	56
•	Added a note regarding the location of LVDS Rterm in the section of Input clock.	56
•	Added a note related to EN_CUSTOM_FILT and changed formats in Table 9.	59



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# PACKAGING INFORMATION

Orderable Device	Status	Package Type	Package	Pins	Package	Eco Plan	Lead/Ball Finish	MSL Peak Temp	Op Temp (°C)	Device Marking	Samples
	(1)		Drawing		Qty	(2)		(3)		(4/5)	
ADS5294IPFP	ACTIVE	HTQFP	PFP	80	96	Green (RoHS & no Sb/Br)	CU NIPDAU	Level-3-260C-168 HR	-40 to 85	ADS5294	Samples
ADS5294IPFPR	ACTIVE	HTQFP	PFP	80	1000	Green (RoHS & no Sb/Br)	CU NIPDAU	Level-3-260C-168 HR	-40 to 85	ADS5294	Samples
ADS5294IPFPT	ACTIVE	HTQFP	PFP	80	250	Green (RoHS & no Sb/Br)	CU NIPDAU	Level-3-260C-168 HR	-40 to 85	ADS5294	Samples

<sup>(1)</sup> The marketing status values are defined as follows:

**ACTIVE:** Product device recommended for new designs.

LIFEBUY: TI has announced that the device will be discontinued, and a lifetime-buy period is in effect.

NRND: Not recommended for new designs. Device is in production to support existing customers, but TI does not recommend using this part in a new design.

**PREVIEW:** Device has been announced but is not in production. Samples may or may not be available.

**OBSOLETE:** TI has discontinued the production of the device.

<sup>(2)</sup> Eco Plan - The planned eco-friendly classification: Pb-Free (RoHS), Pb-Free (RoHS Exempt), or Green (RoHS & no Sb/Br) - please check http://www.ti.com/productcontent for the latest availability information and additional product content details.

**TBD:** The Pb-Free/Green conversion plan has not been defined.

**Pb-Free (RoHS):** TI's terms "Lead-Free" or "Pb-Free" mean semiconductor products that are compatible with the current RoHS requirements for all 6 substances, including the requirement that lead not exceed 0.1% by weight in homogeneous materials. Where designed to be soldered at high temperatures, TI Pb-Free products are suitable for use in specified lead-free processes.

**Pb-Free (RoHS Exempt):** This component has a RoHS exemption for either 1) lead-based flip-chip solder bumps used between the die and package, or 2) lead-based die adhesive used between the die and leadframe. The component is otherwise considered Pb-Free (RoHS compatible) as defined above.

Green (RoHS & no Sb/Br): TI defines "Green" to mean Pb-Free (RoHS compatible), and free of Bromine (Br) and Antimony (Sb) based flame retardants (Br or Sb do not exceed 0.1% by weight in homogeneous material)

<sup>(3)</sup> MSL, Peak Temp. -- The Moisture Sensitivity Level rating according to the JEDEC industry standard classifications, and peak solder temperature.

<sup>(4)</sup> There may be additional marking, which relates to the logo, the lot trace code information, or the environmental category on the device.

<sup>(5)</sup> Multiple Device Markings will be inside parentheses. Only one Device Marking contained in parentheses and separated by a "~" will appear on a device. If a line is indented then it is a continuation of the previous line and the two combined represent the entire Device Marking for that device.

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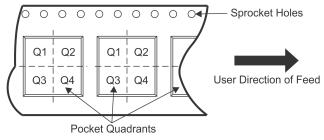
Texas Instruments

# TAPE AND REEL INFORMATION





# QUADRANT ASSIGNMENTS FOR PIN 1 ORIENTATION IN TAPE



*A	l dimensions are nominal												
	Device	Package Type	Package Drawing		SPQ	Reel Diameter (mm)	Reel Width W1 (mm)	A0 (mm)	B0 (mm)	K0 (mm)	P1 (mm)	W (mm)	Pin1 Quadrant
	ADS5294IPFPR	HTQFP	PFP	80	1000	330.0	24.4	15.0	15.0	1.5	20.0	24.0	Q2
	ADS5294IPFPT	HTQFP	PFP	80	250	330.0	24.4	15.0	15.0	1.5	20.0	24.0	Q2

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# PACKAGE MATERIALS INFORMATION

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\*All dimensions are nominal

Device	Package Type	Package Drawing	Pins	SPQ	Length (mm)	Width (mm)	Height (mm)
ADS5294IPFPR	HTQFP	PFP	80	1000	367.0	367.0	45.0
ADS5294IPFPT	HTQFP	PFP	80	250	367.0	367.0	45.0

PFP (S-PQFP-G80)

PowerPAD™ PLASTIC QUAD FLATPACK



NOTES: A. All linear dimensions are in millimeters.

B. This drawing is subject to change without notice.

- C. Body dimensions do not include mold flash or protrusion
- D. This package is designed to be soldered to a thermal pad on the board. Refer to Technical Brief, PowerPad Thermally Enhanced Package, Texas Instruments Literature No. SLMA002 for information regarding recommended board layout. This document is available at www.ti.com <a href="http://www.ti.com">http://www.ti.com</a>.
- E. See the additional figure in the Product Data Sheet for details regarding the exposed thermal pad features and dimensions.

F. Falls within JEDEC MS-026

PowerPAD is a trademark of Texas Instruments.



# THERMAL PAD MECHANICAL DATA

# PFP (S-PQFP-G80)

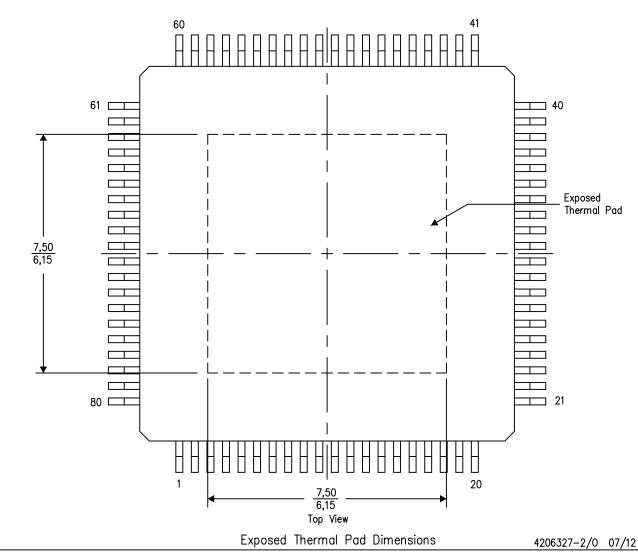
# PowerPAD<sup>™</sup> PLASTIC QUAD FLATPACK

#### THERMAL INFORMATION

This PowerPAD<sup>™</sup> package incorporates an exposed thermal pad that is designed to be attached to a printed circuit board (PCB). The thermal pad must be soldered directly to the PCB. After soldering, the PCB can be used as a heatsink. In addition, through the use of thermal vias, the thermal pad can be attached directly to the appropriate copper plane shown in the electrical schematic for the device, or alternatively, can be attached to a special heatsink structure designed into the PCB. This design optimizes the heat transfer from the integrated circuit (IC).

For additional information on the PowerPAD package and how to take advantage of its heat dissipating abilities, refer to Technical Brief, PowerPAD Thermally Enhanced Package, Texas Instruments Literature No. SLMA002 and Application Brief, PowerPAD Made Easy, Texas Instruments Literature No. SLMA004. Both documents are available at www.ti.com.

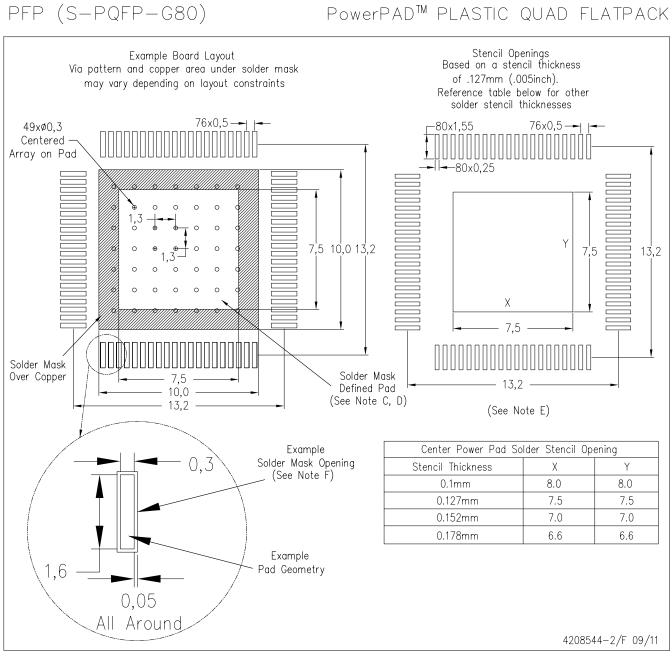
The exposed thermal pad dimensions for this package are shown in the following illustration.



NOTE: A. All linear dimensions are in millimeters

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NOTES:

- A. All linear dimensions are in millimeters.B. This drawing is subject to change without notice.
- C. Customers should place a note on the circuit board fabrication drawing not to alter the center solder mask defined pad.
- D. This package is designed to be soldered to a thermal pad on the board. Refer to Technical Brief, PowerPad Thermally Enhanced Package, Texas Instruments Literature No. SLMA002, SLMA004, and also the Product Data Sheets for specific thermal information, via requirements, and recommended board layout. These documents are available at www.ti.com <http://www.ti.com>. Publication IPC-7351 is recommended for alternate designs.
- E. Laser cutting apertures with trapezoidal walls and also rounding corners will offer better paste release. Customers should contact their board assembly site for stencil design recommendations. Example stencil design based on a 50% volumetric metal load solder paste. Refer to IPC-7525 for other stencil recommendations.
- F. Customers should contact their board fabrication site for solder mask tolerances between and around signal pads.

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