

# FSBF10CH60BTL

## Motion SPM® 3 Series

### Features

- UL Certified No. E209204
- 600 V - 10 A 3 - Phase IGBT Inverter Bridge Including Control ICs for Gate Driving And Protection
- Easy PCB Layout Thanks to Built - In Bootstrap Diodes
- Three Separate Negative DC - link Terminals for Inverter Current Sensing Applications
- Single - Grounded Power Supply for Built - In HVICs
- Isolation Rating of 2500 Vrms / min.
- Short Lead Length Version of FSBF10CH60BT

### Applications

- Motion Control - Home Appliance / Industrial Motor

### Related Resources

- [AN - 9044 : Motion SPM® 3 Series Users Guide](#)

### General Description

FSBF10CH60BTL Is An Advacned Motion SPM® 3 Series that Fairchild Has Newly Developed to Provide A Very Compact and High Performance Inverter Solution for AC Motor Drives in Low - Power Applications Such as Air Conditioners and Washing Machines. It Combines Optimized Circuit Protections and Drives Matched to Low - Loss IGBTs. The System Reliability Is Further Enhanced by The Integrated Under - Voltage Lock - Out and Over - Current Protection. The High Speed Built - In HVIC Provides Optocoupler - Less Single - Supply IGBT Gate Driving Capability that Further Reduces The Overall Size of The Inverter System. Each Phase Leg Current of The Inverter Can Be Monitored Thanks to Three Separate Negative DC Terminals.

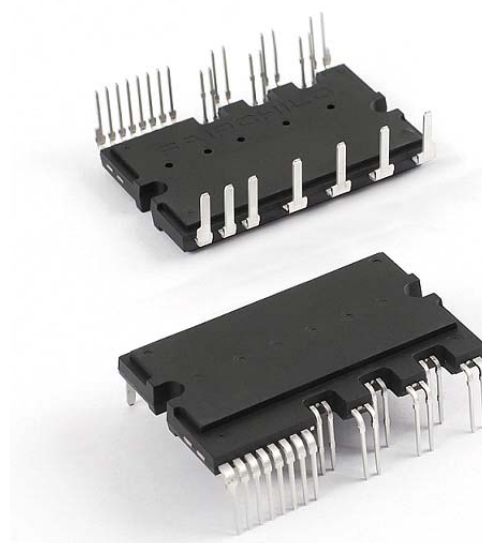


Figure 1. Package Overview

### Package Marking and Ordering Information

Device Marking	Device	Package	Packing Type	Reel Size	Tape Width	Quantity
FSBF10CH60BTL	FSBF10CH60BTL	SPMJB - 027	RAIL	-	-	10

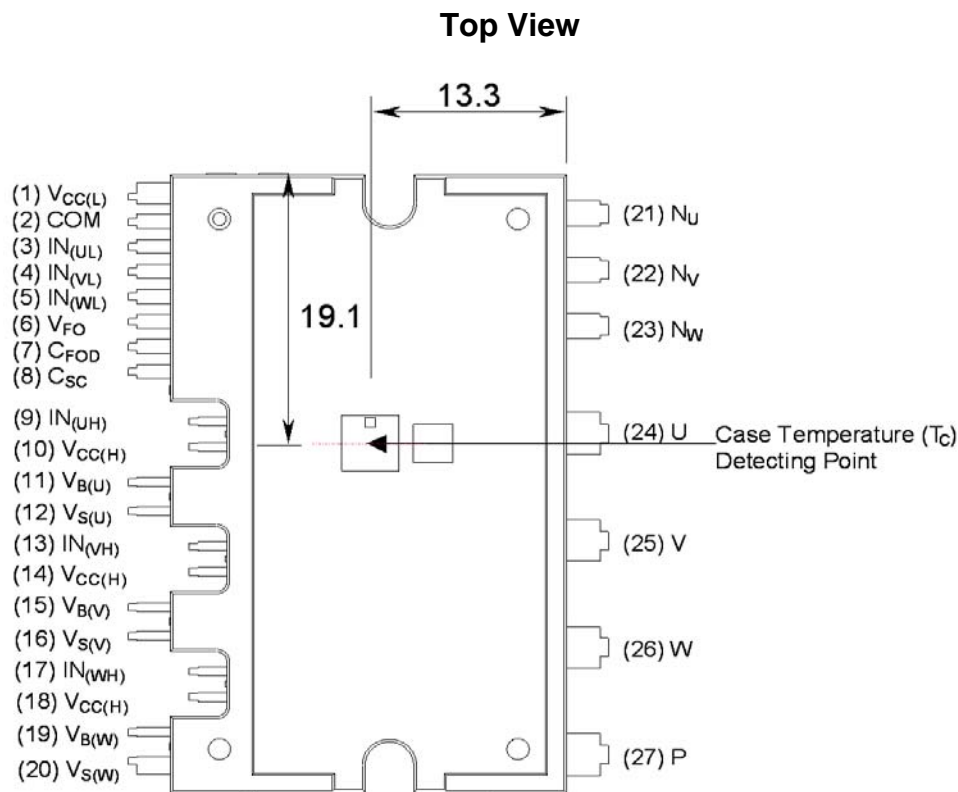
## Integrated Power Functions

- 600 V - 10 A IGBT inverter for three - phase DC / AC power conversion (Please refer to Figure 3)

## Integrated Drive, Protection and System Control Functions

- For inverter high - side IGBTs: Gate drive circuit, High voltage isolated high - speed level shifting  
Control circuit under - voltage (UV) protection  
Note) Available bootstrap circuit example is given in Figures 12 and 13.
- For inverter low - side IGBTs: Gate drive circuit, Short circuit protection (SC)  
Control supply circuit under - voltage (UV) protection
- Fault signaling: Corresponding to UV (low - side supply) and SC faults
- Input interface: Active - high interface, can work with 3.3 / 5 V logic

## Pin Configuration

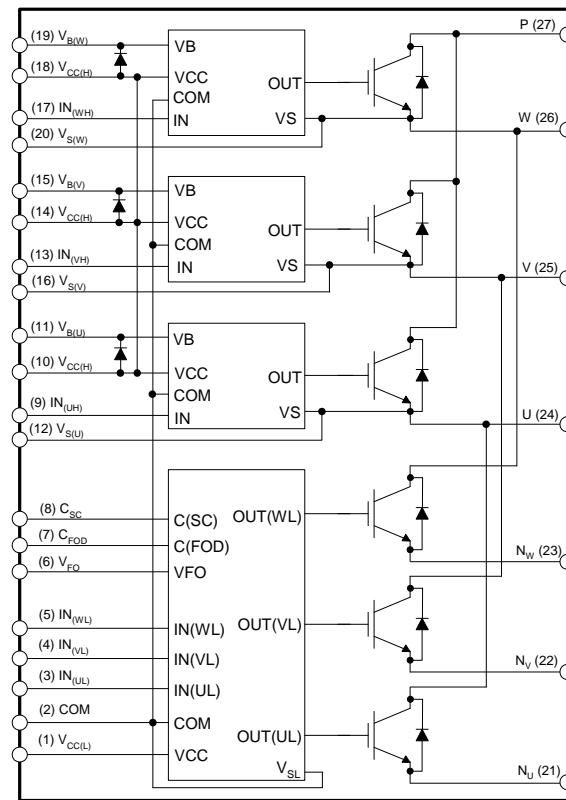


**Figure 2.**

## Pin Descriptions

Pin Number	Pin Name	Pin Description
1	$V_{CC(L)}$	Low - Side Common Bias Voltage for IC and IGBTs Driving
2	COM	Common Supply Ground
3	$IN_{(UL)}$	Signal Input for Low - Side U Phase
4	$IN_{(VL)}$	Signal Input for Low - Side V Phase
5	$IN_{(WL)}$	Signal Input for Low - Side W Phase
6	$V_{FO}$	Fault Output
7	$C_{FOD}$	Capacitor for Fault Output Duration Time Selection
8	$C_{SC}$	Capacitor (Low - Pass Filter) for Short - Current Detection Input
9	$IN_{(UH)}$	Signal Input for High - Side U Phase
10	$V_{CC(H)}$	High - Side Common Bias Voltage for IC and IGBTs Driving
11	$V_{B(U)}$	High - Side Bias Voltage for U Phase IGBT Driving
12	$V_{S(U)}$	High - Side Bias Voltage Ground for U Phase IGBT Driving
13	$IN_{(VH)}$	Signal Input for High - Side V Phase
14	$V_{CC(H)}$	High - Side Common Bias Voltage for IC and IGBTs Driving
15	$V_{B(V)}$	High - Side Bias Voltage for V Phase IGBT Driving
16	$V_{S(V)}$	High - Side Bias Voltage Ground for V Phase IGBT Driving
17	$IN_{(WH)}$	Signal Input for High - Side W Phase
18	$V_{CC(H)}$	High - Side Common Bias Voltage for IC and IGBTs Driving
19	$V_{B(W)}$	High - Side Bias Voltage for W Phase IGBT Driving
20	$V_{S(W)}$	High - Side Bias Voltage Ground for W Phase IGBT Driving
21	$N_U$	Negative DC - Link Input for U Phase
22	$N_V$	Negative DC - Link Input for V Phase
23	$N_W$	Negative DC - Link Input for W Phase
24	U	Output for U Phase
25	V	Output for V Phase
26	W	Output for W Phase
27	P	Positive DC - Link Input

## Internal Equivalent Circuit and Input/Output Pins



### Note:

1. Inverter low - side is composed of three IGBTs, freewheeling diodes for each IGBT and one control IC. It has gate drive and protection functions.
2. Inverter power side is composed of four inverter dc - link input terminals and three inverter output terminals.
3. Inverter high - side is composed of three IGBTs, freewheeling diodes and three drive ICs for each IGBT.

**Figure 3.**

## Absolute Maximum Ratings ( $T_J = 25^\circ\text{C}$ , Unless Otherwise Specified)

### Inverter Part

Symbol	Parameter	Conditions	Rating	Unit
$V_{PN}$	Supply Voltage	Applied between P - $N_U$ , $N_V$ , $N_W$	450	V
$V_{PN(\text{Surge})}$	Supply Voltage (Surge)	Applied between P - $N_U$ , $N_V$ , $N_W$	500	V
$V_{CES}$	Collector - Emitter Voltage		600	V
$\pm I_C$	Each IGBT Collector Current	$T_C = 25^\circ\text{C}$ , $T_J \leq 150^\circ\text{C}$	10	A
$\pm I_{CP}$	Each IGBT Collector Current (Peak)	$T_C = 25^\circ\text{C}$ , $T_J \leq 150^\circ\text{C}$ , Under 1 ms Pulse Width	20	A
$P_C$	Collector Dissipation	$T_C = 25^\circ\text{C}$ per One Chip	20	W
$T_J$	Operating Junction Temperature	(Note 1)	- 40 ~ 150	$^\circ\text{C}$

**Note:**

1. The maximum junction temperature rating of the power chips integrated within the Motion SPM® 3 product is  $150^\circ\text{C}$  ( $@T_C \leq 125^\circ\text{C}$ ).

### Control Part

Symbol	Parameter	Conditions	Rating	Unit
$V_{CC}$	Control Supply Voltage	Applied between $V_{CC(H)}$ , $V_{CC(L)}$ - COM	20	V
$V_{BS}$	High-side Control Bias Voltage	Applied between $V_{B(U)}$ - $V_{S(U)}$ , $V_{B(V)}$ - $V_{S(V)}$ , $V_{B(W)}$ - $V_{S(W)}$	20	V
$V_{IN}$	Input Signal Voltage	Applied between $IN_{(UH)}$ , $IN_{(VH)}$ , $IN_{(WH)}$ , $IN_{(UL)}$ , $IN_{(VL)}$ , $IN_{(WL)}$ - COM	- 0.3 ~ $V_{CC} + 0.3$	V
$V_{FO}$	Fault Output Supply Voltage	Applied between $V_{FO}$ - COM	- 0.3 ~ $V_{CC} + 0.3$	V
$I_{FO}$	Fault Output Current	Sink Current at $V_{FO}$ pin	5	mA
$V_{SC}$	Current Sensing Input Voltage	Applied between $C_{SC}$ - COM	- 0.3 ~ $V_{CC} + 0.3$	V

### Bootstrap Diode Part

Symbol	Parameter	Conditions	Rating	Unit
$V_{RRM}$	Maximum Repetitive Reverse Voltage		600	V
$I_F$	Forward Current	$T_C = 25^\circ\text{C}$ , $T_J \leq 150^\circ\text{C}$	0.5	A
$I_{FP}$	Forward Current (Peak)	$T_C = 25^\circ\text{C}$ , $T_J \leq 150^\circ\text{C}$ , Under 1 ms Pulse Width	2.0	A
$T_J$	Operating Junction Temperature		- 40 ~ 150	$^\circ\text{C}$

### Total System

Symbol	Parameter	Conditions	Rating	Unit
$V_{PN(\text{PROT})}$	Self Protection Supply Voltage Limit (Short Circuit Protection Capability)	$V_{CC} = V_{BS} = 13.5 \sim 16.5 \text{ V}$ , $T_J = 150^\circ\text{C}$ , Non - repetitive, less than 2 $\mu\text{s}$	400	V
$T_C$	Module Case Operation Temperature	- $40^\circ\text{C} \leq T_J \leq 150^\circ\text{C}$ , See Figure 2	- 40 ~ 125	$^\circ\text{C}$
$T_{STG}$	Storage Temperature		- 40 ~ 125	$^\circ\text{C}$
$V_{ISO}$	Isolation Voltage	60 Hz, Sinusoidal, AC 1 minute, Connection pins to heat sink plate	2500	$V_{rms}$

### Thermal Resistance

Symbol	Parameter	Conditions	Min.	Typ.	Max.	Unit
$R_{th(j-c)Q}$	Junction to Case Thermal Resistance	Inverter IGBT part (per 1 / 6 module)	-	-	6.2	$^\circ\text{C} / \text{W}$
$R_{th(j-c)F}$		Inverter FWD part (per 1 / 6 module)	-	-	6.5	$^\circ\text{C} / \text{W}$

**Note:**

2. For the measurement point of case temperature ( $T_C$ ), please refer to Figure 2.

**Electrical Characteristics** ( $T_J = 25^\circ\text{C}$ , Unless Otherwise Specified)**Inverter Part**

Symbol	Parameter	Conditions	Min.	Typ.	Max.	Unit
$V_{CE(SAT)}$	Collector - Emitter Saturation Voltage	$V_{CC} = V_{BS} = 15\text{ V}$ $V_{IN} = 5\text{ V}$ $I_C = 10\text{ A}$ , $T_J = 25^\circ\text{C}$	-	-	2.2	V
$V_F$	FWD Forward Voltage	$V_{IN} = 0\text{ V}$ $I_F = 10\text{ A}$ , $T_J = 25^\circ\text{C}$	-	-	2.6	V
HS	$t_{ON}$	$V_{PN} = 300\text{ V}$ , $V_{CC} = V_{BS} = 15\text{ V}$ $I_C = 10\text{ A}$ $V_{IN} = 0\text{ V} \leftrightarrow 5\text{ V}$ , Inductive load (Note 3)	-	0.75	-	$\mu\text{s}$
	$t_{C(ON)}$		-	0.15	-	$\mu\text{s}$
	$t_{OFF}$		-	0.50	-	$\mu\text{s}$
	$t_{C(OFF)}$		-	0.15	-	$\mu\text{s}$
	$t_{rr}$		-	0.10	-	$\mu\text{s}$
LS	$t_{ON}$	$V_{PN} = 300\text{ V}$ , $V_{CC} = V_{BS} = 15\text{ V}$ $I_C = 10\text{ A}$ $V_{IN} = 0\text{ V} \leftrightarrow 5\text{ V}$ , Inductive load (Note 3)	-	0.50	-	$\mu\text{s}$
	$t_{C(ON)}$		-	0.25	-	$\mu\text{s}$
	$t_{OFF}$		-	0.50	-	$\mu\text{s}$
	$t_{C(OFF)}$		-	0.15	-	$\mu\text{s}$
	$t_{rr}$		-	0.10	-	$\mu\text{s}$
$I_{CES}$	Collector - Emitter Leakage Current	$V_{CE} = V_{CES}$	-	-	1	mA

**Note:**

3.  $t_{ON}$  and  $t_{OFF}$  include the propagation delay time of the internal drive IC.  $t_{C(ON)}$  and  $t_{C(OFF)}$  are the switching time of IGBT itself under the given gate driving condition internally. For the detailed information, please see Figure 4.

**Control Part**

Symbol	Parameter	Conditions	Min.	Typ.	Max.	Unit
$I_{QCCL}$	Quiescent $V_{CC}$ Supply Current	$V_{CC} = 15\text{ V}$ $IN_{(UL, VL, WL)} = 0\text{ V}$ $V_{CC(L)} - \text{COM}$	-	-	23	mA
$I_{QCCH}$		$V_{CC} = 15\text{ V}$ $IN_{(UH, VH, WH)} = 0\text{ V}$ $V_{CC(H)} - \text{COM}$	-	-	600	$\mu\text{A}$
$I_{QBS}$	Quiescent $V_{BS}$ Supply Current	$V_{BS} = 15\text{ V}$ $IN_{(UH, VH, WH)} = 0\text{ V}$ $V_{B(U)} - V_{S(U)}$ , $V_{B(V)} - V_{S(V)}$ , $V_{B(W)} - V_{S(W)}$	-	-	500	$\mu\text{A}$
$V_{FOH}$	Fault Output Voltage	$V_{SC} = 0\text{ V}$ , $V_{FO}$ Circuit: 4.7 k $\Omega$ to 5 V Pull - up	4.5	-	-	V
$V_{FOL}$		$V_{SC} = 1\text{ V}$ , $V_{FO}$ Circuit: 4.7 k $\Omega$ to 5 V Pull - up	-	-	0.8	V
$V_{SC(ref)}$	Short Circuit Trip Level	$V_{CC} = 15\text{ V}$ (Note 4)	0.45	0.5	0.55	V
TSD	Over - Temperature Protection	Temperature at LVIC	-	160	-	$^\circ\text{C}$
$\Delta\text{TSD}$	Over - Temperature Protection Hysteresis	Temperature at LVIC	-	5	-	$^\circ\text{C}$
$UV_{CCD}$	Supply Circuit Under - Voltage Protection	Detection Level	10.7	11.9	13.0	V
$UV_{CCR}$		Reset Level	11.2	12.4	13.4	V
$UV_{BSD}$		Detection Level	10	11	12	V
$UV_{BSR}$		Reset Level	10.5	11.5	12.5	V
$t_{FOD}$	Fault - Out Pulse Width	$C_{FOD} = 33\text{ nF}$ (Note 5)	1.0	1.8	-	ms
$V_{IN(ON)}$	ON Threshold Voltage	Applied between $IN_{(UH)}$ , $IN_{(VH)}$ , $IN_{(WH)}$ , $IN_{(UL)}$ , $IN_{(VL)}$ , $IN_{(WL)}$ - COM	2.8	-	-	V
$V_{IN(OFF)}$	OFF Threshold Voltage		-	-	0.8	V

**Note:**

4. Short - circuit current protection is functioning only at the low - sides.  
 5. The fault - out pulse width  $t_{FOD}$  depends on the capacitance value of  $C_{FOD}$  according to the following approximate equation:  $C_{FOD} = 18.3 \times 10^{-6} \times t_{FOD} [\text{F}]$

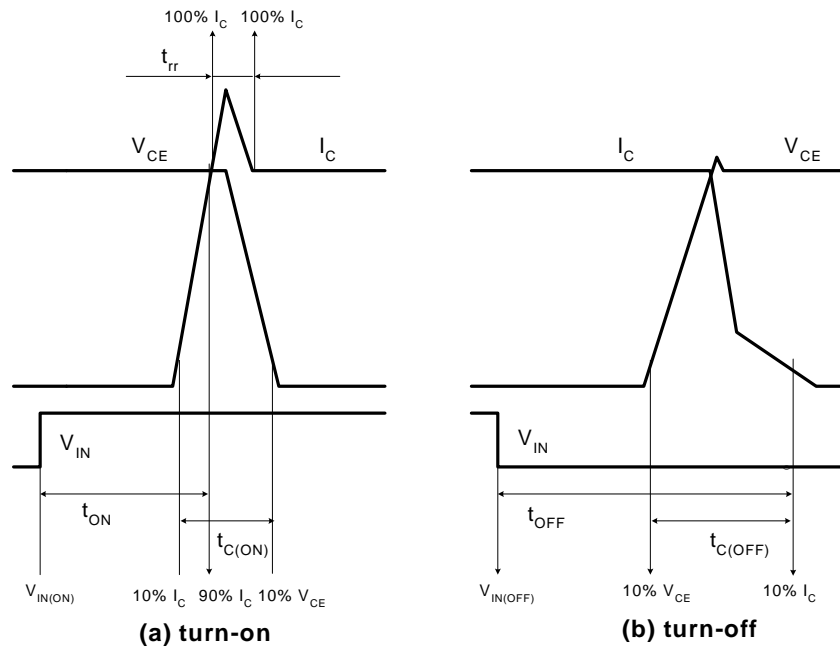


Figure 4. Switching Time Definition

### Switching Loss (Typical)

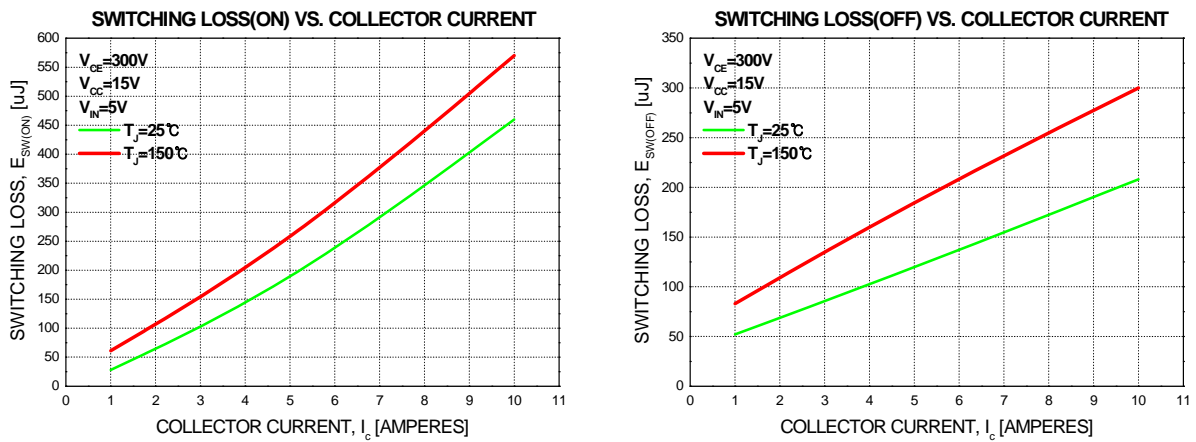
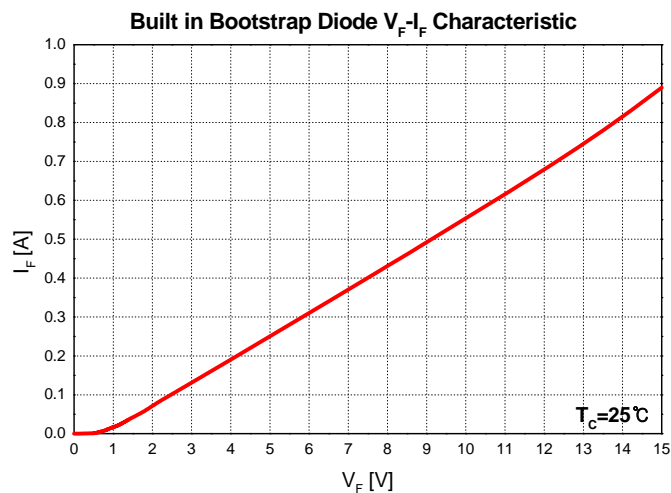


Figure 5. Switching Loss Characteristics

### Bootstrap Diode Part

Symbol	Parameter	Conditions	Min.	Typ.	Max.	Unit
$V_F$	Forward Voltage	$I_F = 0.1 \text{ A}$ , $T_C = 25^\circ\text{C}$	-	2.5	-	V
$t_{rr}$	Reverse Recovery Time	$I_F = 0.1 \text{ A}$ , $T_C = 25^\circ\text{C}$	-	80	-	ns



**Note:**

6. Built in bootstrap diode includes around 15  $\Omega$  resistance characteristic.

**Figure 6. Built in Bootstrap Diode Characteristics**

### Recommended Operating Conditions

Symbol	Parameter	Conditions	Value			Unit
			Min.	Typ.	Max.	
$V_{PN}$	Supply Voltage	Applied between P - $N_U$ , $N_V$ , $N_W$	-	300	400	V
$V_{CC}$	Control Supply Voltage	Applied between $V_{CC(H)}$ , $V_{CC(L)}$ - COM	13.5	15	16.5	V
$V_{BS}$	High - Side Bias Voltage	Applied between $V_{B(U)}$ - $V_{S(U)}$ , $V_{B(V)}$ - $V_{S(V)}$ , $V_{B(W)}$ - $V_{S(W)}$	13.0	15	18.5	V
$dV_{CC} / dt$ , $dV_{BS} / dt$	Control Supply Variation		- 1	-	1	V / $\mu\text{s}$
$t_{dead}$	Blanking Time for Preventing Arm - Short	For Each Input Signal	1.5	-	-	$\mu\text{s}$
$f_{PWM}$	PWM Input Signal	$-40^\circ\text{C} \leq T_C \leq 125^\circ\text{C}$ , $-40^\circ\text{C} \leq T_J \leq 150^\circ\text{C}$	-	-	20	kHz
$V_{SEN}$	Voltage for Current Sensing	Applied between $N_U$ , $N_V$ , $N_W$ - COM (Including surge voltage)	- 4		4	V



## Mechanical Characteristics and Ratings

Parameter	Conditions		Limits			Unit
			Min.	Typ.	Max.	
Mounting Torque	Mounting Screw: M3	Recommended 0.62 N • m	0.51	0.62	1.00	N • m
Device Flatness		Note Figure 7	0	-	+ 120	μm
Weight			-	15.4	-	g

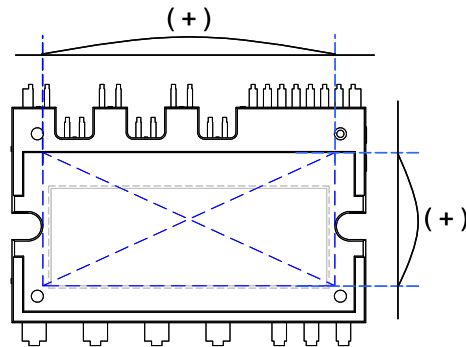
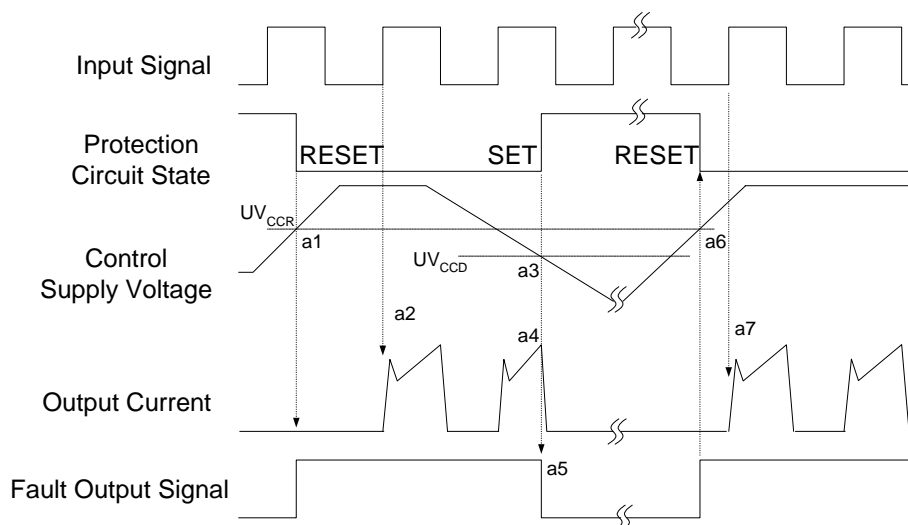


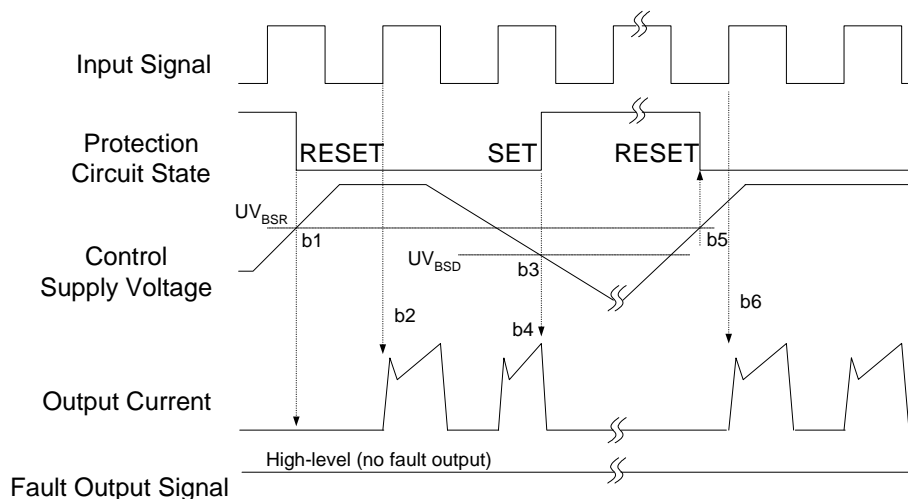
Figure 7. Flatness Measurement Position

## Time Charts of Protective Function



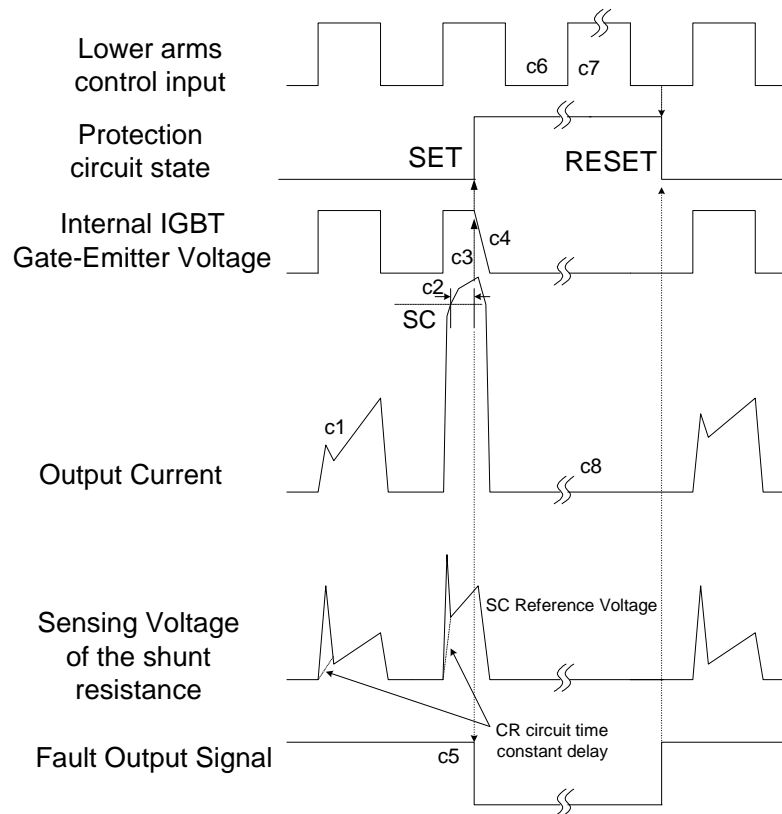
- a1 : Control supply voltage rises: After the voltage rises  $UV_{CCR}$ , the circuits start to operate when next input is applied.
- a2 : Normal operation: IGBT ON and carrying current.
- a3 : Under voltage detection ( $UV_{CCD}$ ).
- a4 : IGBT OFF in spite of control input condition.
- a5 : Fault output operation starts.
- a6 : Under voltage reset ( $UV_{CCR}$ ).
- a7 : Normal operation: IGBT ON and carrying current.

**Figure 8. Under - Voltage Protection (Low - Side)**



- b1 : Control supply voltage rises: After the voltage reaches  $UV_{BSR}$ , the circuits start to operate when next input is applied.
- b2 : Normal operation: IGBT ON and carrying current.
- b3 : Under voltage detection ( $UV_{BSD}$ ).
- b4 : IGBT OFF in spite of control input condition, but there is no fault output signal.
- b5 : Under voltage reset ( $UV_{BSR}$ )
- b6 : Normal operation: IGBT ON and carrying current

**Figure 9. Under - Voltage Protection (High - Side)**



(with the external shunt resistance and CR connection)

c1 : Normal operation: IGBT ON and carrying current.

c2 : Short circuit current detection (SC trigger).

c3 : Hard IGBT gate interrupt.

c4 : IGBT turns OFF.

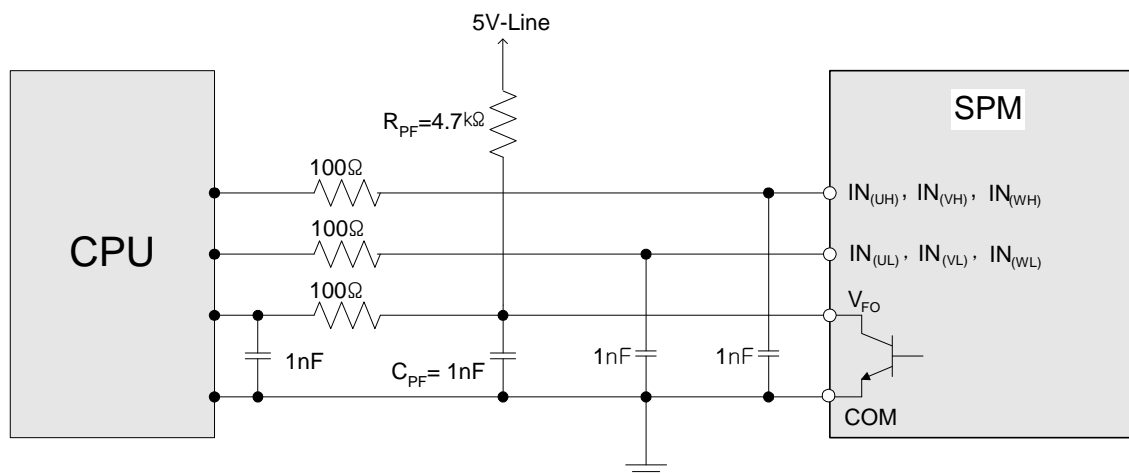
c5 : Fault output timer operation starts: The pulse width of the fault output signal is set by the external capacitor  $C_{FO}$ .

c6 : Input "L" : IGBT OFF state.

c7 : Input "H": IGBT ON state, but during the active period of fault output the IGBT doesn't turn ON.

c8 : IGBT OFF state

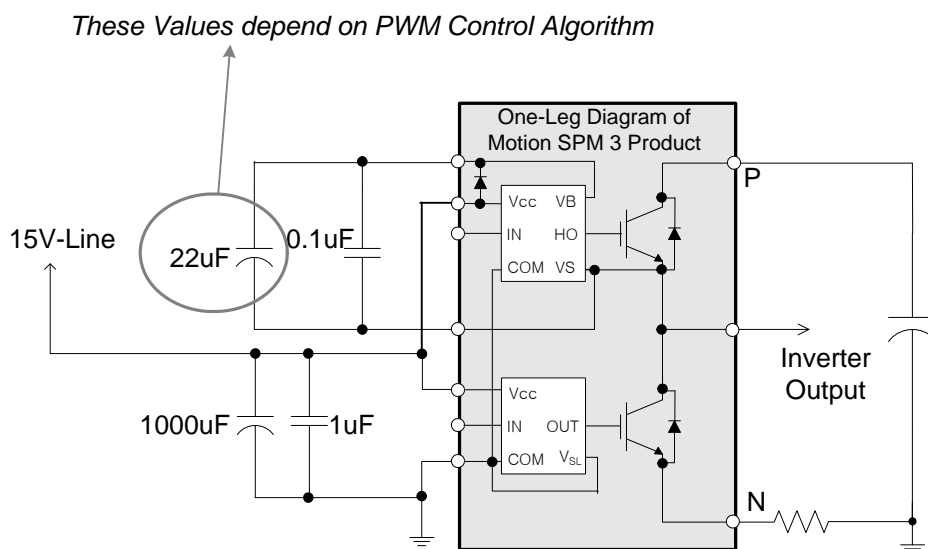
**Figure 10. Short - Circuit Current Protection (Low - Side Operation only)**



**Note:**

- 1) RC coupling at each input might change depending on the PWM control scheme used in the application and the wiring impedance of the application's printed circuit board. The input signal section of the Motion SPM® 3 product integrates 5 kΩ (typ.) pull - down resistor. Therefore, when using an external filtering resistor, please pay attention to the signal voltage drop at input terminal.
- 2) The logic input is compatible with standard CMOS or LSTTL outputs.

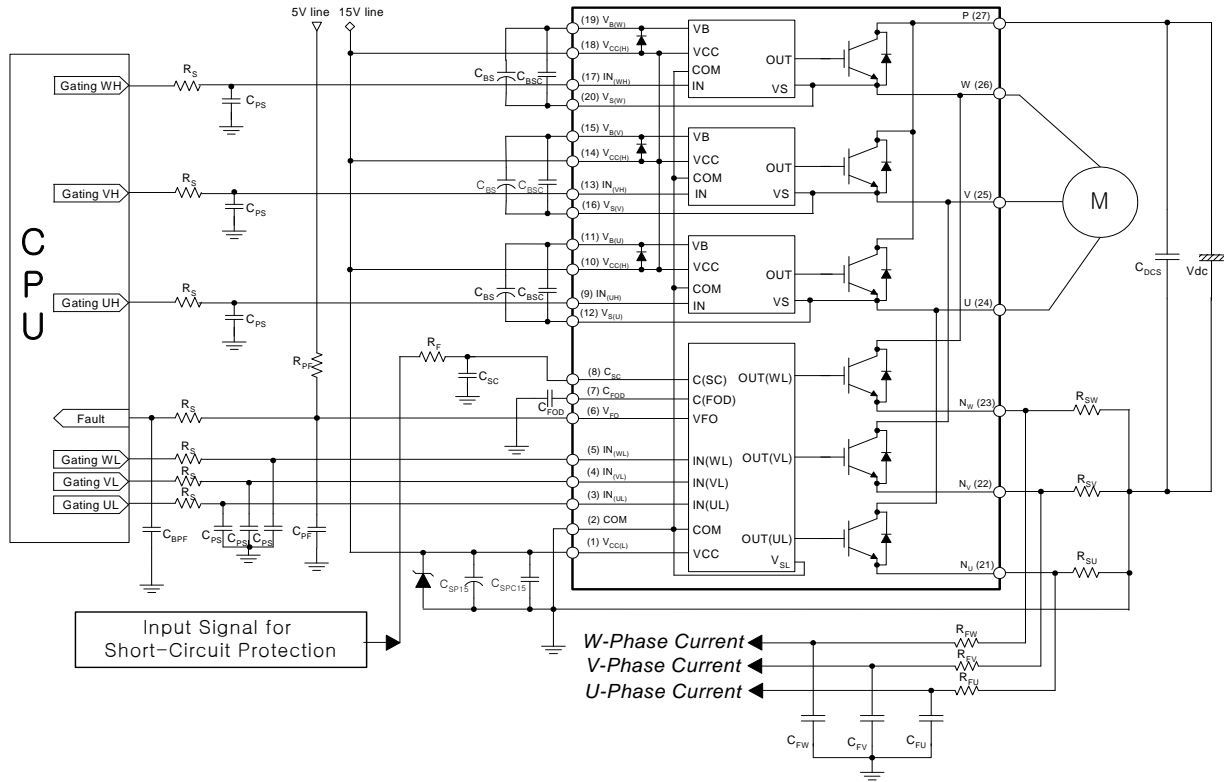
**Figure 11. Recommended CPU I/O Interface Circuit**



**Note:**

- 1) The ceramic capacitor placed between V<sub>CC</sub> - COM should be over 1 μF and mounted as close to the pins of the Motion SPM 3 product as possible.

**Figure 12. Recommended Bootstrap Operation Circuit and Parameters**

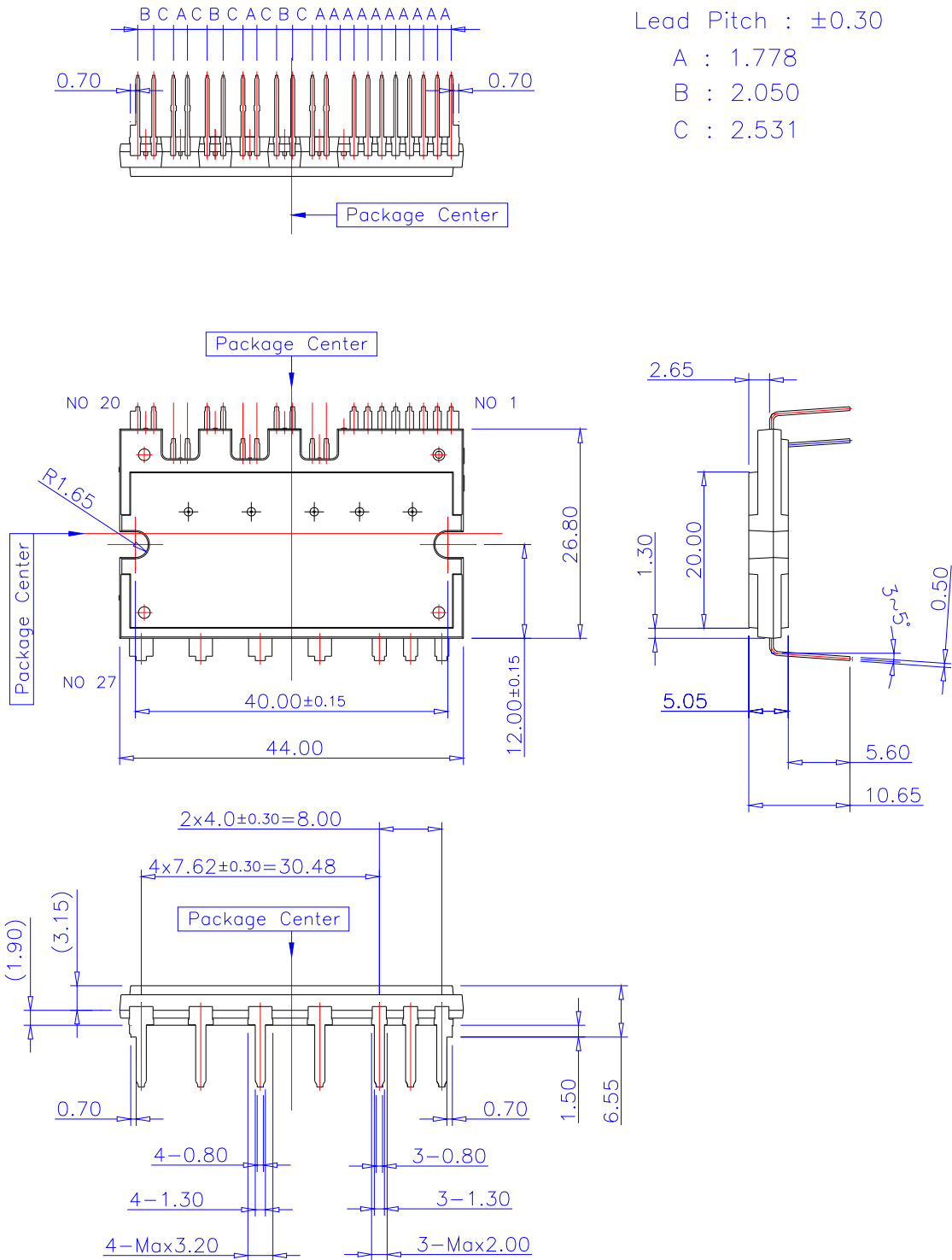


**Note:**

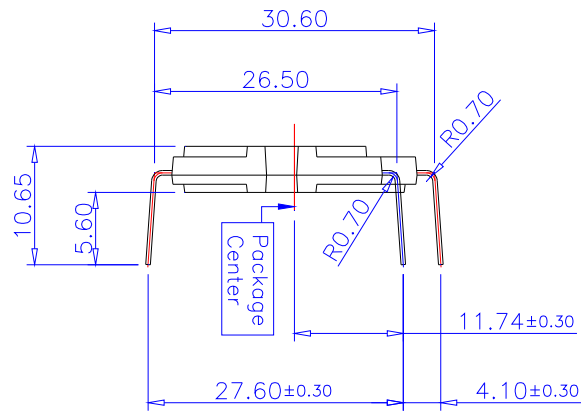
- 1) To avoid malfunction, the wiring of each input should be as short as possible. (less than 2 - 3cm)
- 2) By virtue of integrating an application specific type HVIC inside the Motion SPM® 3 product, direct coupling to CPU terminals without any opto - coupler or transformer isolation is possible.
- 3) VFO output is open collector type. This signal line should be pulled up to the positive side of the 5V power supply with approximately 4.7 kΩ resistance. Please refer to Figure11.
- 4) CSP15 of around 7 times larger than bootstrap capacitor CBS is recommended.
- 5) VFO output pulse width should be determined by connecting an external capacitor (CFOD) between CFOD (pin7) and COM (pin2). (Example: if CFOD = 33 nF, then tFO = 1.8 ms (typ.)) Please refer to the note 5 for calculation method.
- 6) Input signal is High - Active type. There is a 5 kΩ resistor inside the IC to pull down each input signal line to GND. RC coupling circuits should be adopted for the prevention of input signal oscillation. RS CPS time constant should be selected in the range 50 ~ 150 ns. CPS should not be less than 1 nF. (Recommended RS = 100 Ω, CPS = 1 nF)
- 7) To prevent errors of the protection function, the wiring around RF and CSC should be as short as possible.
- 8) In the short - circuit protection circuit, please select the RF CSC time constant in the range 1.5 ~ 2 μs.
- 9) Each capacitor should be mounted as close to the pins of the Motion SPM 3 product as possible.
- 10) To prevent surge destruction, the wiring between the smoothing capacitor and the P & GND pins should be as short as possible. The use of a high frequency non - inductive capacitor of around 0.1 ~ 0.22μF between the P & GND pins is recommended.
- 11) Relays are used at almost every systems of electrical equipments of home appliances. In these cases, there should be sufficient distance between the CPU and the relays.
- 12) CSPC15 should be over 1 μF and mounted as close to the pins of the Motion SPM 3 product as possible.

**Figure 13. Typical Application Circuit**

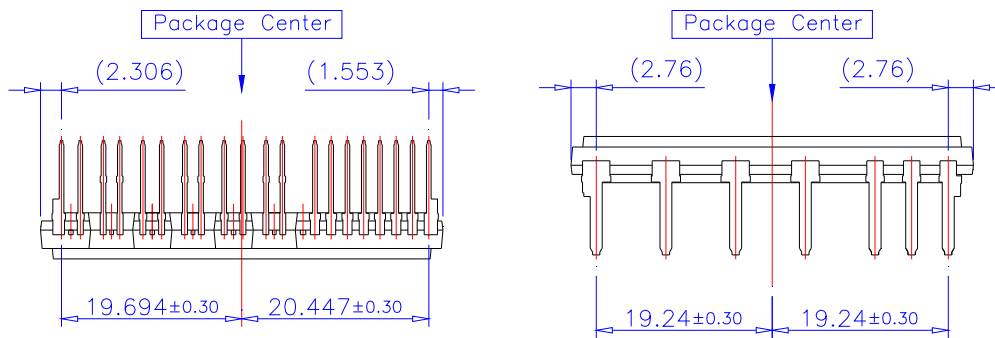
# Detailed Package Outline Drawings (FSBF10CH60BTL)



# Detailed Package Outline Drawings (FSBF10CH60BTL, Continued)

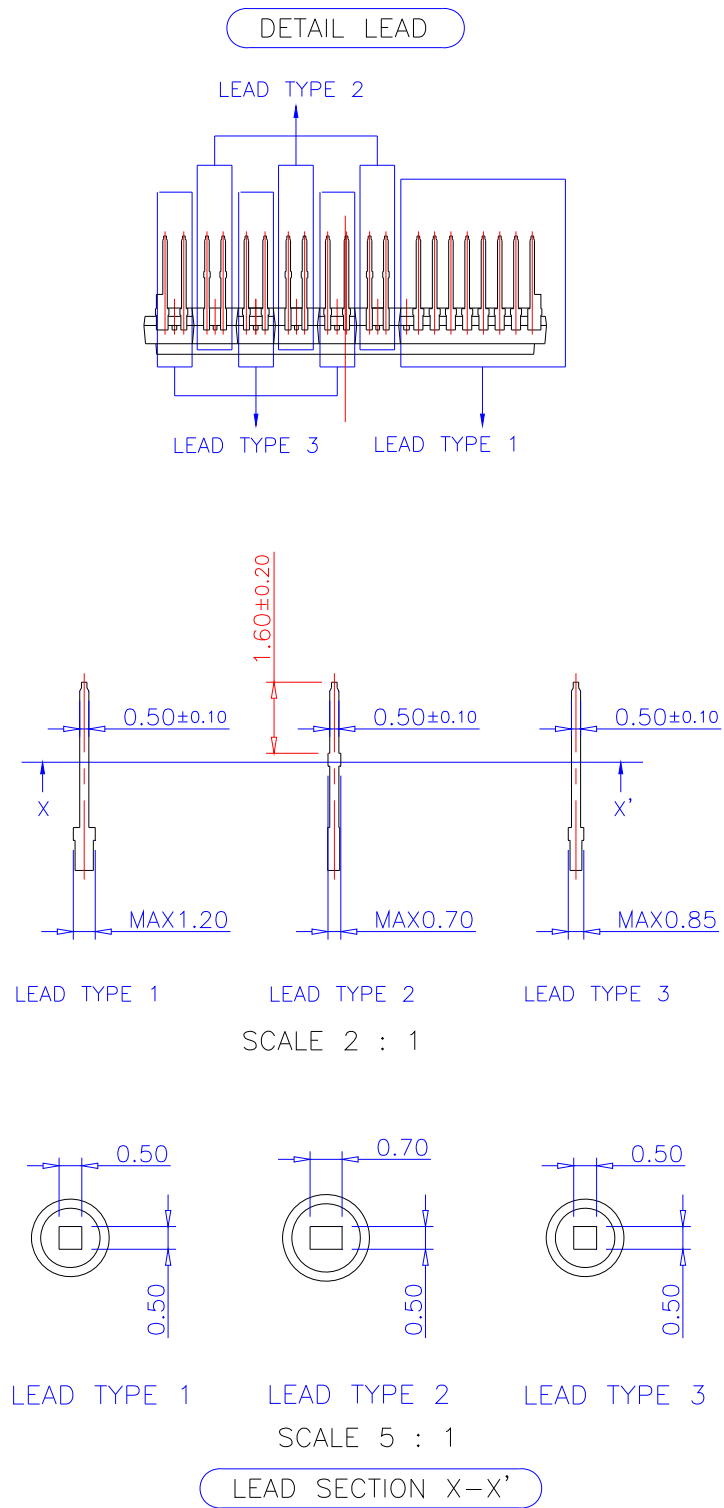


Lead Forming Dimension



PKG Center to Lead Distance


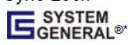



# Detailed Package Outline Drawings (FSBF10CH60BTL, Continued)





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CTL™	GTO™		TinyPWM™
Current Transfer Logic™	IntelliMAX™	Saving our world, 1mW/W/kW at a time™	TinyWire™
DEUXPEED®	ISOPLANAR™	SignalWise™	TranSiC™
Dual Cool™	Making Small Speakers Sound Louder and Better™	SmartMax™	TriFault Detect™
EcoSPARK®	MegaBuck™	SMART START™	TRUECURRENT®*
EfficientMax™	MICROCOUPLER™	Solutions for Your Success™	μSerDes™
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## PRODUCT STATUS DEFINITIONS

### Definition of Terms

Datasheet Identification	Product Status	Definition
Advance Information	Formative / In Design	Datasheet contains the design specifications for product development. Specifications may change in any manner without notice.
Preliminary	First Production	Datasheet contains preliminary data; supplementary data will be published at a later date. Fairchild Semiconductor reserves the right to make changes at any time without notice to improve design.
No Identification Needed	Full Production	Datasheet contains final specifications. Fairchild Semiconductor reserves the right to make changes at any time without notice to improve the design.
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