

FNA40560 Motion SPM[®] 45 Series

Features

- UL Certified No. E209204
- 600 V, 5 A 3 Phase IGBT Inverter Including Control ICs for Gate Drive and Protections
- Easy PCB Layout Thanks to The Built In Bootstrap Diodes and The Dedicated Vs Pins
- Three Separate Open Emitter Pins from Low Side IGBTs for Three Leg Current Sensing
- Single Grounded Power Supply with Bootstrap Operations
- Built In NTC Thermistor for Over Temperature Monitoring
- Isolation Rating of 2000 Vrms / min.

Applications

· Motion Control - Home Appliance / Industrial Motor

Related Resources

- AN 9070 : Motion SPM® 45 Series Users Guide
- AN 9071 : Motion SPM® 45 Series Thermal Performance Information
- AN 9072 : Motion SPM® 45 Series Mounting Guidance
- RD 344 : Reference Design (Three Shunt Solution)
- RD 345 : Reference Design (One Shunt Solution)

September 2013

General Description

FNA40560 Is A Motion SPM[®] 45 Series that Fairchild Has Newly Developed to Provide A Very Compact and High Performance Inverter Solution for AC Motor Drives in Low - Power Applications Such as Air Conditioners and Refrigerators. It Combines Low - Loss Short - Circuit Rated IGBTs and Optimized Gate Drivers in A Fully Isolated Package to Deliver A Simple and Robust Design. The System Reliability Is Further Enhanced by The Built - In NTC for Temperature Monitoring, Integrated Under -Voltage Lock - Out Function for Both High and Low Side, and An Over - Current Protection Input. Three Separate Open - Emitter Pins for Low Side IGBTs Make Three Leg Current Sensing Possible. Built - In Bootstrap Diodes and Dedicated VS Pins Make PCB Layout Easy.

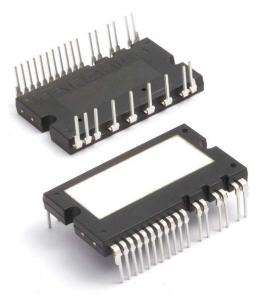


Figure 1. Package Overview

Package Marking and Ordering Information

Device Marking	Device	Package	Packing Type	Reel Size	Tape Width	Quantity
FNA40560	FNA40560	SPMAA - A26	RAIL	-	-	12

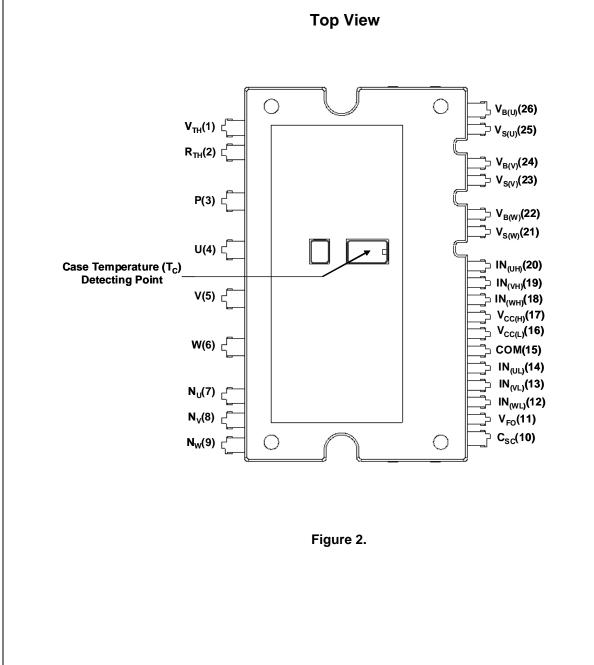
Integrated Power Functions

• 600 V - 5 A IGBT inverter for three - phase DC / AC power conversion (Please refer to Figure 3)

Integrated Drive, Protection and System Control Functions

- For inverter high side IGBTs: Gate drive circuit, High voltage isolated high speed level shifting
 Control circuit under voltage (UV) protection
- For inverter low side IGBTs: Gate drive circuit, Short circuit protection (SC)
 Control supply circuit under voltage (UV) protection
- Fault signaling: Corresponding to UV (low side supply) and SC faults
- Input interface: Active high interface, schmitt trigger input, can work with 3.3 / 5 V logic

Pin Configuration



FNA40560
Motion
SPM® 45
Series

Pin Number	Pin Name	Pin Description
1	V _{TH}	Thermistor Bias Voltage
2	R _{TH}	Series Resistor for the Use of Thermistor (Temperature Detection)
3	Р	Positive DC - Link Input
4	U	Output for U Phase
5	V	Output for V Phase
6	W	Output for W Phase
7	NU	Negative DC - Link Input for U Phase
8	N _V	Negative DC - Link Input for V Phase
9	N _W	Negative DC - Link Input for W Phase
10	C _{SC}	Capacitor (Low - Pass Filter) for Short - Current Detection Input
11	V _{FO}	Fault Output
12	IN _(WL)	Signal Input for Low - Side W Phase
13	IN _(VL)	Signal Input for Low - Side V Phase
14	IN _(UL)	Signal Input for Low - Side U Phase
15	СОМ	Common Supply Ground
16	V _{CC(L)}	Low - Side Common Bias Voltage for IC and IGBTs Driving
17	V _{CC(H)}	High - Side Common Bias Voltage for IC and IGBTs Driving
18	IN _(WH)	Signal Input for High - Side W Phase
19	IN _(VH)	Signal Input for High - Side V Phase
20	IN _(UH)	Signal Input for High - Side U Phase
21	V _{S(W)}	High - Side Bias Voltage Ground for W Phase IGBT Driving
22	V _{B(W)}	High - Side Bias Voltage for W Phase IGBT Driving
23	V _{S(V)}	High - Side Bias Voltage Ground for V Phase IGBT Driving
24	V _{B(V)}	High - Side Bias Voltage for V Phase IGBT Driving
25	V _{S(U)}	High - Side Bias Voltage Ground for U Phase IGBT Driving
26	V _{B(U)}	High - Side Bias Voltage for U Phase IGBT Driving

Internal Equivalent Circuit and Input/Output Pins V_{TH} (1) -^/// Thermister R_{TH} (2) P (3) (26) V_{B(} UVB (25) V_{S(U)} UVS OUT(UH) (24) V_B UVS U(4) VVB (23) V_{S(V} VVS (22) V_{B(W} ٨ WVB (21) V_{S(W)} wvs OUT(VH) ŧ (20) IN(UH) IN(UH) vvs V (5) (19) IN_(VH) IN(VH) (18) IN(WH) IN(WH) (17) V_{CC(H)} VCC OUT(WH) СОМ WVS W(6) (16) V_{CC(L)} vcc OUT(UL) (15) COM сом N_U (7) (14) IN(UL) IN(UL) (13) IN_(VL) IN(VL) (12) IN_{(W} OUT(VL) IN(WL) (11) V_{FO} N_V (8) VFO (10) C_{SC} C(SC) OUT(WL) N_W (9)

Note:

1) Inverter high - side is composed of three IGBTs, freewheeling diodes and one control IC for each IGBT.

2) Inverter low - side is composed of three IGBTs, freewheeling diodes and one control IC for each IGBT. It has gate drive and protection functions.3) Inverter power side is composed of four inverter dc - link input terminals and three inverter output terminals.

Figure 3.

Absolute Maximum Ratings (T_J = 25°C, Unless Otherwise Specified)

Inverter Part

Symbol	Parameter	Conditions	Rating	Unit
V _{PN}	Supply Voltage	Applied between P - N _U , N _V , N _W	450	V
V _{PN(Surge)}	Supply Voltage (Surge)	Applied between P - N _U , N _V , N _W	500	V
V _{CES}	Collector - Emitter Voltage		600	V
± I _C	Each IGBT Collector Current	$T_{C} = 25^{\circ}C, T_{J} < 150^{\circ}C$	5	А
± I _{CP}	Each IGBT Collector Current (Peak)	T_{C} = 25°C, $T_{J}<$ 150°C, Under 1 ms Pulse Width	10	A
P _C	Collector Dissipation	T _C = 25°C per One Chip	29	W
ТJ	Operating Junction Temperature	(Note 1)	- 40 ~ 150	°C

Note:

1. The maximum junction temperature rating of the power chips integrated within the Motion SPM[®] 45 product is 150°C.

Control Part

Symbol	Symbol Parameter Conditions		Rating	Unit
V _{CC}	Control Supply Voltage	Applied between V _{CC(H)} , V _{CC(L)} - COM	20	V
V _{BS}	High - Side Control Bias Voltage	Applied between $V_{B(U)}$ - $V_{S(U)}$, $V_{B(V)}$ - $V_{S(V)}$, $V_{B(W)}$ - $V_{S(W)}$	20	V
V _{IN}	Input Signal Voltage	$\begin{array}{llllllllllllllllllllllllllllllllllll$	- 0.3 ~ V _{CC} + 0.3	V
V _{FO}	Fault Output Supply Voltage	Applied between V _{FO} - COM	$-0.3 \sim V_{CC} + 0.3$	V
I _{FO}	Fault Output Current	Sink Current at V _{FO} pin	1	mA
V_{SC}	Current Sensing Input Voltage	Applied between C _{SC} - COM	$-0.3 \sim V_{CC} + 0.3$	V

Bootstrap Diode Part

Symbol	Parameter	Conditions	Rating	Unit
V _{RRM}	Maximum Repetitive Reverse Voltage		600	V
١ _F	Forward Current	$T_{C} = 25^{\circ}C, T_{J} < 150^{\circ}C$	0.50	А
I _{FP}	Forward Current (Peak)	T_{C} = 25°C, $T_{J}<$ 150°C, Under 1 ms Pulse Width	1.50	A
TJ	Operating Junction Temperature		- 40 ~ 150	°C

Total System

Symbol	Parameter	Conditions	Rating	Unit
V _{PN(PROT)}	Self Protection Supply Voltage Limit (Short Circuit Protection Capability)	V_{CC} = V_{BS} = 13.5 ~ 16.5 V T_J = 150°C, Non - repetitive, less than 2 μs	400	V
T _{STG}	Storage Temperature		- 40 ~ 125	°C
V _{ISO}	Isolation Voltage	60 Hz, Sinusoidal, AC 1 minute, Connection pins to heat sink plate	2000	V _{rms}

Thermal Resistance

Symbol	Parameter	Conditions	Min.	Тур.	Max.	Unit
R _{th(j-c)Q}	Junction to Case Thermal Resistance	Inverter IGBT part (per 1 / 6 module)	-	-	4.2	°C / W
R _{th(j-c)F}		Inverter FWD part (per 1 / 6 module)	-	-	5.9	°C / W

Note:

2. For the measurement point of case temperature (T_C), please refer to Figure 2.

Electrical Characteristics (T_J = 25°C, Unless Otherwise Specified)

Inverter Part

S	ymbol	Parameter	Conditions		Min.	Тур.	Max.	Unit
V	CE(SAT)	Collector - Emitter Saturation Voltage	V _{CC} = V _{BS} = 15 V V _{IN} = 5 V	I _C = 5 A, T _J = 25°C	-	1.7	2.2	V
	V _F	FWD Forward Voltage	V _{IN} = 0 V	I _F = 5 A, T _J = 25°C	-	1.8	2.3	V
HS	t _{ON}	Switching Times	$V_{PN} = 300 \text{ V}, \text{ V}_{CC} = \text{V}$	/ _{BS} = 15 V, I _C = 5 A	0.40	0.70	1.20	μS
	t _{C(ON)}		$T_J = 25^{\circ}C$ $V_{IN} = 0 V \leftrightarrow 5 V$, Inductive load (Note 3)		-	0.20	0.45	μS
	t _{OFF}				-	0.75	1.25	μS
	t _{C(OFF)}				-	0.25	0.50	μS
	t _{rr}				-	0.15	-	μS
LS	t _{ON}	Ī		$V_{PN} = 30 \text{ OV}, V_{CC} = V_{BS} = 15 \text{ V}, I_{C} = 5 \text{ A}$		0.70	1.20	μS
	t _{C(ON)}		$T_J = 25^{\circ}C$ $V_{IN} = 0 V \leftrightarrow 5 V$, Indu	uctive load	-	0.20	0.45	μS
	t _{OFF}		(Note 3)		-	0.75	1.25	μS
	t _{C(OFF)}				-	0.25	0.50	μS
	t _{rr}				-	0.15	-	μS
	I _{CES}	Collector - Emitter Leakage Current	$V_{CE} = V_{CES}$		-	-	1	mA

Note:

3. t_{ON} and t_{OFF} include the propagation delay time of the internal drive IC. t_{C(ON)} and t_{C(OFF)} are the switching time of IGBT itself under the given gate driving condition internally. For the detailed information, please see Figure 4.

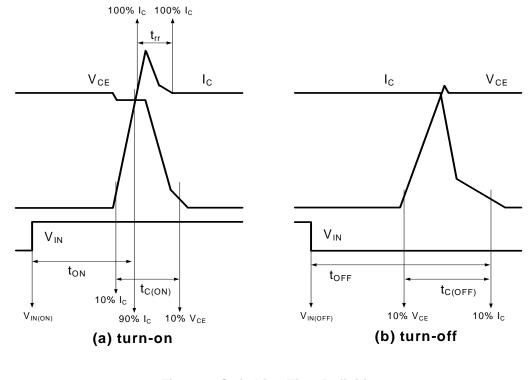
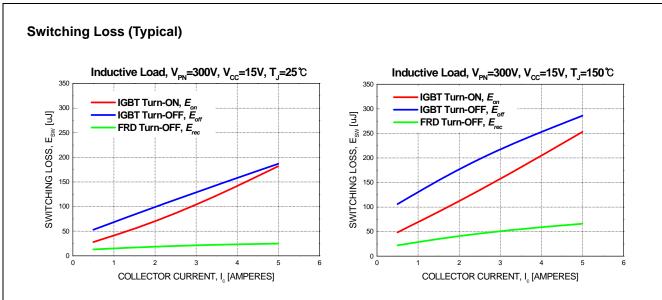


Figure 4. Switching Time Definition





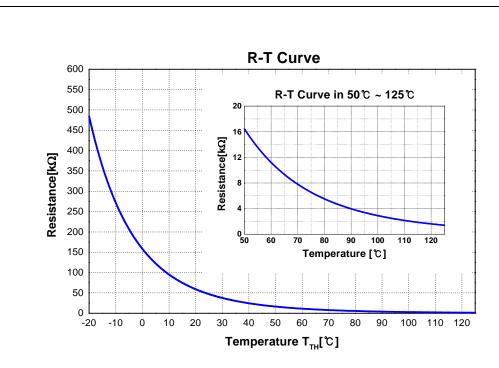
Control Part

Symbol	Parameter	Conditions		Min.	Тур.	Max.	Unit
I _{QCCH}	Quiescent V _{CC} Supply	V _{CC(H)} = 15 V, IN _(UH,VH,WH) = 0 V	V _{CC(H)} - COM	-	-	0.10	mA
IQCCL	Current	$V_{CC(L)} = 15 \text{ V}, \text{ IN}_{(UL,VL, WL)} = 0 \text{ V}$	V _{CC(L)} - COM	-	-	2.65	mA
I _{PCCH}	Operating V _{CC} Supply Current	$V_{CC(H)}$ = 15 V, f _{PWM} = 20 kHz, duty = 50%, applied to one PWM signal input for high - side	V _{CC(H)} - COM	-	-	0.15	mA
I _{PCCL}		$V_{CC(L)}$ = 15 V, f_{PWM} = 20 kHz, duty = 50%, applied to one PWM signal input for low - side	V _{CC(L)} - COM	-	-	3.65	mA
I _{QBS}	Quiescent V _{BS} Supply Current	$V_{BS} = 15 \text{ V}, \text{ IN}_{(UH, VH, WH)} = 0 \text{ V}$	V _{B(U)} - V _{S(U)} , V _{B(V)} - V _{S(V)} , V _{B(W)} - V _{S(W)}	-	-	0.30	mA
I _{PBS}	Operating V _{BS} Supply Current	$V_{CC} = V_{BS} = 15 \text{ V}, f_{PWM} = 20 \text{ kHz},$ duty = 50%, applied to one PWM signal input for high - side		-	-	2.00	mA
V _{FOH}	Fault Output Voltage	V_{SC} = 0 V, V_{FO} Circuit: 10 k Ω to 5 V Pull - up		4.5	-	-	V
V _{FOL}		V_{SC} = 1 V, V_{FO} Circuit: 10 k Ω to 5 V	/ Pull - up	-	-	0.5	V
V _{SC(ref)}	Short Circuit Trip Level	V _{CC} = 15 V (Note 4)		0.45	0.5	0.55	V
UV _{CCD}		Detection level		10.5	-	13.0	V
UV _{CCR}	Supply Circuit Under - Voltage	Reset level		11.0	-	13.5	V
UV_BSD	Protection	Detection level		10.0	-	12.5	V
UV _{BSR}		Reset level		10.5	-	13.0	V
t _{FOD}	Fault - Out Pulse Width			30	-	-	μs
V _{IN(ON)}	ON Threshold Voltage	Applied between IN(UH), IN(VH), II	$N_{(WH)}$, $IN_{(UL)}$, $IN_{(VL)}$,	-	-	2.6	V
V _{IN(OFF)}	OFF Threshold Voltage	IN _(WL) - COM		0.8	-	-	V
R _{TH}	Resistance of	@T _{TH} = 25°C, (Note 5)		-	47	-	kΩ
	Thermister	@T _{TH} = 100°C		-	2.9	-	kΩ

Note:

4. Short - circuit current protection is functioning only at the low - sides.

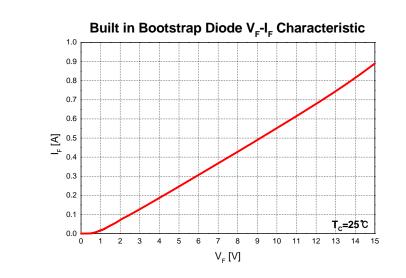
5. T_{TH} is the temperature of thermister itselt. To know case temperature (T_C), please make the experiment considering your application.





Bootstrap Diode Part

Symbol	Parameter	Conditions	Min.	Тур.	Max.	Unit
V _F	Forward Voltage	I _F = 0.1 A, T _C = 25°C	-	2.5	-	V
t _{rr}	Reverse Recovery Time	I _F = 0.1 A, T _C = 25°C	-	80	-	ns



Note:

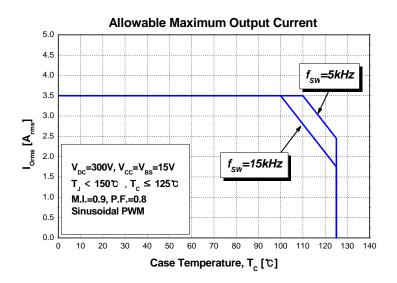
6. Built in bootstrap diode includes around 15 $\,\Omega\,$ resistance characteristic.



Symbol	Deremeter	Conditions		Value		
Symbol	Parameter	Conditions	Min.	Тур.	Max.	Unit
V _{PN}	Supply Voltage	Applied between P - N _U , N _V , N _W	-	300	400	V
V _{CC}	Control Supply Voltage	Applied between V _{CC(H)} , V _{CC(L)} - COM	13.5	15	16.5	V
V_{BS}	High - Side Bias Voltage	Applied between V_B(U) - V_S(U), V_B(V) - V_S(V), V_B(W) - V_S(W)	13.0	15	18.5	V
dV _{CC} / dt, dV _{BS} / dt	Control supply variation		- 1	-	1	V / μs
t _{dead}	Blanking Time for Preventing Arm - Short	For each input signal	1.5	-	-	μs
f _{PWM}	PWM Input Signal	$-40^{\circ}C < T_{J} < 150^{\circ}C$	-	-	20	kHz
V_{SEN}	Voltage for Current Sensing	Applied between N _U , N _V , N _W - COM (Including surge voltage)	- 4		4	V
P _{WIN(ON)}	Minimun Input Pulse	(Note 7)	0.5	-	-	μs
P _{WIN(OFF)}	Width		0.5	-	-	1

Note:

7. This product might not make response if input pulse width is less than the recommanded value.

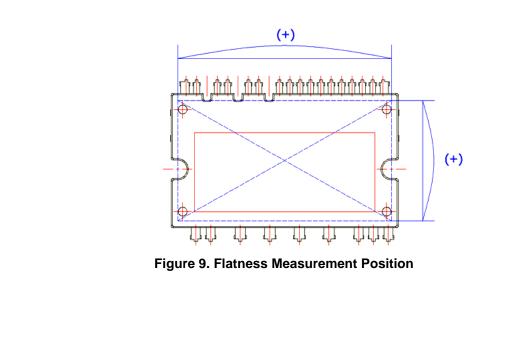


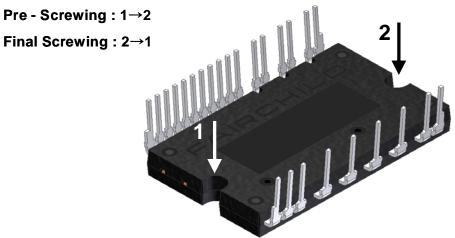
Note:

8. This allowable output current value is the reference data for the safe operation of this product. The allowable output current value may be different from the actual application.

Figure 8. Allowable Maximum Output Current

Parameter	Conditions Note Figure 9		Limits			Unit
			Min.	Тур.	Max.	Unit
Device Flatness			0	-	+ 120	μm
Mounting Torque	Mounting Screw: - M3	Recommended 0.7 N • m	0.6	0.7	0.8	N • m
	Note Figure 10	Recommended 7.1 kg • cm	6.2	7.1	8.1	kg • cm
Weight		•	-	11	-	g

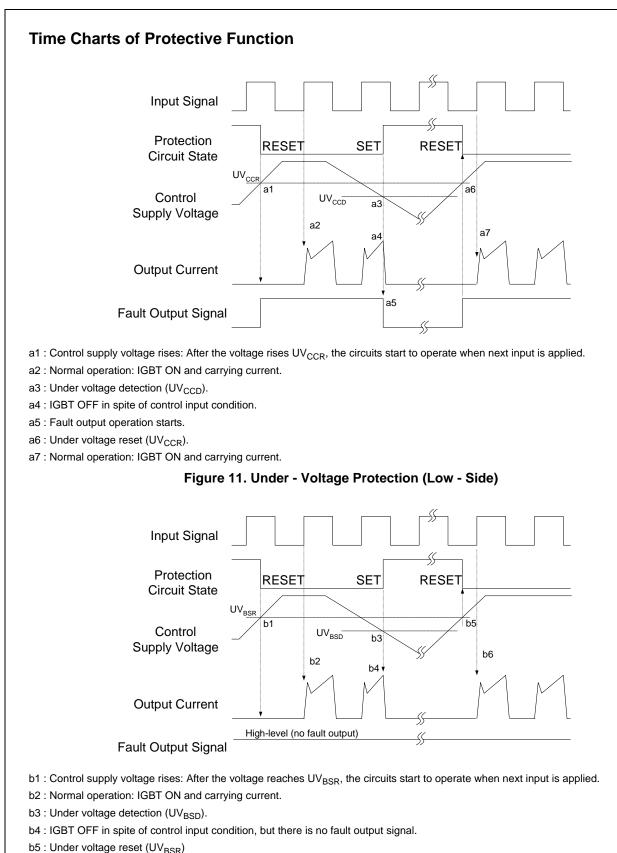




Note:

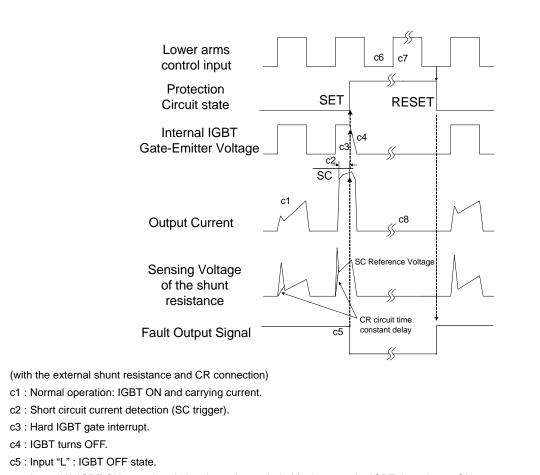
9. Do not make over torque when mounting screws. Much mounting torque may cause ceramic cracks, as well as bolts and Al heat - sink destruction.
10. Avoid one side tightening stress. Figure 10 shows the recommended torque order for mounting screws. Uneven mounting can cause the ceramic substrate of the Motion SPM[®] 45 product to be damaged. The Pre - Screwing torque is set to 20 ~ 30% of maximum torque rating.





b6 : Normal operation: IGBT ON and carrying current

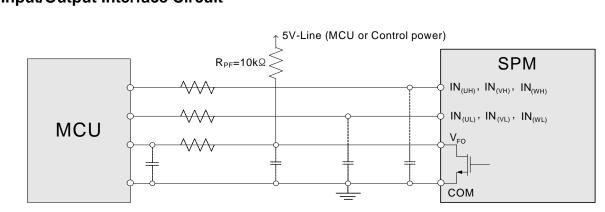
Figure 12. Under - Voltage Protection (High - Side)



c6 : Input "H": IGBT ON state, but during the active period of fault output the IGBT doesn't turn ON.

c7 : IGBT OFF state





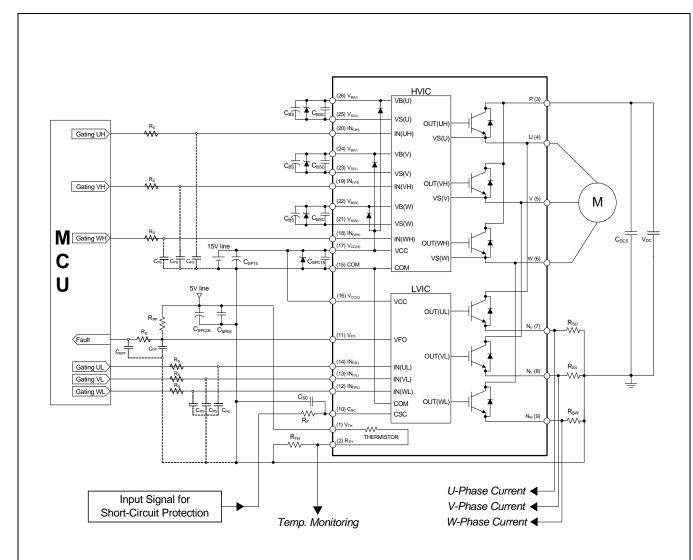
Input/Output Interface Circuit

Note:

1) RC coupling at each input (parts shown dotted) might change depending on the PWM control scheme used in the application and the wiring impedance of the application's printed circuit board. The input signal section of the Motion SPM[®] 45 product integrates 5 kΩ (typ.) pull - down resistor. Therefore, when using an external filtering resistor, please pay attention to the signal voltage drop at input terminal.

2) The logic input is compatible with standard CMOS outputs.

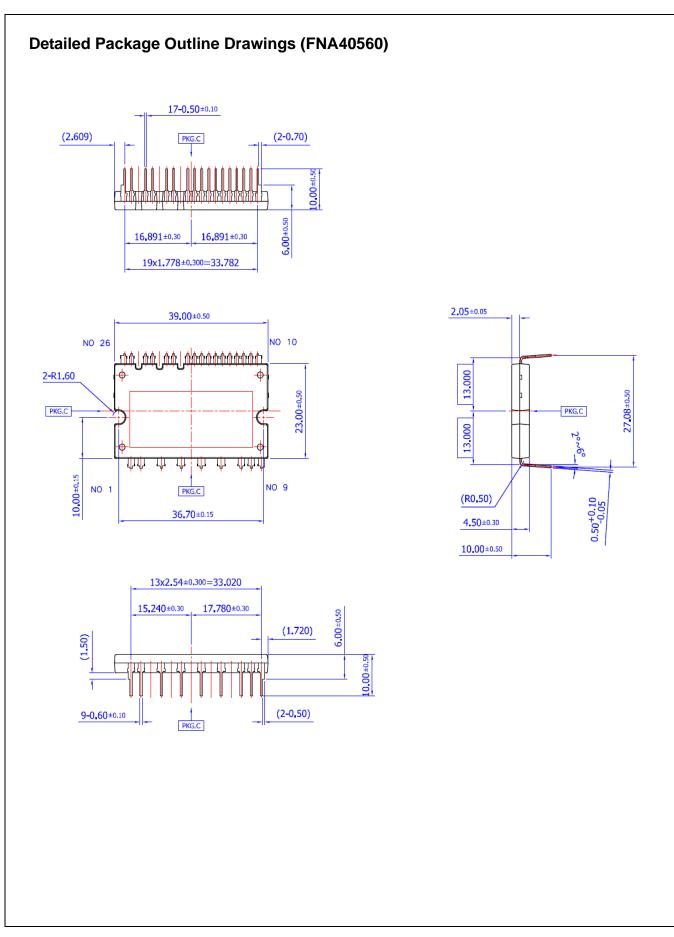
Figure 14. Recommended CPU I/O Interface Circuit



Note:

- 1) To avoid malfunction, the wiring of each input should be as short as possible. (less than 2 3 cm)
- 2) By virtue of integrating an application specific type HVIC inside the Motion SPM[®] 45 product, direct coupling to CPU terminals without any opto coupler or transformer isolation is possible.
- 3) V_{FO} output is open drain type. This signal line should be pulled up to the positive side of the MCU or control power supply with a resistor that makes I_{FO} up to 1 mA. Please refer to Figure 14.
- 4) C_{SP15} of around 7 times larger than bootstrap capacitor C_{BS} is recommended.
- 5) Input signal is High Active type. There is a 5 kΩ resistor inside the IC to pull down each input signal line to GND. RC coupling circuits is recommanded for the prevention of input signal oscillation. R_SC_{PS} time constant should be selected in the range 50 ~ 150 ns. (Recommended R_S = 100 Ω, C_{PS} = 1 nF)
- 6) To prevent errors of the protection function, the wiring around R_F and C_{SC} should be as short as possible.
- 7) In the short circuit protection circuit, please select the R_FC_{SC} time constant in the range 1.5 ~ 2 μ s.
- 8) Each capacitor should be mounted as close to the pins of the SPM as possible.
- 9) To prevent surge destruction, the wiring between the smoothing capacitor and the P & GND pins should be as short as possible. The use of a high frequency non inductive capacitor of around 0.1 ~ 0.22 μF between the P & GND pins is recommended.
- 10) Relays are used at almost every systems of electrical equipments of home appliances. In these cases, there should be sufficient distance between the CPU and the relays.
- 11) The zener diode should be adopted for the protection of ICs from the surge destruction between each pair of control supply terminals. (Recommanded zener diode = 22 V / 1 W)
- 12) Please choose the electrolytic capacitor with good temperature characteristic in C_{BS}. Also, choose 0.1 ~ 0.2 µF R category ceramic capacitors with good temperature and frequency characteristics in C_{BSC}.
- 13) For the detailed information, please refer to the AN 9070, AN 9071, AN 9072, RD 344, and RD 345.

Figure 15. Typical Application Circuit



FNA40560 Motion SPM® 45 Series

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Definition	of Terms
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Preliminary	First Production	Datasheet contains preliminary data; supplementary data will be published at a later date. Fairchild Semiconductor reserves the right to make changes at any time without notice to improve design.
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