

Reference Manual

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VL-EBX-37 (Mamba)

Intel Core 2 Duo SBC with
Video, Ethernet, USB, Serial,
SATA, Audio, Analog + Digital
I/O, PCIe Mini Card, eUSB, and
SPX



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Product Release Notes

Models S and E

Rev 1.0x – Commercial Release.

Rev 0.1x – Engineering build.

Models A and F

Rev 1.0x – Commercial Release. First dual-LVDS models. BIOS revision 6.5.102 release.

Support Page

The VL-EBX-37 support page, at <http://www.versalogic.com/private/mambasupport.asp>, contains additional information and resources for this product including:

- Reference Manual (PDF format)
- Operating system information and software drivers
- Data sheets and manufacturers' links for chips used in this product
- Photograph of the circuit board
- BIOS information and upgrades

This is a private page for VL-EBX-37 users that can be accessed only by entering this address directly. It cannot be reached from the public VersaLogic website.

The VersaTech KnowledgeBase is an invaluable resource for resolving technical issues with your VersaLogic product.

[VersaTech KnowledgeBase](#)

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Description

The VL-EBX-37 is a feature-packed single board computer designed for OEM control projects requiring fast processing, industrial I/O, flexible memory options and designed-in reliability and longevity (product lifespan). Its features include:

- Intel Core 2 Duo 2.26 GHz, 1066 MHz FSB, 3 MB L2 cache
- Up to 8 GB DDR3 socketed memory, two SO-DIMMs
- Two Intel 82574IT-based Ethernet interfaces, autodetect 10BaseT / 100BaseTX / 1000BaseT
- Intel GMA 4500 MHD graphics core
- Two RS-232 (115 Kbps max.) and two RS-232/422/ 485 COM ports (921 Kbps max.)
- Two SATA ports, 3 Gb/s
- Industrial I/O
 - 12-bit analog inputs and outputs
 - Eight analog (and eight optional) inputs
 - Four analog (and four optional) outputs
 - Thirty-two digital I/O lines
- Six USB 2.0 ports
- One eUSB bootable flash interface
- One PCI Express Mini Card socket
- SPX interface supports up to four external SPI devices either of user design or any of the SPX™ series of expansion boards, with clock frequencies from 1-8 MHz
- Intel High Definition Audio (HDA) compatible
- PS/2 keyboard and mouse support
- PC/104-*Plus* (PCI + ISA) expansion
- TVS devices for ESD protection
- CPU temperature sensor
- EBX standard 5.75" x 8.00" footprint
- Field-upgradeable BIOS with OEM enhancements
- Customization available

The VL-EBX-37 is an EBX single board computer with an Intel Core 2 Duo processor. The board is compatible with a variety of popular operating systems including Windows, Windows Embedded, Linux, VxWorks and QNX.

The VL-EBX-37 features high-reliability design and construction, including voltage sensing reset circuits and self-resetting fuses on the +5V and +3.3V supplies to the user I/O connectors.

VL-EBX-37 boards are subjected to 100% functional testing and are backed by a limited two-year warranty. Careful parts sourcing and US-based technical support ensure the highest possible quality, reliability, service and product longevity for this exceptional SBC.

The VL-EBX-37 is equipped with a multifunction utility cable (breakout board) that provides standard I/O interfaces, including four COM ports, PS/2 mouse and keyboard, pushbutton reset, programmable LED and speaker. Additional I/O expansion is available through the stackable PCI and ISA connectors, PCI Express Mini Card socket, and SPX expansion interface.

Technical Specifications

Specifications are typical at +25°C with +5V supply unless otherwise noted. Typical power is computed as the mean value of the Idle and Maximum power specifications. All power specifications represent operation at +25°C with +5V supply running Windows XP with 1 GB RAM, dual Ethernet, keyboard, and mouse. Maximum power is measured with 95% CPU utilization.

Board Size:

EBX standard: 5.75" x 8" (146 mm x 203 mm)

Storage Temperature:

-40°C to 85°C

Operating Temperature:

VL-EBX-37S, A: 0°C to +60°C with heatsink/fan
VL-EBX-37E, F: -40°C to +85°C with heatsink/fan

Power Requirements: (+5V with 1 GB RAM, two network connections, keyboard, mouse, and VGA running Windows XP)

VL-EBX-37S, A: Idle 2.4A (12W), Max 5A (25W)
VL-EBX-37E, F: Idle 2.2A (11W), Max 3.5A (17.5W)

+3.3V or ±12V might be required by some expansion modules

System Reset:

- Major power rails monitored by Super I/O chip
- CPU and base board temperature monitoring
- Fan monitor

DRAM:

Two SO-DIMM sockets, up to 8 GB DDR3
Dual function memory and solid state drive (SSDDR3) capability at SO-DIMM 1 (J13)

Video Interface:

Intel GMA 4500 MHD graphics core
Analog output for VGA
LVDS (one or two ports) output for TFT FPDs
Up to 1920x1200 (24 bits)
Up to 64 MB shared DRAM pre-allocated plus up to 1700 MB using Intel DVMT

SATA Interface:

Two SATA 3 Gb/s ports

Flash Interface:

USB SSD interface (eUSB)
PCIe Mini Card socket

Ethernet Interface:

Two Intel 82574IT based 10BaseT / 100BaseTX / 1000BaseT Ethernet Controllers

Analog Input:

8 or 16-channel, 12-bit, single-ended, 100 Ksps, channel independent input range: ±5, ±10, or unipolar 0 to +5V or 0 to +10V

Analog Output:

4 or 8 -channel, 12-bit, single-ended, 100 Ksps, 0 to 4.096V

COM1/2 Interface:

RS-232, 16C550 compatible, 115 kbps max., full 9-wire

COM3/4 Interface:

RS-232/422/485, 16C550 compatible, 921 Kbps max., 4-wire RS-232

USB:

Eight USB 2.0. Six USB type A ports (on-board), one channel on eUSB, and one on PCIe Mini Card

Audio:

HD audio CODEC
Stereo Line In and Stereo Line Out

SPX:

Supports four external SPI chips of user design or any SPX series expansion board

BIOS:

Phoenix Embedded BIOS© with StrongFrame® Technology and OEM enhancements
Field upgradeable with Flash BIOS Update Utility

Bus Speed:

CPU FSB: VL-EBX-37S: 1.066 GHz;
VL-EBX-37E: 800 MHz
DDR3: VL-EBX-37S: 1066 MT/s;
VL-EBX-37E: 800 MT/s
USB 2.0: 480 Mbps
LPC: 33.33 MHz
PC/104 (ISA): 8.33 MHz
SPX: 8 MHz max.

Compatibility:

PC/104 – Partial compliance
PC/104-Plus

Weight: (no memory installed)

VL-EBX-37S – 0.834 lbs (0.378 kg)
VL-EBX-37E – 0.832 lbs (0.377 kg)
VL-EBX-37A – 0.821 lbs (0.372 kg)
VL-EBX-37F – 0.828 lbs (0.375 kg)

Specifications are subject to change without notification.

VL-EBX-37 Block Diagram

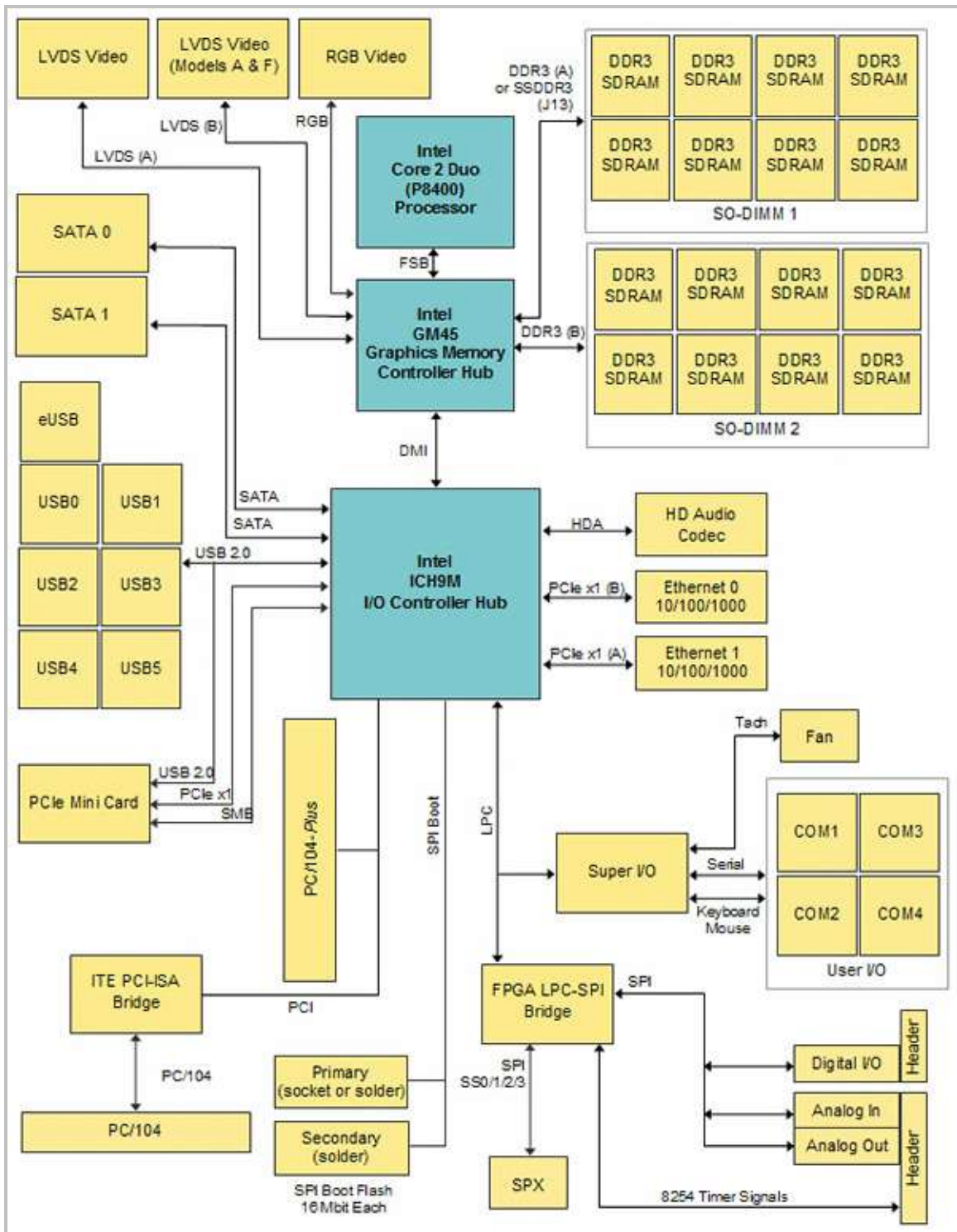


Figure 1. VL-EBX-37 Block Diagram

Thermal Considerations

CPU DIE TEMPERATURE

The CPU die temperature is affected by numerous conditions, such as CPU utilization, CPU speed, ambient air temperature, air flow, thermal effects of adjacent circuit boards, external heat sources, and many others.

The CPU is protected from over-temperature conditions by several mechanisms.

The CPU will automatically slow down by 50% whenever its die temperature exceeds +105°C. When the temperature falls back below +105°C, the CPU resumes full-speed operation.

As a failsafe, if the CPU die temperature climbs above +115°C, the CPU will turn itself off to prevent damage to the chip. Note that Intel does not warrant their CPUs in the event of this occurrence.

MODEL DIFFERENCES

VersaLogic offers both commercial and industrial temperature models of the VL-EBX-37. The basic operating temperature specification for both models is shown below.

- VL-EBX-37S, A: 0°C to +60°C free air, no airflow
- VL- EBX-37E, F: -40°C to +85°C free air

To reliably function at extreme temperatures the extended temperature model specifications deviate from the standard model in the following ways:

- The DRAM interface is slowed. PC3-6400 memory runs at 600 MHz. PC3-8500 memory runs at 800 MHz.
- The DRAM refresh rates are doubled.
- The Front Side Bus speed is reduced to 800 MHz.
- Maximum processor speed is limited to 1200 MHz.
- The graphics core is limited to 400 MHz.

RoHS-Compliance

The VL-EBX-37 is RoHS compliant.

ABOUT RoHS

In 2003, the European Union issued Directive 2002/95/EC regarding the Restriction of the use of certain Hazardous Substances (RoHS) in electrical and electronic equipment.

The RoHS directive requires producers of electrical and electronic equipment to reduce to acceptable levels the presence of six environmentally sensitive substances: lead, mercury, cadmium, hexavalent chromium, and the presence of polybrominated biphenyls (PBB) and polybrominated diphenyl ethers (PBDE) flame retardants, in certain electrical and electronic products sold in the European Union (EU) beginning July 1, 2006.

VersaLogic Corp. is committed to supporting customers with high-quality products and services meeting the European Union's RoHS directive.

Warnings

ELECTROSTATIC DISCHARGE

Warning! Electrostatic discharge (ESD) can damage circuit boards, disk drives and other components. The circuit board must only be handled at an ESD workstation. If an approved station is not available, some measure of protection can be provided by wearing a grounded antistatic wrist strap. Keep all plastic away from the board and do not slide the board over any surface.

After removing the board from its protective wrapper, place the board on a grounded, static-free surface, component side up. Use an antistatic foam pad if available.

The board should also be protected inside a closed metallic anti-static envelope during shipment or storage.

Note The exterior coating on some metallic antistatic bags is sufficiently conductive to cause excessive battery drain if the bag comes in contact with the bottom-side of the VL-EBX-37.

LITHIUM BATTERY

Warning! To prevent shorting, premature failure or damage to the lithium battery, do not place the board on a conductive surface such as metal, black conductive foam or the outside surface of a metalized ESD protective pouch. The lithium battery may explode if mistreated. Do not recharge, disassemble or dispose of in fire. Dispose of used batteries promptly and in an environmentally suitable manner.

HANDLING CARE

Warning! Care must be taken when handling the board not to touch the exposed circuitry with your fingers. Though it will not damage the circuitry, it is possible that small amounts of oil or perspiration on the skin could have enough conductivity to cause the contents of CMOS RAM to become corrupted through careless handling, resulting in CMOS resetting to factory defaults.

EARTH GROUND REQUIREMENT

Warning! All mounting standoffs (eight on EBX and EPIC boards, four on PC/104 boards) should be connected to earth ground (chassis ground). This provides proper grounding for ESD and EMI purposes.

Technical Support

If you are unable to solve a problem after reading this manual, please visit the VL-EBX-37 Product Support web page below. The support page provides links to component datasheets, device drivers, and BIOS and PLD code updates.

[VL-EBX-37 Support Page](#)

The VersaTech KnowledgeBase contains a wealth of technical information about VersaLogic products, along with product advisories. Click the link below to see all KnowledgeBase articles related to the VL-EBX-37.

[VersaTech KnowledgeBase](#)

If you have further questions, contact VersaLogic Technical Support at (503) 747-2261. VersaLogic support engineers are also available via e-mail at Support@VersaLogic.com.

REPAIR SERVICE

If your product requires service, you must obtain a Returned Material Authorization (RMA) number by calling (503) 747-2261.

Please provide the following information:

- Your name, the name of your company, your phone number, and e-mail address
- The name of a technician or engineer that can be contacted if any questions arise
- Quantity of items being returned
- The model and serial number (barcode) of each item
- A detailed description of the problem
- Steps you have taken to resolve or recreate the problem
- The return shipping address

Warranty Repair All parts and labor charges are covered, including return shipping charges for UPS Ground delivery to United States addresses.

Non-warranty Repair All non-warranty repairs are subject to diagnosis and labor charges, parts charges and return shipping fees. Please specify the shipping method you prefer and provide a purchase order number for invoicing the repair.

Note: Please mark the RMA number clearly on the outside of the box before returning.

Initial Configuration

The following components are recommended for a typical development system.

- VL-EBX-37 computer
- ATX power supply
- LVDS display
- USB keyboard
- USB mouse
- SATA hard drive
- USB CD-ROM drive
- DDR3 DRAM SO-DIMM module

The following VersaLogic cables are recommended.

- VL-CBR-2010, 2011, or 2012 – LVDS cable
- VL-CBR-0701 – SATA data cable
- VL-CBR-0401 – ATX to SATA power cable
- VL-CBR-2022 – Main power cable

You will also need a Windows (or other OS) installation CD.

Basic Setup

The following steps outline the procedure for setting up a typical development system. The VL-EBX-37 should be handled at an ESD workstation or while wearing a grounded antistatic wrist strap.

Before you begin, unpack the VL-EBX-37 and accessories. Verify that you received all the items you ordered. Inspect the system visually for any damage that may have occurred in shipping. Contact Support@VersaLogic.com immediately if any items are damaged or missing.

Gather all the peripheral devices you plan to attach to the VL-EBX-37 and their interface and power cables.

It is recommended that you attach standoffs to the board (see Hardware Assembly) to stabilize the board and make it easier to work with.

Figure 2 shows a typical start-up configuration.

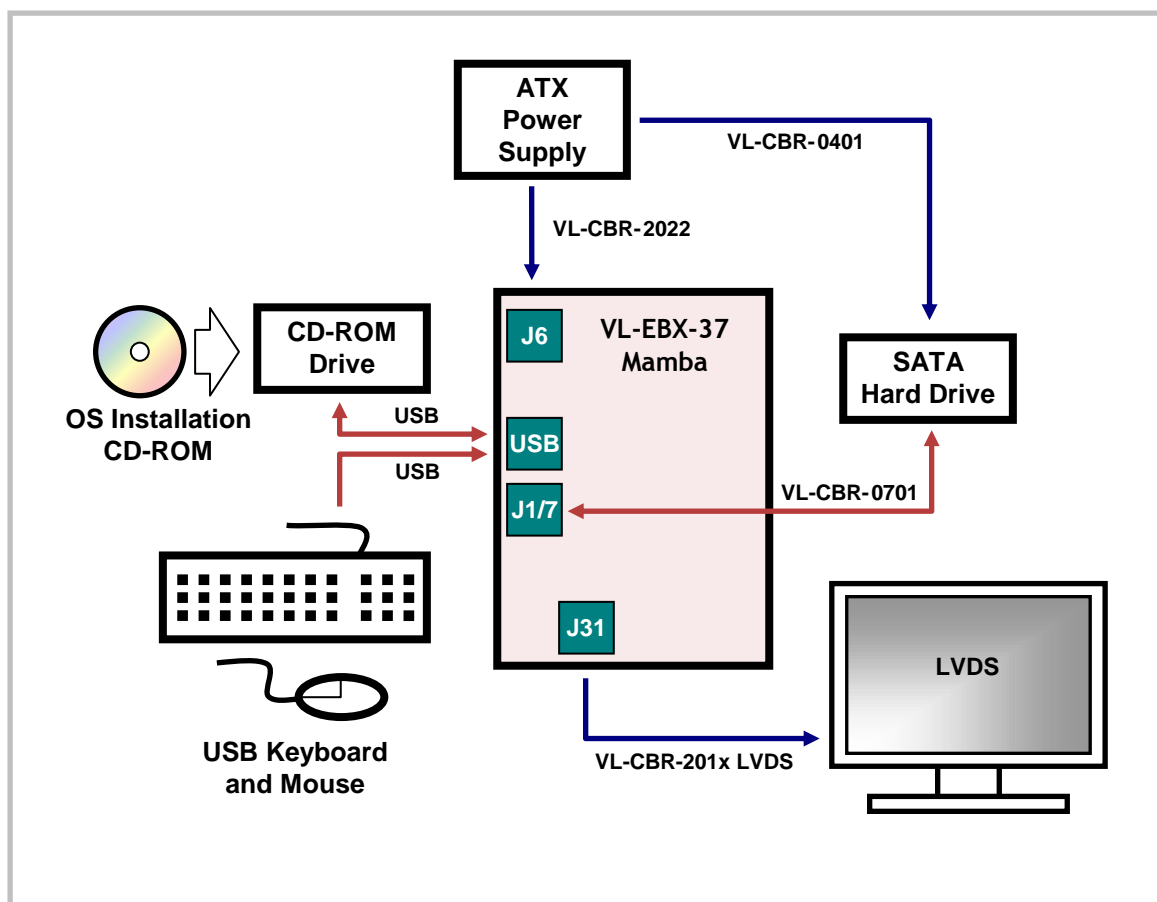


Figure 2. Typical Start-up Configuration

1. Install Memory

- Insert DDR3 DRAM module(s) into SO-DIMM sockets J13 and J29 and latch them into place. If you install only one module, you must install it in the top socket, J13. If you use DDR3 DRAM combined with a solid state drive (SSDDR3), you must install it in socket J13.

2. Attach Cables and Peripherals

- Plug the LVDS adapter cable VL-CBR-201x into socket J31 on the bottom of the board. Attach the adapter cable to the LVDS display. (On models A and F, socket J33 can alternately be used.)
- Plug the USB CD-ROM drive, keyboard, and mouse into on-board USB ports (J2, J3, J4, J8, J9, or J10).
- Plug the SATA data cable VL-CBR-0701 into socket J1 or J7, and attach the SATA hard drive to the cable.
- Attach the ATX SATA power cable (VL-CBR-0401) to the ATX power supply and to the SATA hard drive.

3. Attach Power

- Plug the power adapter cable VL-CBR-2022 into connector J6. Attach the motherboard connector of the ATX power supply to the adapter.

4. Review Configuration

- Before you power up the system, double check all the connections. Make sure all cables are oriented correctly and that adequate power will be supplied to the VL-EBX-37 and peripheral devices.

5. Power On

- Turn on the ATX power supply and the flat panel display. If the system is correctly configured, a video signal should be present.

6. Select a Boot Drive

- During startup, press the B key to display the boot menu. Insert the OS installation CD in the CD-ROM drive, and select to boot from the CD-ROM drive.

7. Install Operating System

- Install the operating system according to the instructions provided by the OS manufacturer. (See Operating System Installation.)

Note If you intend to operate the VL-EBX-37 under Windows XP or Windows XP Embedded, be sure to use Service Pack 3 (SP3) and all updates for full support of the latest hardware features.

CMOS Setup

See VersaLogic KnowledgeBase article [VT1665 - EBX-37 Mamba CMOS Setup Reference](#) for complete information about the CMOS Setup parameters.

Operating System Installation

The standard PC architecture used on the VL-EBX-37 makes the installation and use of most of the standard x86 processor-based operating systems very simple. The operating systems listed on the [VersaLogic OS Compatibility Chart](#) use the standard installation procedures provided by the maker of the OS. Special optimized hardware drivers for a particular operating system, or a link to the drivers, are available at the VL-EBX-37 Product Support web page at <http://www.versalogic.com/private/Mambasupport.asp>.

Dimensions and Mounting

The VL-EBX-37 complies with all EBX standards which provide for specific mounting hole and PC/104-Plus stack locations as shown in the diagram below.

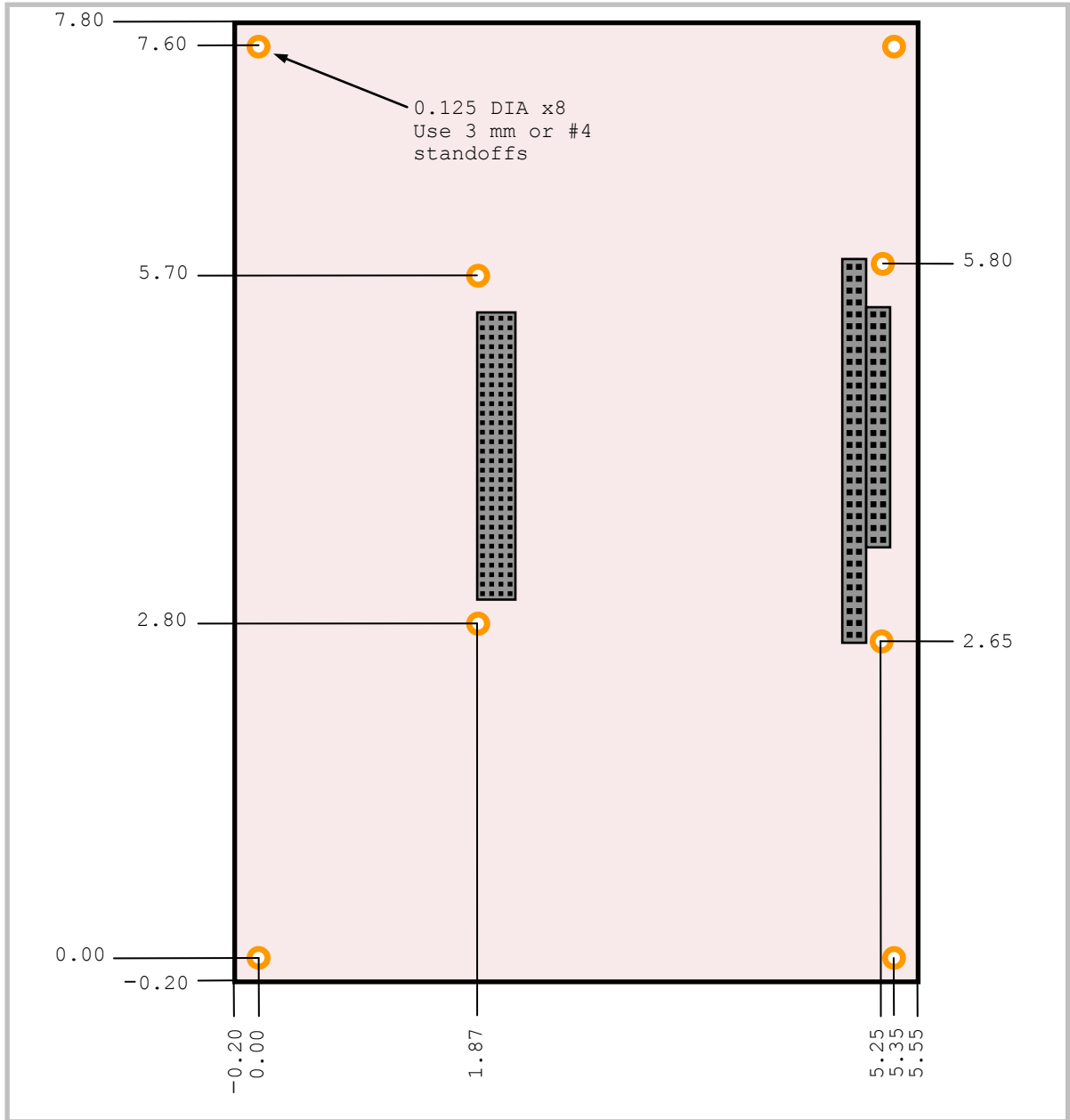


Figure 3. VL-EBX-37 Dimensions and Mounting Holes
(Not to scale. All dimensions in inches.)

Caution The VL-EBX-37 must be supported at all eight mounting points to prevent excessive flexing when expansion modules are mated and de-mated. Flex damage caused by excessive force on an improperly mounted circuit board is not covered under the product warranty.

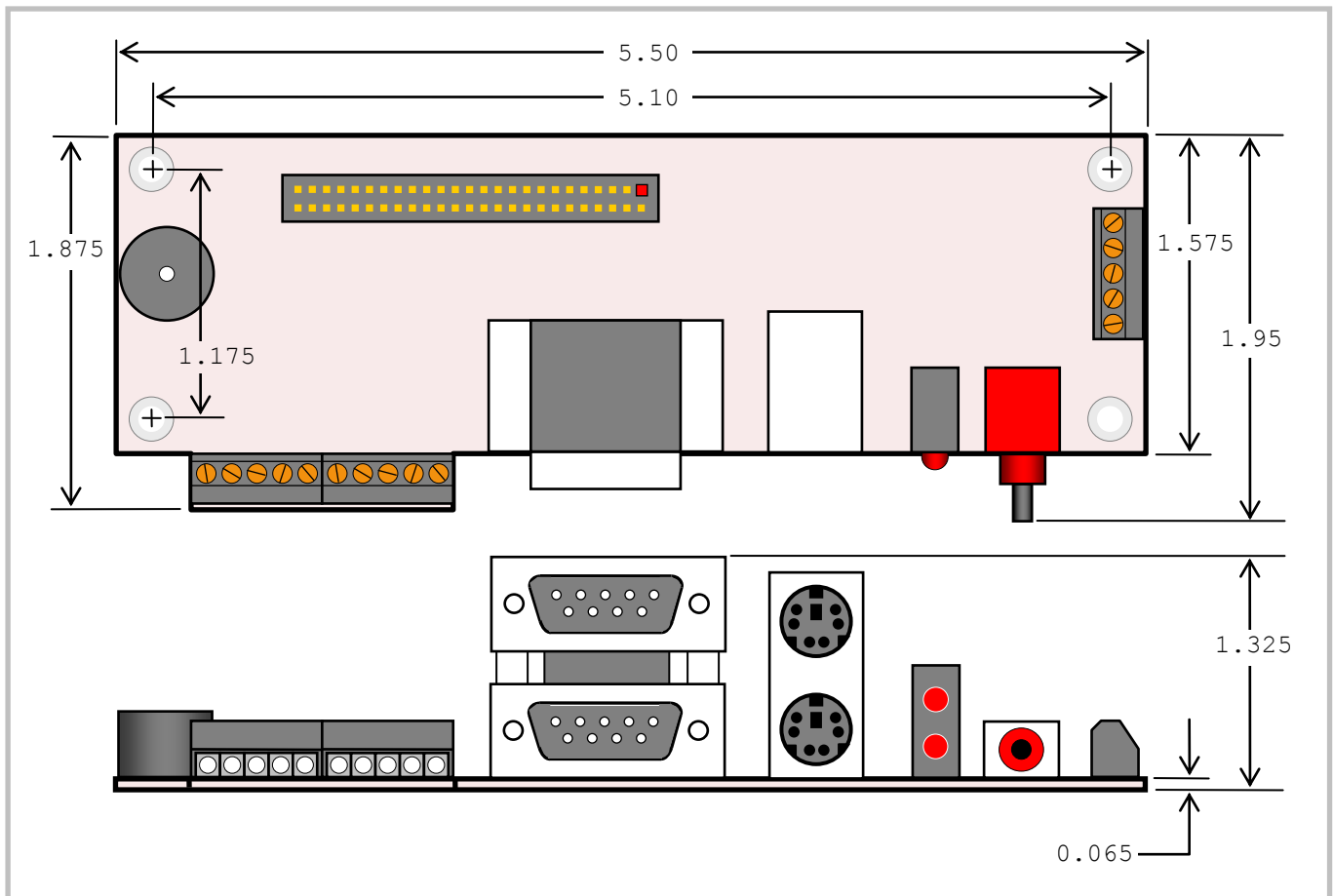


Figure 4. VL-CBR-5009 Dimensions and Mounting Holes

(Not to scale. All dimensions in inches.)

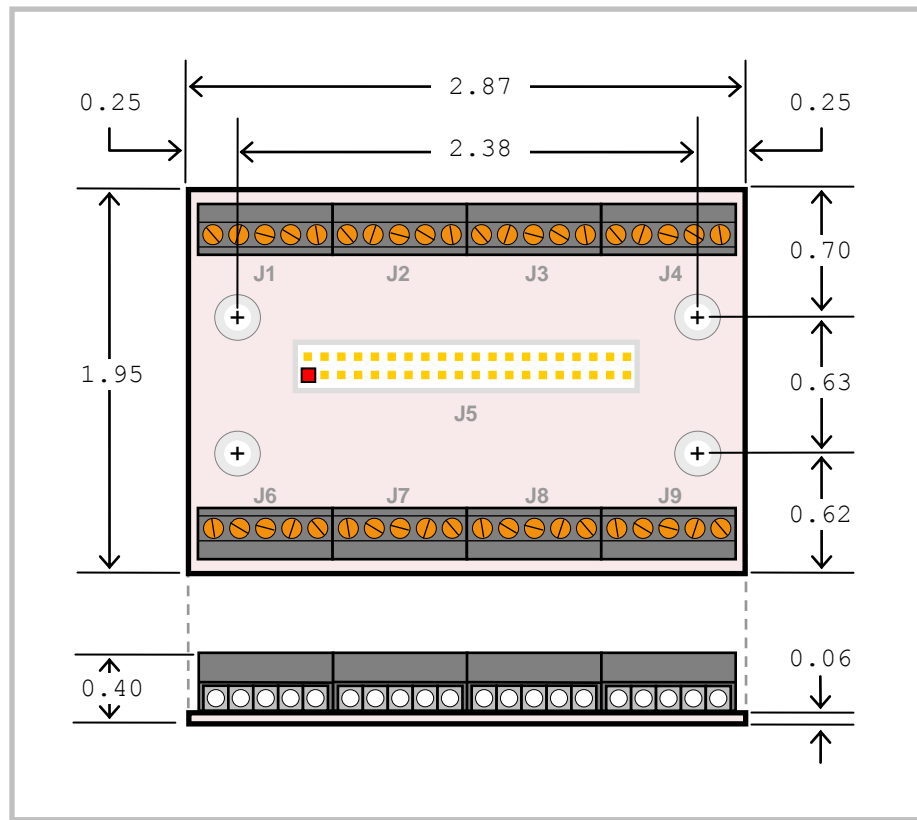


Figure 5. VL-CBR-4004 Dimensions and Mounting Holes
(Not to scale. All dimensions in inches.)

HARDWARE ASSEMBLY

The VL-EBX-37 mounts on four hardware standoffs using the corner mounting holes (A). These standoffs are secured to the underside of the circuit board using pan head screws.

Four additional standoffs (B) must be used under the circuit board to prevent excessive flexing when expansion modules are mated and separated. These are secured with four male-female standoffs (C), threaded from the top side, which also serve as mounting struts for the PC/104 stack.

The entire assembly can sit on a table top or be secured to a base plate. When bolting the unit down, make sure to secure all eight standoffs (A and B) to the mounting surface to prevent circuit board flexing.

An extractor tool is available (part number VL-HDW-203) to separate the PC/104 modules from the stack.

Note Standoffs and screws are available as part number VL-HDW-105 (metric thread) or VL-HDW-106 (English thread).

Note All eight mounting standoffs should be connected to earth ground (chassis ground). This provides proper grounding for ESD and EMI purposes.

STANDOFF LOCATIONS

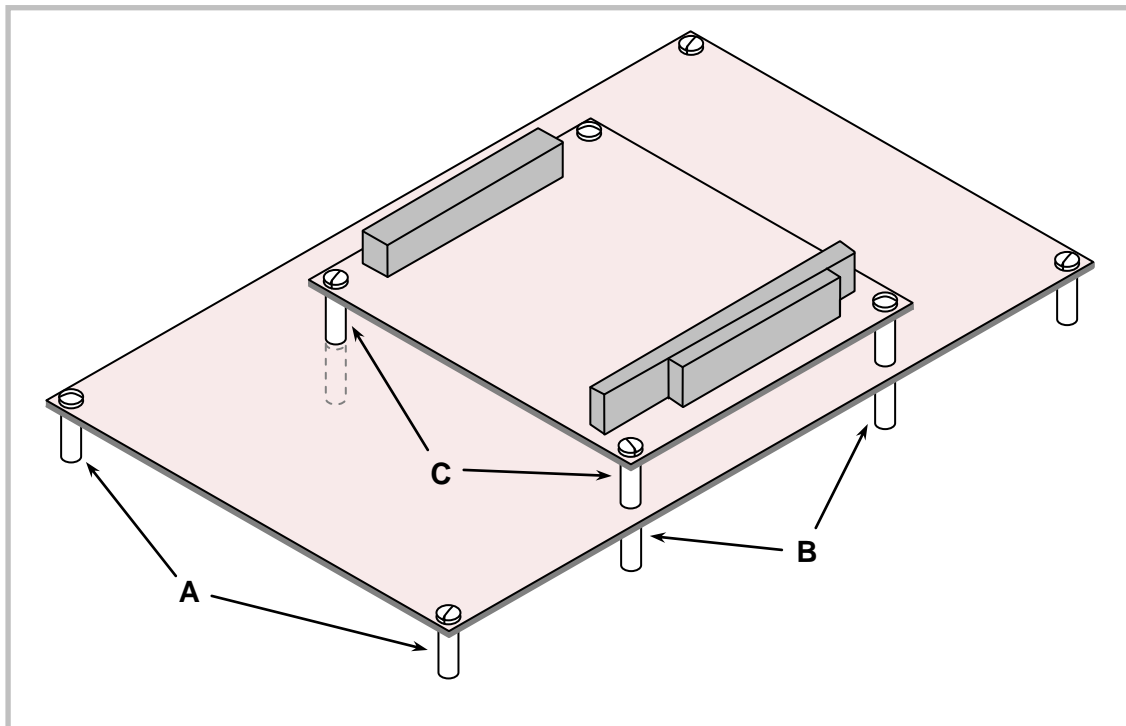


Figure 6. Standoff Locations

External Connectors

VL-EBX-37 CONNECTOR LOCATIONS – TOP

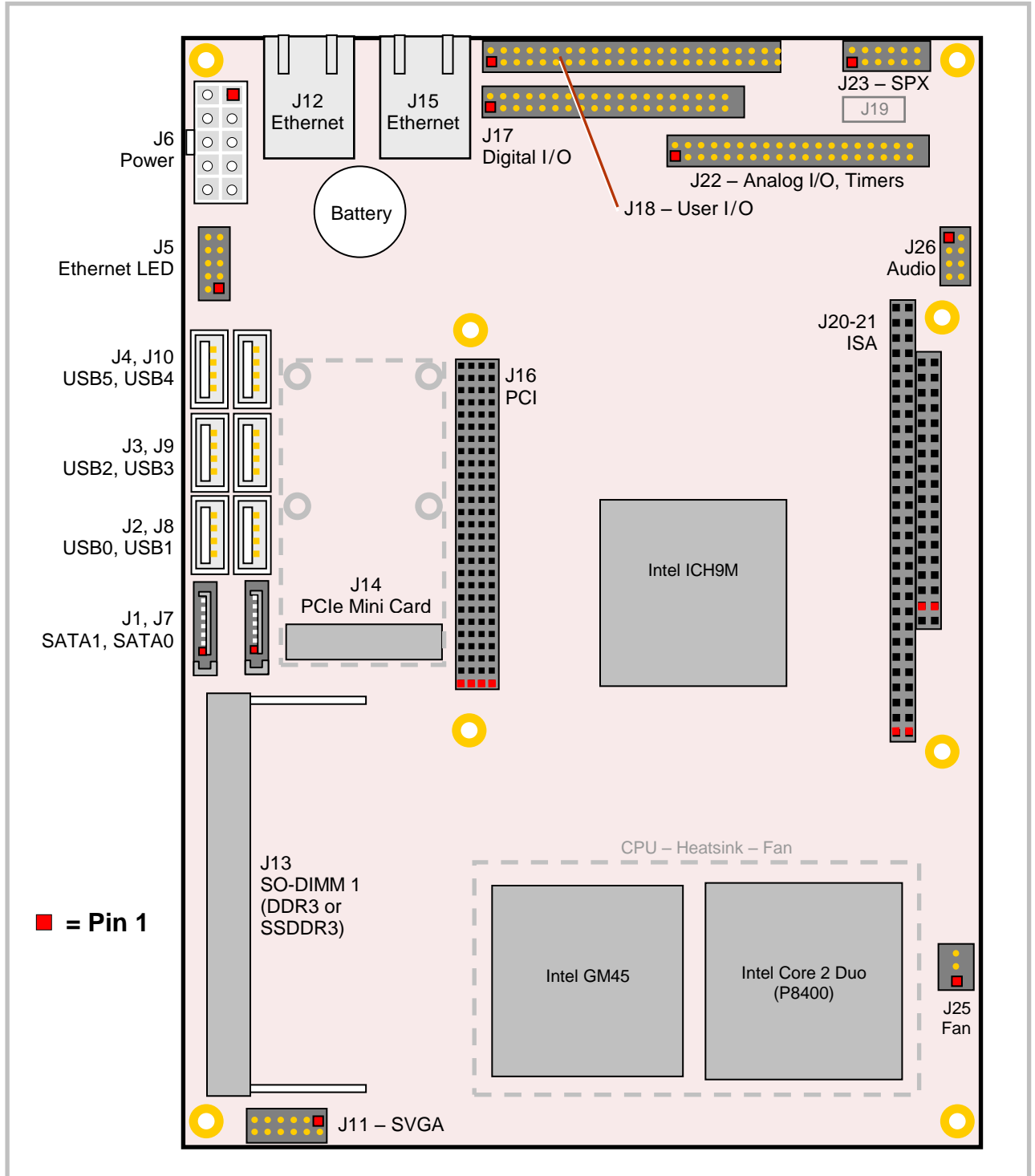


Figure 7. VL-EBX-37 Connector Locations - Top

VL-EBX-37 CONNECTOR LOCATIONS – BOTTOM

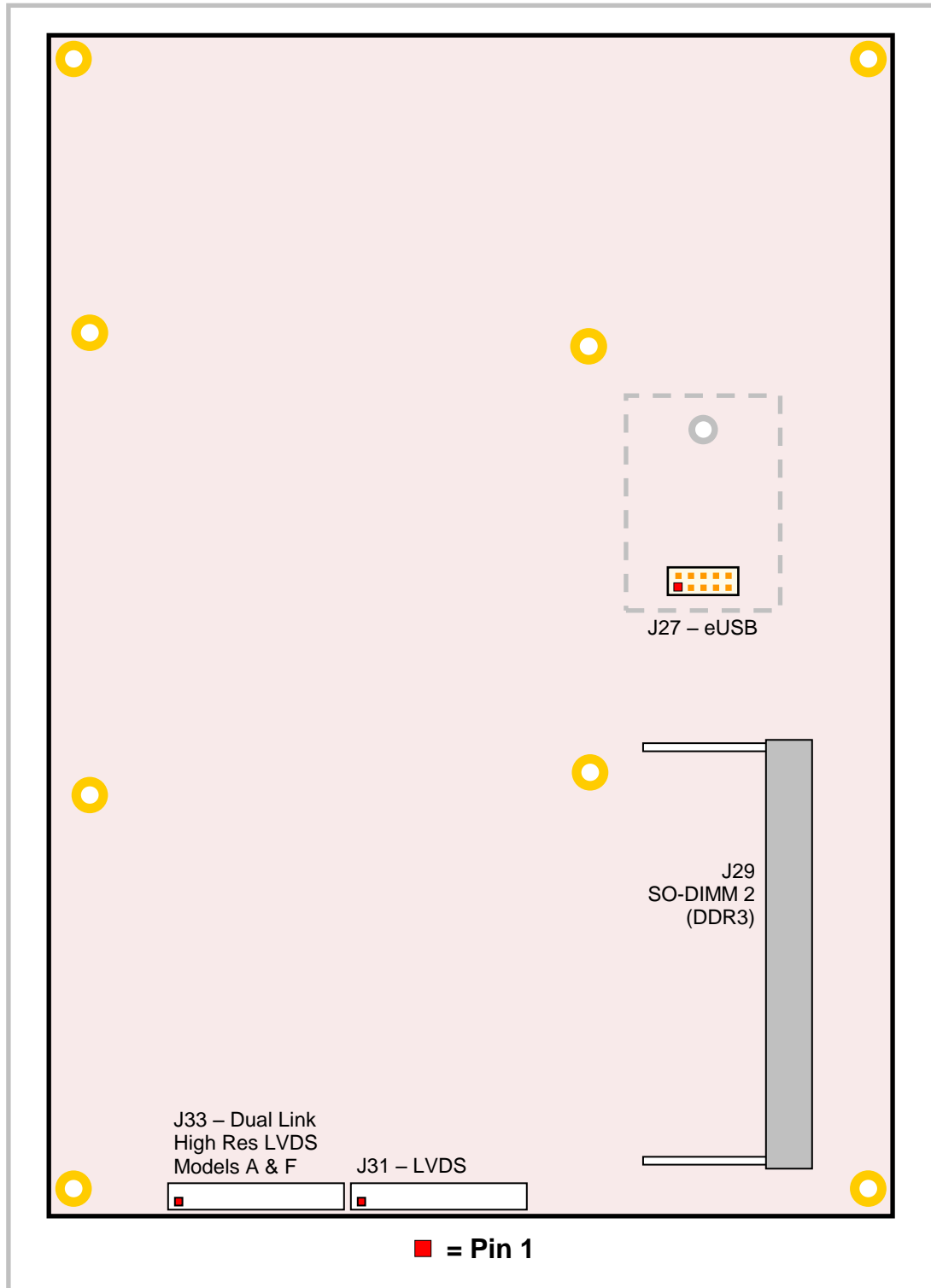


Figure 8. VL-EBX-37 Connector Locations - Bottom

VL-EBX-37 CONNECTOR FUNCTIONS AND INTERFACE CABLES

The following table notes the function of each connector, as well as mating connectors and cables, and the page where a detailed pinout or further information is available.

Table 1: Connector Functions and Interface Cables

Connector ¹	Function	Mating Connector	Transition Cable	Cable Description	Pin 1 Location ² x coord. y coord.	Page
J1	SATA 1	Standard SATA	VL-CBR-0701 or VL-CBR-0702 ⁴ VL-CBR-0401	500 mm (19.75") 7-pin, straight-to-straight SATA data; ATX to SATA power adapter	-0.037 3.675	26
J2	USB 0	Standard USB Type A	—	—	0.027 4.268	26
J3	USB 2	Standard USB Type A	—	—	0.027 4.978	26
J4	USB 5	Standard USB Type A	—	—	0.027 5.688	26
J5	Ethernet LED	—	—	—	0.004 6.063	31
J6	Main Power Input (EBX compliant)	Molex 39-01-2100 Molex 39-00-0059 (10 ea.)	VL-CBR-2022	6" ATX to EPIC power cable	0.157 7.341	20
J7	SATA 0	Standard SATA	VL-CBR-0701; VL-CBR-0401	Refer to J1 (SATA 1)	0.318 3.675	26
J8	USB 1	Standard USB Type A	—	—	0.342 4.268	26
J9	USB 3	Standard USB Type A	—	—	0.342 4.978	26
J10	USB 4	Standard USB Type A	—	—	0.342 5.688	26
J11	SVGA Video Output	FCI 89361-712LF or FCI 89947-712LF	VL-CBR-1201	12" 12-pin 2 mm IDC to 15-pin HD D-Sub VGA	0.842 -0.035	27
J12	Gigabit Ethernet 1	RJ45	—	—	0.665 7.280	30
J13	SO-DIMM 1	(DDR3 RAM or SSSDDR3)	—	—	0.216 1.599	22
J14	PCIe Mini Card	—	—	—	0.622 3.423	32
J15	Gigabit Ethernet 2	RJ45	—	—	1.632 7.280	30
J16	PC/104-Plus	AMP 1375799-1	—	—	2.112 3.100	33
J17	Digital I/O 1-32	FCI 89361-340LF	VL-CBR-4004A	12" 2 mm 40-pin to 40-pin IDC to VL-CBR-4004 board	2.178 7.254	34
J18	COM1-4, PLED, PS/2 Keyboard/ Mouse, Reset Button, Speaker	FCI 89361-350LF	VL-CBR-5009A	18" 2 mm 50-pin to 50-pin IDC to breakout board VL-CBR-5009	2.179 7.605	40
J19	Factory Use Only	—	—	—		
J20-J21	PC/104	AMP 1375795-2	—	—	5.050 2.700	33
J22	Analog I/O, Timers	FCI 89361-340LF	VL-CBR-4004A	12" 2 mm 40-pin to 40-pin IDC to VL-CBR-4004 board	3.574 6.901	44
J23	SPX	FCI 89361714LF	VL-CBR-1401; VL-CBR-1402	2 mm 14-pin IDC, 2 or 4 SPX device cable	4.584 7.601	49
J25	CPU Fan	—	—	Fan power cable with 2-pin connector	5.385 1.065	—
J26	Audio	FCI 89947-708LF or FCI 89361-708LF	VL-CBR-0803	12" latching 8-pin 2 mm to two 3.5 mm stereo audio	5.376 6.341	53
J27 ³	eUSB Flash Drive	—	—	—	1.110 4.106	53
J29 ³	SO-DIMM 2	(DDR3 RAM)	—	—	0.539 1.599	22
J31 J33 ³	LVDS LVDS Dual Link	20-pin, PanelMate 1.25mm	VL-CBR-2010; VL-CBR-2011; VL-CBR-2012 (24-bit)	18-bit TFT FPD using 20-pin Hirose 18-bit TFT FPD using 20-pin JAE	3.366 0.069 4.617 0.069	28

- Connectors are not installed at locations J19, J24, J28, J30 and J32. Connector J24 is for factory use only.
- The PCB origin is the mounting hole to the lower left as shown in Figure 3 (lower right when viewing bottom side of board).
- Connectors J27, J29, J31, and J33 are on the bottom of the board. Connector J33 is on models A and F only.
- VL-CBR-0701 is friction latching; VL-CBR-0702 is mechanical latching.

VL-CBR-5009 CONNECTOR LOCATIONS

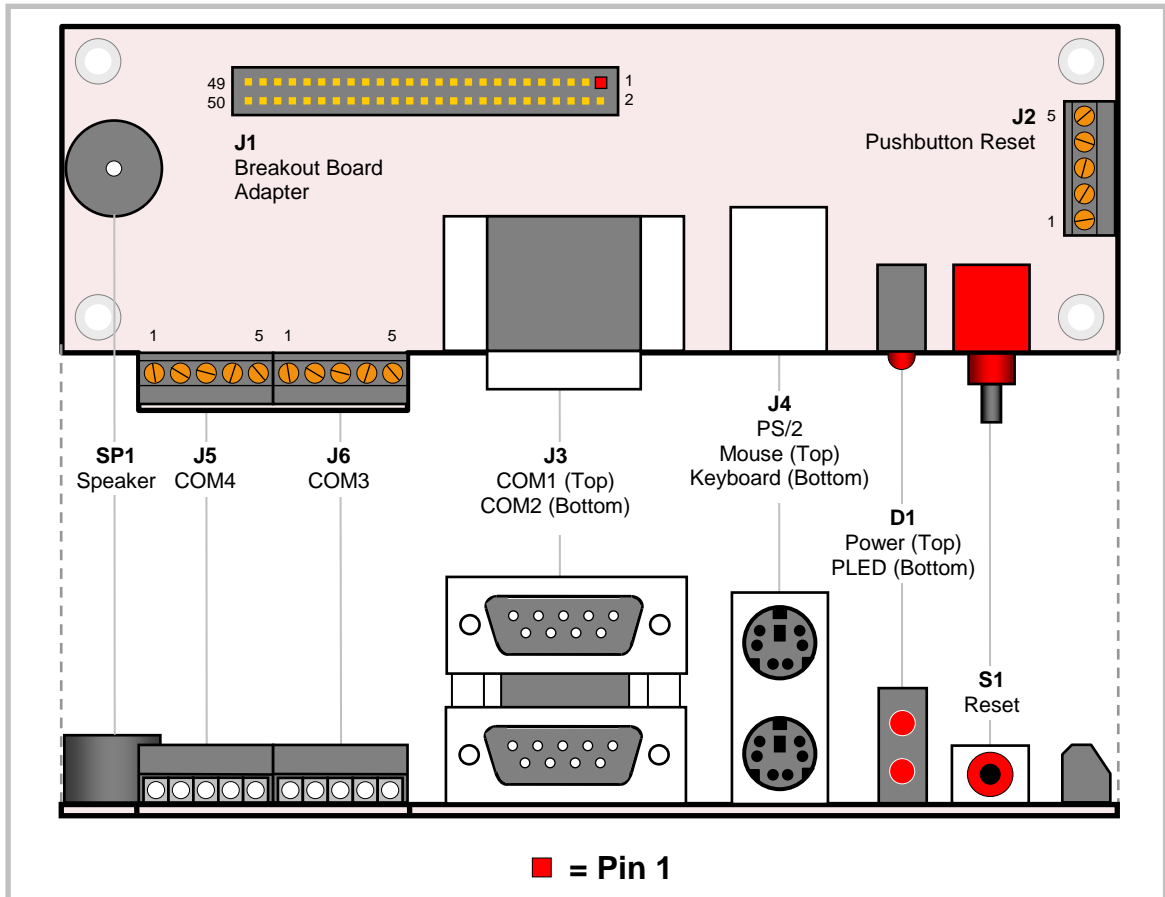


Figure 9. VL-CBR-5009 Connectors

VL-CBR-5009 CONNECTOR FUNCTIONS

Table 2: VL-CBR-5009 Connector Functions

Connector / Component	Function	Part Number	Description
D1	Power and Programmable LEDs	Dialight 552-0211	LEDx2 T1 3/4 PC Mount Red/Red
J1	High Density Connector	FCI 98414-F06-50U	2 mm, 50 pins, keyed, latching header
J2	Pushbutton Reset	Conta-Clip 10250.4	5-pin screw terminal
J3	COM1, COM2	Kycon K42-E9P/P-A4N	Dual stacked DB-9 male
J4	PS/2 Keyboard and Mouse	Kycon KMDG-6S/6S-S4N	Dual stacked PS/2 female
J5	COM4	Conta-Clip 10250.4	5-pin screw terminal
J6	COM3	Conta-Clip 10250.4	5-pin screw terminal
S1	Reset Button	E-Switch 800SP9B7M6RE	Right angle momentary switch
SP1	Speaker	Challenge Electronics DBX05	Miniature PC speaker

VL-CBR-4004 CONNECTOR LOCATIONS

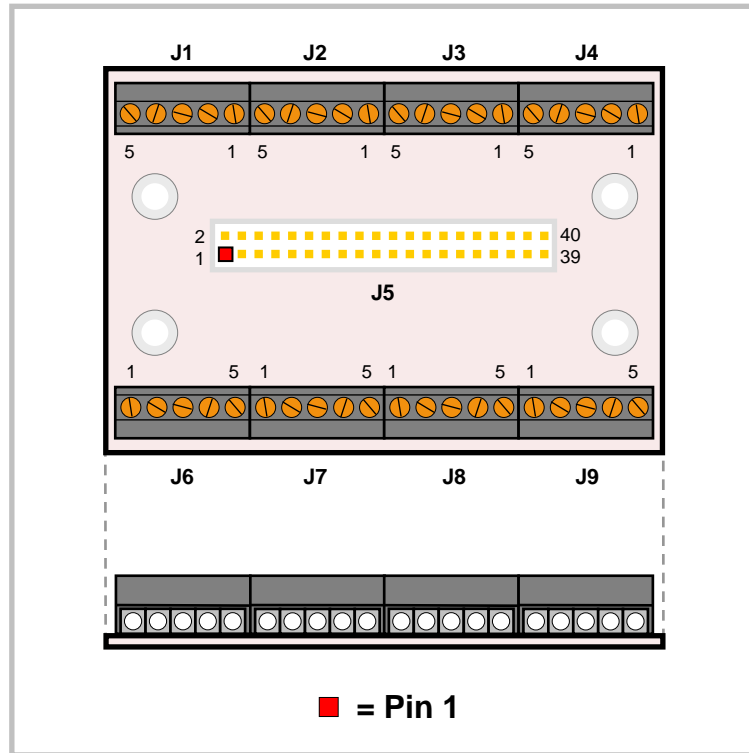


Figure 10. VL-CBR-4004 Connectors

The VL-CBR-4004 can be attached to connector J7 (digital I/O) and connector J22 (analog I/O and timers).

Jumper Blocks

JUMPERS AS-SHIPPED CONFIGURATION

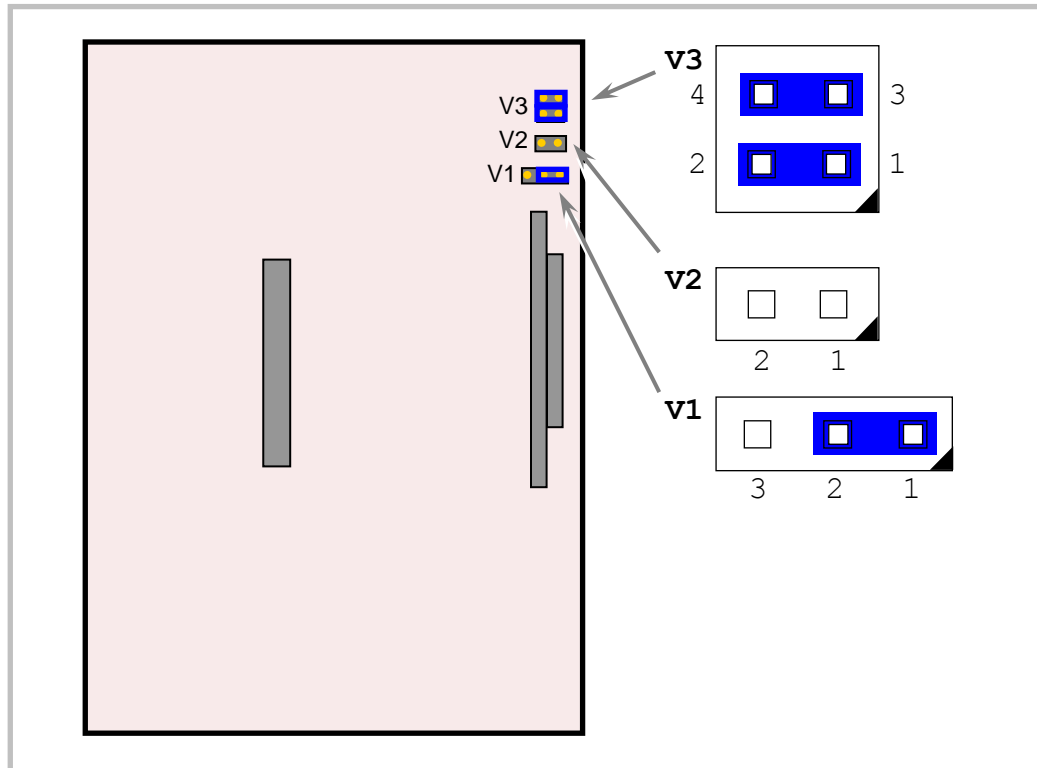


Figure 11. Jumper Block Locations

JUMPER SUMMARY

Table 3: Jumper Summary

Jumper Block	Description	As Shipped	Page
V1	CMOS RAM and Real-time Clock Erase [1-2] In – Normal [2-3] In – Erase CMOS RAM and real-time clock	[1-2] In	22
V2	System BIOS Selector In – Backup system BIOS selected Out – Primary system BIOS selected The Primary system BIOS is field upgradeable using the BIOS upgrade utility. See http://www.versalogic.com/private/mambasupport.asp for more information.	Out	24
V3[1-2]	COM3 RS-422 Rx or RS-485 Termination In – 100 Ohm terminated Out – COM3 not terminated	In	41
V3[3-4]	COM4 RS-422 Rx or RS-485 Termination In – 100 Ohm terminated Out – COM4 not terminated	In	41

Power Supply

POWER CONNECTOR (J6)

Main power is applied to the VL-EBX-37 through an EPIC-style 10-pin polarized connector at location J6.

Warning! To prevent severe and possibly irreparable damage to the system, it is critical that the power connectors are wired correctly. Make sure to use all +5V_{DC} pins and all ground pins to prevent excess voltage drop.

Table 4: Main Power Connector Pinout

J6 Pin	Signal Name	Description
1	GND	Ground
2	GND	Ground
3	GND	Ground
4	+12V _{DC}	Power Input
5	+3.3V _{DC}	Power Input
6	NC	Not Connected
7	+5V _{DC}	Power Input
8	+5V _{DC}	Power Input
9	-12V _{DC}	Power Input
10	GND	Ground

Note The +3.3V_{DC}, +12V_{DC} and -12V_{DC} inputs on the main power connector are only required for PC/104-*Plus* and PC/104 expansion modules that require these voltages.

POWER REQUIREMENTS

The VL-EBX-37 requires +5.0 volts ($\pm 5\%$) for proper operation. The higher voltages required for the RS-232 ports and analog input sections are generated as needed on-board. Low-voltage supply circuits provide the many power rails required by the CPU and other on-board devices.

The exact power requirement of the VL-EBX-37 depends on several factors, including memory configuration, CPU speed, peripheral connections, type and number of expansion modules and attached devices. For example, PS/2 keyboards typically draw their power directly from the VL-EBX-37, and USB devices can draw considerable power depending on the device.

POWER DELIVERY CONSIDERATIONS

The VL-EBX-37 draws 25W (5A) as measured on a typical time averaging ammeter. The board can experience large, short-term current transients during operation, so care must be taken to provide robust power to the board. A good power delivery method eliminates such problems as voltage drop and lead inductance. Using the VersaLogic approved power supply (VL-PS200-ATX) and power cable (VL-CBR-2022) will ensure high quality power delivery to the board. Customers who design their own power delivery methods should take into consideration the guidelines below to ensure good power connections.

Also note that the 5V @ 5A typical operating current does not include any off-board power usage that may be fed through the VL-EBX-37 power connector. PC/104 boards on the expansion site and USB devices plugged into the board will source additional 5V power through the VL-EBX-37 power connector.

- Do not use wire smaller than 18 AWG. Use high quality UL 1007 compliant stranded wire.
- The length of the wire should not exceed 18".
- Avoid using any additional connectors in the power delivery system.
- The power and ground leads should be twisted together, or as close together as possible to reduce lead inductance.
- A separate conductor must be used for each of the power pins.
- All 5V pins and all ground pins must be independently connected between the power source and the power connector.
- Implement the remote sense feature on your power supply if it has one. Connect the remote sense lines in tandem with one of the power connector 5V and ground pins. This is done at the connector to compensate for losses in the power wires.
- Use a high quality power supply that can supply a stable voltage while reacting to widely varying current draws.

LITHIUM BATTERY

Warning! To prevent shorting, premature failure or damage to the lithium battery, do not place the board on a conductive surface such as metal, black conductive foam or the outside surface of a metalized ESD protective pouch. The lithium battery may explode if mistreated. Do not recharge, disassemble or dispose of in fire. Dispose of used batteries promptly.

Normal battery voltage should be at least 3.0V. If the voltage drops below 3.0V, contact the factory for a replacement (part number HB3/0-1). The life expectancy under normal use is approximately 10 years.

CPU

The Intel Core 2 Duo processor combines fast performance, using Intel's 45 nm technology, with advanced power savings features. The P8400 model used on the VL-EBX-37 has a maximum clock rate of 2.26 GHz, a maximum front side bus speed of 1066 MHz, and features 3 MB of L2 cache. Other features include DDR3 SDRAM support and an integrated display controller. For more CPU information see the VL-EBX-37 support page.

System RAM

COMPATIBLE MEMORY MODULES

The VL-EBX-37 accepts two 204-pin SO-DIMM memory modules with the following characteristics:

- Size Up to 4 GB
- Voltage 1.5V
- Type DDR3 – VersaLogic VL-MM7 Series modules
SSDDR3 – VL-MF7 Series modules; 1 GB or 2 GB RAM plus 8 GB
SATA flash (socket J13 only)

RAM SIZE LIMITATION

Most Windows operating systems can be purchased in 32-bit or 64-bit versions, depending on the processor of the target system on which it will be executing. Due to the way that this board maps memory, 32-bit OS versions will not be able to identify or use more than 2 GB of RAM. The 64-bit Windows versions, and Linux kernels using a HIGHMEM64 configuration, will correctly identify and use memory sizes larger than 2 GB.

SSDDR3 DUAL FUNCTION MEMORY AND SOLID STATE DRIVE

The VersaLogic VL-MF7 Series modules provide 1 or 2 GB of RAM plus 8 GB of flash storage. These modules function only in socket J13. The solid state drive (SSD) can function as a bootable SATA drive or secondary storage device without claiming either of the SATA channels at connectors J1 or J7.

CMOS RAM

CLEARING CMOS RAM

A jumper may be installed into V1[2-3] to erase the contents of the CMOS RAM and the Real-Time Clock. When clearing CMOS RAM:

1. Power off the VL-EBX-37.
2. Remove the jumper from V1[1-2], install it on V1[2-3] and leave it for four seconds.
3. Move the jumper back to V1[1-2].
4. Power on the VL-EBX-37.

CMOS Setup Defaults

The VL-EBX-37 permits you to modify CMOS Setup defaults. This allows the system to boot up with user-defined settings from cleared or corrupted CMOS RAM, battery failure or battery-less operation. All CMOS setup defaults can be changed, except the time and date. CMOS Setup defaults can be updated with the BIOS Update Utility. See the [General BIOS Information page](#) for details.

Note: If CMOS Setup default settings make the system unbootable and prevent the user from entering CMOS Setup, the system can be recovered by switching to the Backup BIOS.

DEFAULT CMOS RAM SETUP VALUES

After the CMOS RAM is cleared, the system will load default CMOS RAM parameters the next time the board is powered on. The default CMOS RAM setup values are used in order to boot the system whenever the main CMOS RAM values are blank, or when the system battery is dead or has been removed from the board.

Custom default values will be used for CMOS restoration when available. Otherwise, factory defaults will be used. Factory defaults can still be loaded when custom defaults have been programmed by selecting “Reload Factory-Defaults and Restart” on the Exit tab, but CMOS restoration will continue to use custom defaults as long as they are available.

To remove custom defaults, either re-program the BIOS or follow the “Saving CMOS Setup Parameters as Custom Defaults” procedure below after selecting “Reload Factory-Defaults.”

SAVING CMOS SETUP PARAMETERS AS CUSTOM DEFAULTS

To save custom CMOS defaults, perform the following steps.

1. Configure CMOS Setup to your preferred custom default settings.
2. Install DOS onto one of the devices that has been configured as a boot device, or onto an auxiliary boot device (such as a USB flash drive) that can be booted from using the Boot Action Menu, and need not be configured in the Boot Device Prioritization list.
3. Copy FBU to this device.
4. Boot the VL-EBX-37 from this device. To boot from the auxiliary device using the Boot Action Menu, press Ctrl-B during the memory count, or about twice per second after power on. From the Boot Action Menu, select the auxiliary device to boot from it.
5. Run FBU and select "Save CMOS contents." A file named CMOS.BIN is created and saved to the floppy.
6. Select the FBU option "Load Custom CMOS defaults."
7. Select the CMOS.BIN file and press the P key to program the new CMOS defaults.
8. Reboot the system. If FBU cleared CMOS RAM after the programming operation, the new custom defaults will now be in effect.

Primary and Backup BIOS

The Primary system BIOS is field upgradeable using the BIOS upgrade utility (see the [VL-EBX-37 Support Page](#) for more information). The Backup BIOS is available if the Primary BIOS becomes corrupted. Jumper V2[1-2] controls whether the system uses the Primary or Backup BIOS. By default the Primary BIOS is selected (jumper removed).

Real-time Clock

The VL-EBX-37 features a battery-backed 146818-compatible real-time clock/calendar chip. Under normal battery conditions, the clock maintains accurate timekeeping functions when the board is powered off.

SETTING THE CLOCK

CMOS Setup (accessed by pressing the Delete key during a system boot) can be used to set the time/date of the real-time clock.

Fan Tachometer Monitor

The Super I/O chip on the VL-EBX-37 contains a hardware monitor which includes a 16-bit fan tachometer register that can be read to obtain the speed of the fan on the VL-EBX-37. When one byte of the 16-bit register is read, the other byte latches the current value until it is read, in order to ensure a valid reading. The order is LSB first, MSB second. The value FFFFh indicates that the fan is not spinning. For more information see the [SMSC SCH3114 Super I/O Chip Datasheet](#).

FAN TACHOMETER READ CODE EXAMPLE

```
#include <stdio.h>
#include <conio.h>
#include <stdlib.h>
#include <graph.h>
#include <dos.h>

//Definitions
#define TRUE          1
#define FALSE        0
#define ESC           27
#define SIOINDEX     0x2E
#define SIODATA      0x2F
#define FANTACHREG    0x28
#define RLSREG        0x40
#define RTOFFSET      0x70
#define START         0x01

void main ()
{
    int baseIOHigh;
    int baseIOLow;
    int FTraw;
    int Bindex;
    int Bdata;
    double fanRPM;
    char keypressed = 0;

    _clearscreen( _GCLEARSCREEN );
    _settextposition(2,1);
    printf( "FANTACH DEMO...(press ESC to quit).\n" );
```

```

/*      Read in the HWM base address...      */
outp( SIOINDEX, 0x55 );      //Enter SIO config mode.
outp( SIOINDEX, 0x07 );      //Point to Logical Device Config reg.
outp( SIODATA, 0x0A );      //Select SMSC Runtime reg.
outp( SIOINDEX, 0x60 );      //Index High Byte of Runtime reg base address.
baseIOHigh = inp( SIODATA );      //Read High Byte.
outp( SIOINDEX, 0x61 );      //Index Low Byte of Runtime reg base address.
baseIOLow = inp( SIODATA ) + RTOFFSET;      //Read Low Byte and add offset to runtime reg base.
outp( SIOINDEX, 0xAA );      //Exit SIO Config mode
Bindex = (baseIOHigh << 8) + baseIOLow;      //Convert high and low bytes to 16-bit address.
Bdata = Bindex + 1;

/*      Start Hardware Monitoring...      */
outp( Bindex, RLSREG );      //Index Ready, Lock, Start Reg.
outp( Bdata, inp( Bdata ) | START );      //Set bit 0 to start.

while (keypressed != ESC)
{
    if (kbhit())
    {
        keypressed = getch();
    }

    /*      Read FanTach1 LSB first, latches MSB.      */
    outp( Bindex, FANTACHREG );      //Fantach 1 LSB
    FTraw = inp( Bdata );
    outp( Bindex, FANTACHREG + 1 );      //Fantach 1 MSB
    FTraw += inp( Bdata ) << 8;

    /* FTraw now contains the number of 90KHz pulses it took to find 5
       tach edges. (5 edges = 2 tach pulses = 1 revolution) */

    /*      Convert Raw to RPMs...      */
    RPM = 1 / (FTraw * 11.11uS / 2) * 60      */
    fanRPM = FTraw * 0.00001111;
    fanRPM /= 2;
    fanRPM = 1/fanRPM;
    settxtposition(4,1);
    if ( fanRPM > 0 )
    {
        printf ( "FanTach 1: %5.0fRPMs      \n", fanRPM*60 );
        delay(100);
    }
    else
    {
        printf ( "FanTach 1: Stalled! \n" );
        delay(100);
    }
}

exit ( 0 );
}

```

SATA Ports (J1, J7)

The VL-EBX-37 provides two serial ATA (SATA) ports, which communicate at a rate of up to 3.0 gigabits per second. The SATA connectors at location J1 and J7 are standard 7-pin straight SATA friction latching connectors.

Power to SATA drives is supplied by the ATX power supply. Note that the standard SATA drive power connector is different than the common 4-pin Molex connector used on IDE drives. Most current ATX power supplies provide SATA connectors, and many SATA drives provide both types of power connectors. If the power supply you are using does not provide SATA connectors, adapters are available.

Table 5: SATA Port Pinout

J1 or J7 Pin	Signal Name	Function
1	GND	Ground
2	TX+	Transmit +
3	TX-	Transmit -
4	GND	Ground
5	RX-	Receive -
6	RX+	Receive +
7	GND	Ground

USB (Multiple Connectors)

The VL-EBX-37 includes eight USB channels. There are six USB ports with standard USB Type A connectors, located on the baseboard at locations J2, J3, J4, J8, J9, and J10. The eUSB connector at J27 and PCIe Mini Card connector at J14 each provide one USB channel. These connectors are protected against ESD damage.

The USB interface on the VL-EBX-37 is UHCI (Universal Host Controller Interface) and EHCI (Enhance Host Controller Interface) compatible, which provides a common industry software/hardware interface.

Video Interface (J11, J31, J33)

An on-board video controller integrated into the chipset provides high-performance video output for the VL-EBX-37. The controller supports dual, simultaneous, independent video output. The VL-EBX-37 can also be operated without video attached. See “Console Redirection.”

The VL-EBX-37 uses a shared-memory architecture. It supports two types of video output, SVGA and LVDS Flat Panel Display.

SVGA OUTPUT CONNECTOR (J11)

An adapter cable, part number VL-CBR-1201, is available to translate J11 into a standard 15-pin D-Sub SVGA connector. This connector is protected against ESD damage.

Table 6: Video Output Pinout

J11 Pin	Signal Name	Function	Mini DB15 Pin
1	GND	Ground	6
2	RED	Red Video	1
3	GND	Ground	7
4	GREEN	Green Video	2
5	GND	Ground	8
6	BLUE	Blue Video	3
7	GND	Ground	5
8	HSYNC	Horizontal Sync	13
9	GND	Ground	10
10	VSYNC	Vertical Sync	14
11	SCL	DDC Serial Data Line Clock	15
12	SDA	DDC Serial Data Line	12

LVDS FLAT PANEL DISPLAY CONNECTOR (J31, J33)

The integrated LVDS Flat Panel Display in the VL-EBX-37 is an ANSI/TIA/EIA-644-1995 specification-compliant interface. VL-EBX-37 Models S and E have one LVDS connector at J31 and supports single-channel mode operation. Models A and F have an additional LVDS connector at J33 to provide a second channel for optional dual-channel mode (both connectors used concurrently to drive one LVDS display). Single-channel mode supports up to 24 bits of RGB pixel data plus 4 bits of timing control on the four differential data output pairs. Dual-channel mode supports up to 48 bits of RGB pixel data plus 4 bits of timing control on the eight differential data output pairs. The second LVDS connector (J33) can not be used to support a second LVDS panel. The LVDS clock frequency ranges from 25 MHz to 112 MHz.

CMOS Setup provides several options for standard LVDS flat panel types. If these options do not match the requirements of the panel you are attempting to use, contact Support@VersaLogic.com for a custom video BIOS.

Table 7: LVDS Flat Panel Display Pinouts

J31 Pin	J31 Signal Name	J31 Function	J33 Pin	J33 Signal Name	J33 Function
1	GND	Ground	1	GND	Ground
2	NC	Not Connected	2	NC	Not Connected
3	LVDSA3	Diff. Data 3 (+)	3	LVDSB3	Diff. Data 3 (+)
4	LVDSA3#	Diff. Data 3 (-)	4	LVDSB3#	Diff. Data 3 (-)
5	GND	Ground	5	GND	Ground
6	LVDSCLK0	Differential Clock (+)	6	LVDSCLK1	Differential Clock (+)
7	LVDSCLK0#	Differential Clock (-)	7	LVDSCLK1#	Differential Clock (-)
8	GND	Ground	8	GND	Ground
9	LVDSA2	Diff. Data 2 (+)	9	LVDSB2	Diff. Data 2 (+)
10	LVDSA2#	Diff. Data 2 (-)	10	LVDSB2#	Diff. Data 2 (-)
11	GND	Ground	11	GND	Ground
12	LVDSA1	Diff. Data 1 (+)	12	LVDSB1	Diff. Data 1 (+)
13	LVDSA1#	Diff. Data 1 (-)	13	LVDSB1#	Diff. Data 1 (-)
14	GND	Ground	14	GND	Ground
15	LVDSA0	Diff. Data 0 (+)	15	LVDSB0	Diff. Data 0 (+)
16	LVDSA0#	Diff. Data 0 (-)	16	LVDSB0#	Diff. Data 0 (-)
17	GND	Ground	17	GND	Ground
18	GND	Ground	18	GND	Ground
19	+3.3V	+3.3V (Protected)	19	+5V	+5V
20	+3.3V	+3.3V (Protected)	20	+5V	+5V

Warning! The power voltage supplied by the J33 connector is +5V. Plugging a 3.3V LVDS panel into connector J33 could cause damage to the panel.

The power provided to pins 19 and 20 of both connectors is protected by a software-controllable power switch (1 Amp max.). This switch is controlled by the L_VDD_EN signal from the LVDS interface controller in the Intel GM45 controller. See the [Intel GM45 Datasheet](#) for detailed information.

COMPATIBLE LVDS PANEL DISPLAYS

The following flat panel displays are reported to work properly with the integrated graphics video controller chip used on the VL-EBX-37.

Table 8: Compatible Flat Panel Displays

Manufacturer	Model Number	Panel Size	Resolution	Interface	Panel Technology
eVision Displays	xxx084S01 series	8.4"	800 x 600 18-bit	LVDS	TFT
au Optronix	B084SN01	8.4"	800 x 600 18-bit	LVDS	TFT
eVision Displays	xxx104S01 series	10.4"	800 x 600 18-bit	LVDS	TFT
au Optronix	B104SN01	10.4"	800 x 600 18-bit	LVDS	TFT
eVision Displays	xxx141X01 series	14.1"	1024 x 768 18-bit	LVDS	TFT
Sharp	LQ121S1LG411	12.1"	800 x 600 18-bit	LVDS	TFT

CONSOLE REDIRECTION

The VL-EBX-37 can be operated without using the on-board video output by redirecting the console to a serial communications port. CMOS Setup and some operating systems such as DOS can use this console for user interaction.

Console redirection settings are configured on the Features tab of CMOS Setup. The default setting (On Remote User Detect) causes the console to be redirected to the serial port only when a signal (a Ctrl-C character) is detected from the terminal. Console redirection can also be set to Always or Never. Notes on console redirection:

- When console redirection is enabled, you can access CMOS Setup by typing Ctrl-C.
- The decision to redirect the console is made early in BIOS execution, and cannot be changed later.
- The redirected console uses 115200 baud, 8 data bits, 1 stop bit, no parity, and no flow control.

Null Modem

The following diagram illustrates a typical DB-9 to DB-9 RS-232 null modem adapter. Pins 7 and 8 are shorted together on each connector. Unlisted pins have no connection.

System 1	<-->	System 2
Name Pin		Pin Name
TX 3	<-->	2 RX
RX 2	<-->	3 TX
RTS 7	<-->	1 DCD
CTS 8		
DSR 6	<-->	4 DTR
DCD 1	<-->	7 RTS
		8 CTS
DTR 4	<-->	6 DSR
GND 5	<-->	5 GND

Ethernet Interface (J12, J15)

The VL-EBX-37 features two on-board Intel 82574IT Gigabit Ethernet controllers. The controllers provide a standard IEEE 802.3 Ethernet interface for 1000Base-T, 100Base-TX, and 10Base-T applications. RJ45 connectors are located at locations J12 (Ethernet 1) and J15 (Ethernet 2). While these controllers are not NE2000-compatible, they are widely supported. Drivers are readily available to support a variety of operating systems. These interfaces are protected against ESD damage.

ETHERNET CONNECTORS

Two board-mounted RJ45 connectors are provided to make connection with Category 5 or 6 Ethernet cables. The 82574IT Ethernet controller auto-negotiates connection speed. These interfaces use IEC 61000-4-2-rated TVS components to help protect against ESD damage.

The RJ45 connectors have two built-in LEDs to provide an indication of the Ethernet status as shown in the following table.

Table 9: RJ45 Connector Status LEDs

LED	State	Description
Green/Orange (Link Speed)	Orange	1 Gbps speed
	Green	100 Mbps speed
	Off	10 Mbps speed or cable not connected
Yellow (Activity)	On	Cable connected (intermittent with activity)
	Off	Cable not connected

STATUS LED (J5)

Connector J5 provides an additional on-board Ethernet status LED interface. The +3.3V power supplied to this connector is protected by a 1 Amp fuse.

Table 10: Ethernet Status LED Pinout

J5 Pin	Signal Name	Function
1	+3.3V	Protected Power Supply
2	YEL1	Yellow LED - Ethernet 0
3	ORN1	Orange LED - Ethernet 0
4	GRN1	Green LED - Ethernet 0
5	+3.3V	Protected Power Supply
6	YEL2	Yellow LED - Ethernet 1
7	ORN2	Orange LED - Ethernet 1
8	GRN2	Green LED - Ethernet 1
9	GND	Ground
10	W_DISABLE#	PCIe Mini Card Disable

W_Disable# Signal

The W_DISABLE# is for use with optional wireless PCIe Mini Cards. The signal allows you to disable a wireless card's radio operation in order to meet public safety regulations or when otherwise desired. The W_DISABLE# signal is an active low signal that when driven low (shorted to ground) disables radio operation on the PCIe Mini Card wireless device. When the W_DISABLE# is not asserted, or in a high impedance state, the radio may transmit if not disabled by other means such as software. See "PCI Express Mini Card (J14)."

PCI Express Mini Card (J14)

The PCI Express Mini Card connector at J14 accepts a full-height PCI Express Mini Card. The interface includes one PCIe x1 lane, one USB 2.0 channel, and the SMBus interface. The socket is compatible with plug-in Wi-Fi modems, GPS receivers, flash data storage, and other cards for added flexibility.

An Intel WiFi Link 5300 PCI Express Mini card (VL-WD10-CBN) is available from VersaLogic. A WiFi antenna (VL-CBR-ANT01) and a 12" WiFi card to bulkhead RP-SMA transition cable (VL-CBR-0201) are also available. For more information, contact Sales@VersaLogic.com.

To secure a Mini Card to the VL-EBX-37 use two screws (M2 x 5 mm, Philips, pan head, 4 mm, stainless) and two washers (M2, split lock, OD 4.4 mm, stainless). Screw and washer sets are available in 10-count packages as part number VL-HDW-107.

Table 11: PCIe Mini Card Pinout

Pin	Signal Name	Function	Pin	Signal Name	Function
1	WAKE#	Wake	2	3.3VAUX	3.3V auxiliary source
3	NC	Not connected	4	GND	Ground
5	NC	Not connected	6	1.5V	1.5V power
7	CLKREQ#	Reference clock request	8	NC	Not connected
9	GND	Ground	10	NC	Not connected
11	REFCLK-	Reference clock input –	12	NC	Not connected
13	REFCLK+	Reference clock input +	14	NC	Not connected
15	GND	Ground	16	NC	Not connected
17	NC	Not connected	18	GND	Ground
19	NC	Not connected	20	W_DISABLE#	Wireless disable
21	GND	Ground	22	PERST#	Card reset
23	PERn0	Lane 0 receive –	24	3.3VAUX	3.3V auxiliary source
25	PERp0	Lane 0 receive +	26	GND	Ground
27	GND	Ground	28	1.5V	1.5V power
29	GND	Ground	30	SMB_CLK	SMBus clock
31	PETn0	PCIe lane 0 transmit –	32	SMB_DATA	SMBus data
33	PETp0	PCIe lane 0 transmit +	34	GND	Ground
35	GND	Ground	36	USB_D-	USB data –
37	GND	Ground	38	USB_D+	USB data +
39	3.3VAUX	3.3V auxiliary source	40	GND	Ground
41	3.3VAUX	3.3V auxiliary source	42	LED_WWAN#	Wireless WAN LED
43	GND	Ground	44	LED_WLAN#	Wireless LAN LED
45	NC	Not connected	46	LED_WPAN#	Wireless PAN LED
47	NC	Not connected	48	1.5V	1.5V power
49	NC	Not connected	50	GND	Ground
51	NC	Not connected	52	3.3VAUX	3.3V auxiliary source

Expansion Bus (J16, J20/J21)

PC/104-Plus – PCI (J16)

PC/104-Plus modules can be secured directly to the top of the VL-EBX-37. The VL-EBX-37 is compliant with revision 2.3 of the PC/104-Plus specification and can support four bus master capable PC/104-Plus modules. The BIOS automatically allocates I/O and memory resources. CMOS Setup may be used to select IRQ assignment. (See the [PC/104-Plus Physical Pinout](#).)

PC/104 – ISA (J20/J21)

The VL-EBX-37 provides full support of the PC/104 (ISA) bus, including support of 16-bit I/O and memory transfers. PC/104 modules can be added to the stack above the VL-EBX-37. Most PC/104 cards will work, but be sure to check the requirements of your PC/104 card against the limitations listed below.

Available I/O Ranges

The following I/O ranges are available to the ISA bus:

- 019h – 01Eh ▪ 03Eh – 03Fh ▪ 0A2h – 0A3h ▪ 0D2h – 0DDh ▪ 4D2h – 4FFh
- 022h – 023h ▪ 043h – 04Dh ▪ 0A6h – 0A7h ▪ 0E0h – 0EFh ▪ 580h – BFFh
- 026h – 027h ▪ 053h – 05Fh ▪ 0AAh – 0ABh ▪ 0F1h – 207h ▪ D00h
- 02Ah – 02Bh ▪ 063h ▪ 0AEh – 0AFh ▪ 210h – 2F7h
- 032h – 033h ▪ 065h ▪ 0B6h – 0B7h ▪ 300h – 3BFh
- 036h – 037h ▪ 067h – 070h ▪ 0BAh – 0BBh ▪ 3E0h – 3F7h
- 03Ah – 03Bh ▪ 078h – 07Fh ▪ 0BEh – 0BFh ▪ 400h – 4CFh

Available base I/O addresses for COM ports are: 220h, 228h, 238h, 338h, 3F8h, 2F8h, 3E8h, and 2E8h.

Available Memory Ranges

The following memory range is available on the ISA bus:

- A0000h – B7FFFh
- D0000h – DFFFFh

IRQ SUPPORT

The following IRQs are available on the ISA bus: IRQ 3, IRQ 4, IRQ5, and IRQ 10.

Each of the four IRQs must be enabled in CMOS Setup before they can be used on the ISA bus. Because ISA IRQ sharing is not supported, make sure that any IRQ channel used for an ISA device is not used elsewhere. For example, if ISA IRQ 4 is enabled, you must use a different IRQ for COM1.

DMA and Bus Master Support

The VL-EBX-37 does not support PC/104 DMA or bus mastering.

Digital I/O (J17)

The 40-pin I/O connector (J17) incorporates 32 digital I/O lines. Table 12 shows the function of each pin. The digital I/O lines are controlled using the SPI registers. See "SPI Registers" for a complete description of the registers.

The digital lines are grouped into two banks of 16-bit bi-directional ports. The direction of each 8-bit port is controlled by software. The digital I/O lines are powered up in the input mode. The 24 mA source/sink drive and short protected outputs are an excellent choice for industrial LVTTTL interfacing. All I/O pins use +3.3V signaling.

Warning! Damage may occur if the I/O pins are connected to +5V logic.

Table 12: J17 I/O Connector Pinout

J17 Pin	Signal	VL-CBR-4004 Connector	VL-CBR-4004 Pin (Silkscreen)
1	Digital I/O 1	J1	5 (IO1)
2	Digital I/O 2		4 (IO2)
3	Digital I/O 3		3 (IO3)
4	Digital I/O 4		2 (IO4)
5	Ground		1 (GND1)
6	Digital I/O 5	J2	5 (IO5)
7	Digital I/O 6		4 (IO6)
8	Digital I/O 7		3 (IO7)
9	Digital I/O 8		2 (IO8)
10	Ground		1 (GND1)
11	Digital I/O 9	J3	5 (IO9)
12	Digital I/O 10		4 (IO10)
13	Digital I/O 11		3 (IO11)
14	Digital I/O 12		2 (IO12)
15	Ground		1 (GND2)
16	Digital I/O 13	J4	5 (IO13)
17	Digital I/O 14		4 (IO14)
18	Digital I/O 15		3 (IO15)
19	Digital I/O 16		2 (IO16)
20	Ground		1 (GND2)
21	Digital I/O 17	J6	1 (IO17)
22	Digital I/O 18		2 (IO18)
23	Digital I/O 19		3 (IO19)
24	Digital I/O 20		4 (IO20)
25	Ground		5 (GND3/PBRST#)
26	Digital I/O 21	J7	1 (IO21)
27	Digital I/O 22		2 (IO22)
28	Digital I/O 23		3 (IO23)
29	Digital I/O 24		4 (IO24)
30	Ground		5 (GND3)
31	Digital I/O 25	J8	1 (IO25)
32	Digital I/O 26		2 (IO26)
33	Digital I/O 27		3 (IO27)
34	Digital I/O 28		4 (IO28)
35	Ground		5 (GND4)
36	Digital I/O 29	J9	1 (IO29)
37	Digital I/O 30		2 (IO30)
38	Digital I/O 31		3 (IO31)
39	Digital I/O 32		4 (IO32)
40	Ground		5 (GND4)

DIGITAL I/O PORT CONFIGURATION USING THE SPI INTERFACE

Digital I/O channels 0-31 are accessed via SPI slave select 6 (writing 6h to the SS field in SPICONTROL). Each pair of I/O ports is configured by a set of paged I/O registers accessible through SPI. These registers control settings such as signal direction, input polarity, and interrupt source.

Digital I/O Initialization Using the SPI Interface

There are two Microchip MCP23S17 digital I/O devices used. Digital I/O channels 0-15 map to device #0 (address "000") and channels 15-31 to device #1 (address "001"). Please refer to the [Microchip MCP23S17 datasheet](#) for more information about the MCP23S17. Before accessing the digital I/O devices a '1' must be written to the control bit HAEN in the IOCON register (write a 8h to this register) in the MCP23S17 devices. This write is done to device address "000" which will actually write this HAEN bit to both devices. Once this HAEN bit is set then both devices can be independently accessed. This must be done anytime these parts are reset. Example code is shown below (this assumes the FPGA base address is the default setting CA0h).

```

MOV    DX, CA8h
MOV    AL, 26h      ;SPICONTROL: SPI Mode 00, 24bit, auto, SPI 6
OUT    DX, AL
MOV    DX, CA9h
MOV    AL, 30h      ;SPISTATUS: 8MHz, no IRQ, left-shift
OUT    DX, AL
MOV    DX, CABh
MOV    AL, 08h      ;SPIDATA1: Set HAEN Bit to a '1'
OUT    DX, AL
MOV    DX, CACH
MOV    AL, 0Ah      ;SPIDATA2: MCP23S17 IOCON addr 0x0A
OUT    DX, AL
MOV    DX, CADh
MOV    AL, 40h      ;SPIDATA3: MCP23S17 write to device "000"
OUT    DX, AL

BUSY:  MOV    DX, CA9h
        IN     AL, DX      ;Get SPI status
        AND    AL, 01h     ;Isolate the BUSY bit
        JNZ   BUSY        ;Loop back if SPI transaction is not complete

```

Digital I/O Interrupt Generation Using the SPI Interface

Digital I/O can be configured to issue hardware interrupts on the transition (high to low or low to high) of any digital I/O pin. IRQ assignment is made in SPI control register SPISTATUS. This IRQ is shared among all SPI devices connected to the VL-EBX-37 (the ADC and DAC devices on the SPI interface do not have interrupts). Digital I/O chip interrupt configuration is achieved through I/O port register settings. Please refer to the [Microchip MCP23S17 datasheet](#) for more information.

The on-board digital I/O chips must be configured for open-drain and mirrored interrupts in order for any SPI device to use hardware interrupts. The following code example illustrates how to do this for device #0 on channels 0-15. Normally, the BIOS initializes the on-board digital I/O chips at boot time.

```

MOV    DX, CA8h
MOV    AL, 26h      ;SPICONTROL: SPI Mode 00, 24bit, auto SPI 6
OUT    DX, AL
MOV    DX, CA9h
MOV    AL, 30h     ;SPISTATUS: 8MHz, no IRQ, left-shift
OUT    DX, AL
MOV    DX, CABh
MOV    AL, 44h     ;SPIDATA1: Mirror & Open-Drain interrupts
OUT    DX, AL
MOV    DX, CACH
MOV    AL, 0Ah     ;SPIDATA2: MCP23S17 address 0x0A
OUT    DX, AL
MOV    DX, CADh
MOV    AL, 40h     ;SPIDATA3: MCP23S17 write command
OUT    DX, AL

BUSY:  MOV    DX, CA9h
        IN    AL, DX      ;Get SPI status
        AND   AL, 01h     ;Isolate the BUSY bit
        JNZ   BUSY       ;Loop back if SPI transaction is not complete

MOV    DX, CA8h
MOV    AL, 27h     ;SPICONTROL: SPI Mode 00, 24bit, auto SPI 6
OUT    DX, AL
MOV    DX, CA9h
MOV    AL, 30h     ;SPISTATUS: 8MHz, no IRQ, left-shift
OUT    DX, AL
MOV    DX, CABh
MOV    AL, 44h     ;SPIDATA1: Mirror & Open-Drain interrupts
OUT    DX, AL
MOV    DX, CACH
MOV    AL, 0Ah     ;SPIDATA2: MCP23S17 address 0x0A
OUT    DX, AL
MOV    DX, CADh
MOV    AL, 40h     ;SPIDATA3: MCP23S17 write command
OUT    DX, AL

```

Writing to a Digital I/O Port Using the SPI Interface

The following code example initiates a write of 55h to Digital I/O port bits DIO15-DIO8.

```

;Write 44h to configure MCP23S17 register IOCON

MOV    DX, CA8h
MOV    AL, 26h     ;SPICONTROL: SPI Mode 00, 24bit, SPI 6
OUT    DX, AL
MOV    DX, CA9h
MOV    AL, 30h     ;SPISTATUS: 8MHz, no IRQ, left-shift
OUT    DX, AL
MOV    DX, CABh
MOV    AL, 44h     ;SPIDATA1: mirror and open-drain interrupts
OUT    DX, AL
MOV    DX, CACH
MOV    AL, 0Ah     ;SPIDATA2: MCP23S17 IOCON register address 0Ah
OUT    DX, AL
MOV    DX, CADh
MOV    AL, 40h     ;SPIDATA3: MCP23S17 write command
OUT    DX, AL
CALL   BUSY       ;Poll busy flag to wait for SPI transaction

```

```

;Configure MCP23S17 register IODIRA for outputs
    MOV     DX, CABh
    MOV     AL, 00h      ;SPIDATA1: 00h for outputs
    OUT     DX, AL
    MOV     DX, CACH
    MOV     AL, 00h      ;SPIDATA2: MCP23S17 register address 00h
    OUT     DX, AL
    MOV     DX, CADh
    MOV     AL, 40h      ;SPIDATA3: MCP23S17 write command
    OUT     DX, AL
    CALL    BUSY         ;Poll busy flag to wait for SPI transaction

;Write 55h to MCP23S17 register GPIOA
    MOV     DX, CABh
    MOV     AL, 55h      ;SPIDATA1: data to write
    OUT     DX, AL
    MOV     DX, CACH
    MOV     AL, 14h      ;SPIDATA2: MCP23S17 register address 14h
    OUT     DX, AL
    MOV     DX, CADh
    MOV     AL, 40h      ;SPIDATA3: MCP23S17 write command
    OUT     DX, AL
    CALL    BUSY         ;Poll busy flag to wait for SPI transaction

BUSY: MOV     DX, CA9h
      IN      AL, DX      ;Get SPSTATUS
      AND     AL, 01h     ;Isolate the BUSY flag
      JNZ     BUSY       ;Loop if SPI transaction not complete

```

Reading a Digital I/O Port Using the SPI Interface

The following code example reads the DIO15-DIO8 input lines.

```
'REGISTER ASSIGNMENT
'-----
CONST SPICONTROL1 = &HCA8
CONST SPICONTROL2 = &HCA9
CONST SPISTATUS = &HCA9
CONST SPIDATA1 = &HCAB
CONST SPIDATA2 = &HCAC
CONST SPIDATA3 = &HCAD

'INITIALIZE SPI CONTROLLER
'=====

'SPICONTROL1 Register
'-----
'D7 CPOL      = 0 SPI Clock Polarity (SCLK idles low)
'D6 CPHA      = 0 SPI Clock Phase (Data read on rising edge)
'D5 SPILEN1   = 1 SPI Frame Length (24-Bit)
'D4 SPILEN0   = 0 " " " "
'D3 MAN_SS    = 0 SPI Slave Select Mode (Automatic)
'D2 SS2       = 1 SPI Slave Select (On-Board DIO 0-15)
'D1 SS1       = 1 " " " "
'D0 SS0       = 0 " " " "
OUT SPICONTROL1, &H26

'SPICONTROL2 Register
'-----
'D7 IRQSEL1   = 0 IRQ Select (IRQ3)
'D6 IRQSEL0   = 0 " " "
'D5 SPICLK1   = 1 SPI SCLK Frequency (8.333 MHz)
'D4 SPICLK0   = 1 " " " "
'D3 HW_IRQ_EN = 0 Hardware IRQ Enable (Disabled)
'D2 LSBIT_1ST = 0 SPI Shift Direction (Left Shifted)
'D1 0         = 0 This bit has no function
'D0 0         = 0 This bit has no function
OUT SPICONTROL2, &H30

'INITIALIZE MCP23S17
'=====

'MCP23S17 IOCON Register
'-----
'D7 BANK      = 0 Registers in same bank (addresses are sequential)
'D6 MIRROR    = 1 The INT pins are internally connected
'D5 SEQOP     = 0 Sequential op disabled. Addr ptr does not increment.
'D4 DISSLW    = 0 Slew rate control for SDA output (enabled)
'D3 HAEN      = 0 Hardware address enable (addr pins disabled)
'D2 ODR       = 1 INT pin is open-drain
'D1 INTPOL    = 0 Polarity of INT output pin (ignored when ODR=1)
'D0 0         = 0 This bit has no function
OUT SPIDATA1, &H44

'MCP23S17 IOCON Register Address
'-----
OUT SPIDATA2, &HA

'MCP23S17 SPI Control Byte (Write)
'-----
'D7 SLAVEFA3  = 0 Slave Address (Fixed Portion)
```

```

'D6 SLAVEFA2 = 1 " " " "
'D5 SLAVEFA1 = 0 " " " "
'D4 SLAVEFA0 = 0 " " " "
'D3 SLAVEHA2 = 0 Slave Address Bits (Hardware Address Bits)
'D2 SLAVEHA1 = 0 " " " "
'D1 SLAVEHA0 = 0 " " " "
'D0 READWRITE = 0 Read/Write Bit = Write
OUT SPIDATA3, &H40

WHILE (INP(SPISTATUS) AND &H1) = &H1: WEND

'INITIALIZE DIRECTION OF DIO LINES D15-D8 AS INPUTS
'=====

'Direction = All Inputs
OUT SPIDATA1, &HFF

'MCP23S17 IODIRA Register Address
OUT SPIDATA2, &H0

'MCP23S17 SPI Control Byte (Write)
OUT SPIDATA3, &H40

WHILE (INP(SPISTATUS) AND &H1) = &H1: WEND

'Repeat until ESC key is pressed
WHILE INKEY$ <> CHR$(27)

'READ DIO INPUT DATA FROM MCP23S17
'-----

'MCP23S17 GPIOA Register Address
OUT SPIDATA2, &H12

'MCP23S17 SPI Control Byte (Read)
OUT SPIDATA3, &H41

WHILE (INP(SPISTATUS) AND &H1) = &H1: WEND

'DIO Input Data
PRINT HEX$(INP(SPIDATA1))

WEND

SYSTEM

```

Utility I/O (J18)

A number of interfaces on the VL-EBX-37 are grouped together and made accessible through utility I/O connector J18. Cables and boards are available from VersaLogic that provide discrete connectors for each of the interfaces; however, you can create custom cables that surface only the interfaces required by your application.

The 50-pin I/O connector incorporates the COM ports, PS/2 keyboard and mouse, programmable LED, reset button, and speaker interfaces. Table 13 illustrates the function of each pin. The +5V power lines provided to J13 are protected by a 1 Amp fuse.

Table 13: J18 I/O Connector Pinout

J18 Pin	VL-CBR-5009 Connector	Pin	Signal	
1	COM1 J3 Top DB9	1	Data Carrier Detect	
2		6	Data Set Ready	
3		2	Receive Data	
4		7	Request to Send	
5		3	Transmit Data	
6		8	Clear to Send	
7		4	Data Terminal Ready	
8		9	Ring Indicator	
9		5	Ground	
10	COM2 J3 Bottom DB9	1	Data Carrier Detect	
11		6	Data Set Ready	
12		2	Receive Data	
13		7	Request to Send	
14		3	Transmit Data	
15		8	Clear to Send	
16		4	Data Terminal Ready	
17		9	Ring Indicator	
18		5	Ground	
19	COM3 J6		RS-232	RS-422/485
20		1	Ground	Ground
21		5	RTS	TxD+
22		4	TXD	TxD-
23		–	Ground	Ground
24		2	RXD	RxD-
25		3	CTS	RxD+
		–	Ground	Ground
26	COM4 J5	1	Ground	Ground
27		5	RTS	TxD+
28		4	TXD	TxD-
29		–	Ground	Ground
30		2	RXD	RxD-
31	3	CTS	RxD+	
32	–	Ground	Ground	
33	Mouse J4 Top	4	+5V (Protected)	
34		1	Mouse Data	
35		3	Ground	
36		5	Mouse Clock	
37*	PBRESET S1	1	Pushbutton Reset	
38		2	Ground	
39	PBRESET* J2	1	Ground	
40		4	Not connected	
41		3	Ground	
42		5	Not connected	
43	Keyboard J4 Bottom	4	+5V (Protected)	
44		1	Keyboard Data	
45		3	Ground	
46	5	Keyboard Clock		
47	PLED D1	1	+5V (Protected)	
48		2	Programmable LED	
49	Speaker SP1	1	+5V (Protected)	
50		2	Speaker Drive	

* The pushbutton reset signal from J18 pin 37 is also routed to VL-CBR-5009 J2 pin 2.

Serial Ports (J18)

The VL-EBX-37 features four on-board 16550-based serial channels located at standard PC I/O addresses. COM1 and COM2 are RS-232 (115.2 Kbps) serial ports. IRQ lines are chosen in CMOS Setup. COM ports normally cannot share interrupts with other COM ports or with other devices.

COM3 and COM4 can be operated in RS-232 4-wire, RS-422 or RS-485 modes. Additional non-standard baud rates are also available (programmable in the normal baud registers) of up to 921 Kbps. IRQ lines are chosen in CMOS Setup.

Each COM port can be independently enabled, disabled, or assigned a different I/O base address in CMOS Setup.

COM PORT CONFIGURATION

There are no configuration jumpers for COM1 and COM2 since they only operate in RS-232 mode. Use CMOS Setup to select between RS-232 4-wire, RS-422, and RS485 operating modes for COM3 and COM4.

Jumper block V3 is used to enable the RS-422/485 termination resistor for COM3 and COM4. Jumper V3[1-2] enables the RS-422/485 termination resistor for COM3, and jumper V3[3-4] for COM4. The termination resistor should be enabled for RS-422 and the RS-485 endpoint station. It should be disabled for RS-232 and the RS-485 intermediate station.

If RS-485 mode is used, the half-duplex differential twisted pair (TxD+/RxD+ and TxD-/RxD-) is formed by connecting both transmit and receive pairs together. For example, on VL-CBR-5009 connectors J6 and J5, the TxD+/RxD+ signal is formed by connecting pins 3 and 5, and the TxD-/RxD- signal is formed by connecting pins 2 and 4.

COM3 / COM4 RS-485 MODE LINE DRIVER CONTROL

The VL-EBX-37 features automatic RS-485 direction control for COM3 and COM4. The purpose of this function is to save the effort of RS-485 direction control in software. The direction control signal RTS is used to tri-state the transmitter when no other data is available, so that other nodes can use the shared lines.

RS-485 direction control is set using the Serial Port 3 > Mode and Serial Port 4 > Mode parameters in CMOS Setup. To enable manual direction control, set the COM port mode to RS485 ManuFC; to enable auto direction control, set the parameter to RS485 AutoFC. Manual direction control is configured by asserting the RTS handshake line. Asserting the RTS handshake line puts the RS-485 port in transmit mode; de-asserting the line puts it in receive mode.

SERIAL PORT CONNECTORS

The pinouts of the DB-9M connectors apply to the serial connectors on the VersaLogic breakout board VL-CBR-5009.

These connectors are protected against ESD damage.

Table 14: COM1-2 Pinout – VL-CBR-5009 Connector J3

COM1	COM2	RS-232
Top DB-9 J3 Pin	Bottom DB-9 J3 Pin	
1	1	DCD
2	2	RXD*
3	3	TXD*
4	4	DTR
5	5	Ground
6	6	DSR
7	7	RTS
8	8	CTS
9	9	RI

Table 15: COM3-4 Pinout – VL-CBR-5009 Connectors J5-6

COM3	COM4	RS-232	RS-422	RS-485
J6 Pin	J5 Pin			
1	1	Ground	Ground	Ground
2	2	RXD	RxD-	RxD-
3	3	CTS	RxD+	RxD+
4	4	TXD	TxD-	TxD-
5	5	RTS	TxD+	TxD+

PS/2 Keyboard and Mouse (J18)

A standard PS/2 keyboard and mouse interface is accessible through connector J4 of the VersaLogic VL-CBR-5009 breakout board. The breakout board is connected to connector J18 of the VL-EBX-37. The +5V power provided to the keyboard and mouse is protected by a 1 Amp fuse.

This connector uses IEC 61000-4-2-rated TVS components to help protect against ESD damage.

Table 16: PS/2 Mouse and Keyboard Pinout

VL-CBR-5009 J4 Top Pin	Signal	Description
1	MSDATA	Mouse Data
2	–	No Connection
3	GND	Ground
4	MKPWR	+5V (Protected)
5	MSCLK	Mouse Clock
6	–	No Connection
VL-CBR-5009 J4 Bottom Pin	Signal	Description
1	KBDATA	Keyboard Data
2	–	No Connection
3	GND	Ground
4	MKPWR	+5V (Protected)
5	KBCLK	Keyboard Clock
6	–	No Connection

Programmable LED (J18)

Connector J18 includes an output signal for attaching a software controlled LED. Connect the cathode of the LED to J18, pin 48, and connect the anode to +5V. An on-board resistor limits the current to 15 mA when the circuit is turned on. A programmable LED is provided on the VL-CBR-5009 breakout board.

To turn the LED on and off, set or clear bit D7 in I/O port CA0h (or C90h). When changing the register, make sure not to alter the values of the other bits.

The following code examples show how to turn the LED on and off. Refer to page 54 for further information:

LED On		LED Off	
MOV	DX, CA0H	MOV	DX, CA0H
IN	AL, DX	IN	AL, DX
OR	AL, 80H	AND	AL, 7FH
OUT	DX, AL	OUT	DX, AL

Note The LED is turned on by the BIOS during system startup. This causes the light to function as a "power on" indicator if it is not otherwise controlled by user code.

External Speaker (J18)

A miniature 8 ohm speaker can be connected between J18 pins 50 and 49. A speaker is provided on the VL-CBR-5009 breakout board.

Push-Button Reset (J18)

Connector J18 includes an input for a push-button reset switch. Shorting J18 pin 37 to ground causes the VL-EBX-37 to reboot. This connector is protected against ESD damage.

A reset button is provided on the VL-CBR-5009 breakout board.

Analog Input (J22)

The VL-EBX-37 uses a multi-range, 12-bit Linear Technology LTC1857 A/D converter with eight single-ended input signals (even and odd analog channels, for example inputs 1 and 2, can also be combined as differential inputs). The converter has a 100 kilo-samples-per-second (Ksps) sampling rate, with a 4 μ s acquisition time, with per-channel input ranges of 0 to +5V, \pm 5V, 0 to +10V and \pm 10V.

The VL-EBX-37 A/D converter is controlled using the SPI registers. The A/D converter is accessed via SPI slave select 5 (writing 5h to the SS field in SPICONTROL).

See "SPI Registers" for a complete description of the registers.

See the [Linear Technology LTC1857 A/D Converter Datasheet](#) for programming information.

Warning! Application of analog voltages greater than +25V or less than -25V can damage the converter.

Note: Custom models of the VL-EBX-37 can accommodate 16 A/D channels. Contact Sales@VersaLogic.com for more information on custom orders.

EXTERNAL CONNECTIONS

Single-ended analog voltages are applied to connector J22 as shown in the following table. Standard VL-EBX-37 models include eight analog input channels.

Table 17: Analog Input Pinout

J22 Pin	Signal	VL-CBR-4004 Connector	VL-CBR-4004 Pin (Silkscreen)
1	Analog Input 1	J1 Analog Input	5 (IO1)
2	Analog Input 2		4 (IO2)
3	Analog Input 3		3 (IO3)
4	Analog Input 4		2 (IO4)
5	Ground		1 (GND1)
6	Analog Input 5	J2 Analog Input	5 (IO5)
7	Analog Input 6		4 (IO6)
8	Analog Input 7		3 (IO7)
9	Analog Input 8		2 (IO8)
10	Ground		1 (GND1)
11	Analog Input 9	J3 Analog Input (Custom*)	5 (IO9)
12	Analog Input 10		4 (IO10)
13	Analog Input 11		3 (IO11)
14	Analog Input 12		2 (IO12)
15	Ground		1 (GND2)
16	Analog Input 13	J4 Analog Input (Custom*)	5 (IO13)
17	Analog Input 14		4 (IO14)
18	Analog Input 15		3 (IO15)
19	Analog Input 16		2 (IO16)
20	Ground		1 (GND2)

* Contact Sales@VersaLogic.com for information on custom orders.

ANALOG INPUT USING THE SPI INTERFACE

See "SPI Registers" for a description of the SPI interface and registers.

Initiating an Analog Conversion Using the SPI Interface

The following procedure can be used to initiate an analog conversion using the SPI interface.

1. Write 15h to the SPICONTROL register (I/O address CA8h) – This value configures the SPI port to select the on-board A/D converter, 16-bit frame length, low SCLK idle state, rising edge SCLK edge, and automatic slave select.
2. Write 10h to the SPISTATUS register (I/O address CA9h) – This value selects 2 MHz SCLK speed, hardware IRQ disable, and left-shift data. A 2 MHz clock is used to avoid having to insert a delay after the SPI cycle to wait for the end of the 4 μ s A/D signal acquisition interval. If a 4 MHz SPI clock is used then there must be a delay of 1.5 μ s after the SPI cycle ends before starting an A/D conversion; if an 8 MHz SPI clock is used then there must be a delay of 2.75 μ s after the end of the SPI cycle.
3. Write any value to SPIDATA2 (I/O address CACH) – This data will be ignored by the A/D converter.

4. Write bit 0 of the analog input channel number to Bit 6, bits 2-1 of the analog input channel number to bits 5-4, and a 2-bit input range code to bits 3-2 of SPIDATA3 (I/O address CADh) – Any write operation to this register triggers an SPI transaction. The 2-bit input-range codes are 0 ($\pm 5V$), 1 ($\pm 10V$), 2 (0 to +5V) or 3 (0 to +10V). For example, if converting the 4th A/D channel (channel number 3) with a 0 to +5V range then SPIDATA3 is set to 58h
5. Poll the SPI BUSY bit in the SPISTATUS register until the conversion is completed.
6. Write a '1' to ADCONVST0 Bit 0 of the FPGA ADC, DAC control/status register (I/O address CAFh) to start a conversion
7. Poll the ADCBUSY0 Bit 2 of the FPGA ADC/DAC control/status register (I/O address CAFh) until this bit is a '0' (not busy) to indicate a conversion is completed (a conversion takes a maximum of 5 μs).
8. Read the conversion data from SPIDATA3 (upper 8 bits of the 12-bit conversion) and SPIDATA2 (lower 4 bits of the 12-bit conversion are in the upper 4 bits of this byte). The data read is from the previous conversion not the one for the SPI values written in Steps 1–5. Another conversion cycle is required to retrieve that data. Typically a number of channels are sampled at one time so this conversion delay is not significant.

Anytime an SPI command is written to the A/D device a conversion must be issued for that command. Another command will not be accepted until a conversion is performed.

Analog Output (J22)

The VL-EBX-37 uses a 12-bit Linear Technology LTC2634 D/A converter with four (4) single-ended output signals. The converter has 5 μ s per-channel update rate with a 0 to 4.096V output voltage range. There is an expansion option to increase the output channels to eight (8).

The VL-EBX-37 D/A converter is controlled using the SPI registers. The D/A converter is accessed via SPI slave select 7 (writing 7h to the SS field in SPICONTROL). See "SPX Expansion Bus (J23)" for a complete description of the registers.

See the [Linear Technology LTC2634 D/A Converter Datasheet](#) for programming information.

Table 18: Analog Output Pinout

J22 Pin	Signal	VL-CBR-4004 Connector	VL-CBR-4004 Pin (Silkscreen)
21	Analog Output 1	J6 Analog Output	1 (IO17)
22	Analog Output 2		2 (IO18)
23	Analog Output 3		3 (IO19)
24	Analog Output 4		4 (IO20)
25	Ground		5 (GND3/PBRST#)
26	Analog Output 5	J7 Analog Output (Custom*)	1 (IO21)
27	Analog Output 6		2 (IO22)
28	Analog Output 7		3 (IO23)
29	Analog Output 8		4 (IO24)
30	Ground		5 (GND3)

* Contact Sales@VersaLogic.com for information on custom orders.

Analog Output Using the SPI Interface

The following procedure can be used to set an analog output using the SPI interface.

1. Write 27h to the SPICONTROL register (I/O address CA8h) – This value configures the SPI port to select the D/A converter, 24-bit frame length, low SCLK idle state, rising edge SCLK edge, and automatic slave select.
2. Write 30h to the SPISTATUS register (I/O address CA9h) – This value selects 8 MHz SCLK speed, hardware IRQ disable, and left-shift data.
3. Write the LS 4-bits of the 12-bit output value into the MS 4-bits of SPIDATA1 (I/O address CABh). For example, if writing a 12-bit value of 123h the value of 30h is written to SPIDATA1.
4. Write the MS 8-bits of the 12-bit output value to SPIDATA2 (I/O address CACh). For example, if writing a 12-bit value of 123h the value of 12h is written to SPIDATA2.
5. Write the analog output channel number (0 to 3) to Bits 3-0 and the write-and-update-channel command 3h to Bits 7-4 of SPIDATA3 (I/O address CADh) – Any write operation to this register triggers an SPI transaction. For example, if writing to the third DAC channel (channel number 2) the value written to SPIDATA3 is 32h.
6. Poll the SPI BUSY bit in the SPISTATUS register until the conversion is completed.
7. The D/A output will be stable in no more than 5 μ s.

Counter Timers (J22)

The VL-EBX-37 includes three uncommitted 8254 type counter/timer channels for general program use. External control signals for the three channels are available on connector J22 (see Table 19).

Table 19: J22 Counter Timer Pinout

J22 Pin	Signal Direction*	Signal Name	Function	VL-CBR-4004 Connector	VL-CBR-4004 Pin (Silkscreen)
31	Output	OCTC3	Timer 3 Counter Output	J8	1 (IO25)
32	Input	GCTC3	Timer 3 Gate Input		2 (IO26)
33	Input	ICTC3	Timer 3 Clock Input		3 (IO27)
34	Output	OCTC4	Timer 4 Counter Output		4 (IO28)
36	Input	GCTC4	Timer 4 Gate Input	J9	1 (IO29)
37	Input	ICTC4	Timer 4 Clock Input		2 (IO30)
38	Output	OCTC5	Timer 5 Counter Output		3 (IO31)
39	Input	GCTC5	Timer 5 Gate Input		4 (IO32)

* Relative to VL-EBX-37

The Custom Programming appendix discusses how to use and configure these timers using the following registers.

Register	Read/Write	Address	Name
IRQCTRL	R/W	CA3h or C93h	Interrupt Control Register
IRQSTAT	R-Status/Write-Clear	CA4h or C94h	Interrupt Status Register
TMCNTRL	R/W	CA5h or C95h	Timer Control Register
TIMBASEMS	R/W	CA6h or C96h	Timer Base MS Address Register
TIMBASELS	R/W	CA7h or C97h	Timer Base LS Address Register

SPX Expansion Bus (J23)

Up to four serial peripheral expansion (SPX) devices can be attached to the VL-EBX-37 at connector J23 using the VL-CBR-1401 or VL-CBR-1402 cable. The SPX interface provides the standard serial peripheral interface (SPI) signals: SCLK, MISO, and MOSI, as well as four chip selects, SS0# to SS3#, and an interrupt input, SINT#.

The +5V power provided to pins 1 and 14 of J23 is protected by a 1 Amp resettable fuse.

Table 20: SPX Expansion Bus Pinout

J23 Pin	Signal Name	Function
1	V5_0	+5V (Protected)
2	SCLK	Serial Clock
3	GND	Ground
4	MISO	Serial Data In
5	GND	Ground
6	MOSI	Serial Data Out
7	GND	Ground
8	SS0#	Chip Select 0
9	SS1#	Chip Select 1
10	SS2#	Chip Select 2
11	SS3#	Chip Select 3
12	GND	Ground
13	SINT#	Interrupt Input
14	V5_0	+5V (Protected)

SPI is, in its simplest form, a three wire serial bus. One signal is a Clock, driven only by the permanent Master device on-board. The others are Data In and Data Out with respect to the Master. The SPX implementation adds additional features, such as chip selects and an interrupt input to the Master. The Master device initiates all SPI transactions. A slave device responds when its Chip Select is asserted and it receives Clock pulses from the Master.

The SPI clock rate can be software configured to operate at speeds between 1 MHz and 8 MHz. Please note that since this clock is divided from a 33 MHz PCI clock, the actual generated frequencies are not discrete integer MHz frequencies. All four common SPI modes are supported through the use of clock polarity and clock idle state controls.

VERSALOGIC SPX EXPANSION MODULES

VersaLogic offers a number of SPX modules that provide a variety of standard functions, such as analog input, digital I/O, CANbus controller, and others. These are small boards (1.2" x 3.78") that can mount on the PC/104 stack, using standard standoffs, or up to two feet away from the baseboard. For more information, contact VersaLogic at info@VersaLogic.com.

SPI REGISTERS

A set of control and data registers are available for SPI transactions. The following tables describe the SPI control registers (SPICONTROL and SPISTATUS) and data registers (SPIDATA3-0).

SPICONTROL (READ/WRITE) CA8h (or C98h)

D7	D6	D5	D4	D3	D2	D1	D0
CPOL	CPHA	SPILEN1	SPILEN0	MAN_SS	SS2	SS1	SS0

Table 21: SPI Control Register 1 Bit Assignments

Bit	Mnemonic	Description																																				
D7	CPOL	SPI Clock Polarity – Sets the SCLK idle state. 0 = SCLK idles low 1 = SCLK idles high																																				
D6	CPHA	SPI Clock Phase – Sets the SCLK edge on which valid data will be read. 0 = Data read on rising edge 1 = Data read on falling edge																																				
D5-D4	SPILEN	SPI Frame Length – Sets the SPI frame length. This selection works in manual and auto slave select modes. <table border="1"> <thead> <tr> <th>SPILEN1</th> <th>SPILEN0</th> <th>Frame Length</th> </tr> </thead> <tbody> <tr> <td>0</td> <td>0</td> <td>8-bit</td> </tr> <tr> <td>0</td> <td>1</td> <td>16-bit</td> </tr> <tr> <td>1</td> <td>0</td> <td>24-bit</td> </tr> <tr> <td>1</td> <td>1</td> <td>32-bit</td> </tr> </tbody> </table>	SPILEN1	SPILEN0	Frame Length	0	0	8-bit	0	1	16-bit	1	0	24-bit	1	1	32-bit																					
SPILEN1	SPILEN0	Frame Length																																				
0	0	8-bit																																				
0	1	16-bit																																				
1	0	24-bit																																				
1	1	32-bit																																				
D3	MAN_SS	SPI Manual Slave Select Mode – This bit determines whether the slave select lines are controlled through the user software or are automatically controlled by a write operation to SPIDATA3 (CADh). If MAN_SS = 0, then the slave select operates automatically; if MAN_SS = 1, then the slave select line is controlled manually through SPICONTROL bits SS2, SS1, and SS0. 0 = Automatic, default 1 = Manual																																				
D2-D0	SS	SPI Slave Select – These bits select which slave select will be asserted. The SSx# pin on the baseboard will be directly controlled by these bits when MAN_SS = 1. <table border="1"> <thead> <tr> <th>SS2</th> <th>SS1</th> <th>SS0</th> <th>Slave Select</th> </tr> </thead> <tbody> <tr> <td>0</td> <td>0</td> <td>0</td> <td>None, port disabled</td> </tr> <tr> <td>0</td> <td>0</td> <td>1</td> <td>SPX Slave Select 0, J23 pin-8</td> </tr> <tr> <td>0</td> <td>1</td> <td>0</td> <td>SPX Slave Select 1, J23 pin-9</td> </tr> <tr> <td>0</td> <td>1</td> <td>1</td> <td>SPX Slave Select 2, J23 pin-10</td> </tr> <tr> <td>1</td> <td>0</td> <td>0</td> <td>SPX Slave Select 3, J23 pin-11</td> </tr> <tr> <td>1</td> <td>0</td> <td>1</td> <td>A/D Converter (on-board)</td> </tr> <tr> <td>1</td> <td>1</td> <td>0</td> <td>Digital I/O (on-board)</td> </tr> <tr> <td>1</td> <td>1</td> <td>1</td> <td>D/A Converter (on-board)</td> </tr> </tbody> </table>	SS2	SS1	SS0	Slave Select	0	0	0	None, port disabled	0	0	1	SPX Slave Select 0, J23 pin-8	0	1	0	SPX Slave Select 1, J23 pin-9	0	1	1	SPX Slave Select 2, J23 pin-10	1	0	0	SPX Slave Select 3, J23 pin-11	1	0	1	A/D Converter (on-board)	1	1	0	Digital I/O (on-board)	1	1	1	D/A Converter (on-board)
SS2	SS1	SS0	Slave Select																																			
0	0	0	None, port disabled																																			
0	0	1	SPX Slave Select 0, J23 pin-8																																			
0	1	0	SPX Slave Select 1, J23 pin-9																																			
0	1	1	SPX Slave Select 2, J23 pin-10																																			
1	0	0	SPX Slave Select 3, J23 pin-11																																			
1	0	1	A/D Converter (on-board)																																			
1	1	0	Digital I/O (on-board)																																			
1	1	1	D/A Converter (on-board)																																			

SPISTATUS (READ/WRITE) CA9h (or C99h)

D7	D6	D5	D4	D3	D2	D1	D0
IRQSEL1	IRQSEL0	SPICLK1	SPICLK0	HW_IRQ_EN	LSBIT_1ST	HW_INT	BUSY

Table 22: SPI Control Register 2 Bit assignments

Bit	Mnemonic	Description															
D7-D6	IRQSEL	<p>IRQ Select – These bits select which IRQ will be asserted when a hardware interrupt from a connected SPI device occurs. The HW_IRQ_EN bit must be set to enable SPI IRQ functionality.</p> <table border="1"> <thead> <tr> <th>IRQSEL1</th> <th>IRQSEL0</th> <th>IRQ</th> </tr> </thead> <tbody> <tr> <td>0</td> <td>0</td> <td>IRQ3</td> </tr> <tr> <td>0</td> <td>1</td> <td>IRQ4</td> </tr> <tr> <td>1</td> <td>0</td> <td>IRQ5</td> </tr> <tr> <td>1</td> <td>1</td> <td>IRQ10</td> </tr> </tbody> </table>	IRQSEL1	IRQSEL0	IRQ	0	0	IRQ3	0	1	IRQ4	1	0	IRQ5	1	1	IRQ10
IRQSEL1	IRQSEL0	IRQ															
0	0	IRQ3															
0	1	IRQ4															
1	0	IRQ5															
1	1	IRQ10															
D5-D4	SPICLK	<p>SPI SCLK Frequency – These bits set the SPI clock frequency.</p> <table border="1"> <thead> <tr> <th>SPICLK1</th> <th>SPICLK0</th> <th>Frequency</th> </tr> </thead> <tbody> <tr> <td>0</td> <td>0</td> <td>1.042 MHz</td> </tr> <tr> <td>0</td> <td>1</td> <td>2.083 MHz</td> </tr> <tr> <td>1</td> <td>0</td> <td>4.167 MHz</td> </tr> <tr> <td>1</td> <td>1</td> <td>8.333 MHz</td> </tr> </tbody> </table>	SPICLK1	SPICLK0	Frequency	0	0	1.042 MHz	0	1	2.083 MHz	1	0	4.167 MHz	1	1	8.333 MHz
SPICLK1	SPICLK0	Frequency															
0	0	1.042 MHz															
0	1	2.083 MHz															
1	0	4.167 MHz															
1	1	8.333 MHz															
D3	HW_IRQ_EN	<p>Hardware IRQ Enable – Enables or disables the use of the selected IRQ (IRQSEL) by an SPI device. 0 = SPI IRQ disabled, default 1 = SPI IRQ enabled</p> <p>Note: The selected IRQ is shared with PC/104 ISA bus devices. CMOS settings must be configured for the desired ISA IRQ.</p>															
D2	LSBIT_1ST	<p>SPI Shift Direction – Controls the SPI shift direction of the SPIDATA registers. The direction can be shifted toward the least significant bit or the most significant bit. 0 = SPIDATA data is left-shifted (MSbit first), default 1 = SPIDATA data is right-shifted (LSbit first)</p>															
D1	HW_INT	<p>SPI Device Interrupt State – This bit is a status flag that indicates when the hardware SPX signal SINT# is asserted. 0 = Hardware interrupt on SINT# is deasserted 1 = Interrupt is present on SINT#</p> <p>This bit is read-only and is cleared when the SPI device’s interrupt is cleared.</p>															
D0	BUSY	<p>SPI Busy Flag – This bit is a status flag that indicates when an SPI transaction is underway. 0 = SPI bus idle 1 = SCLK is clocking data in and out of the SPIDATA registers</p> <p>This bit is read-only.</p>															

SPIDATA0 (READ/WRITE) CAAh (or C9Ah)

D7	D6	D5	D4	D3	D2	D1	D0
MSbit							LSbit

SPIDATA1 (READ/WRITE) CABh (or C9Bh)

D7	D6	D5	D4	D3	D2	D1	D0
MSbit							LSbit

SPIDATA2 (READ/WRITE) CACH (or C9Ch)

D7	D6	D5	D4	D3	D2	D1	D0
MSbit							LSbit

SPIDATA3 (READ/WRITE) CADh (or C9Dh)

D7	D6	D5	D4	D3	D2	D1	D0
MSbit							LSbit

SPIDATA3 contains the most significant byte (MSB) of the SPI data word. A write to this register will initiate the SPI clock and, if the MAN_SS bit = 0, will also assert a slave select to begin an SPI bus transaction. Increasing frame sizes from 8-bit uses the lowest address for the least significant byte of the SPI data word; for example, the LSB of a 24-bit frame would be SPIDATA1. Data is sent according to the LSBIT_1ST setting. When LSBIT_1ST = 0, the MSbit of SPIDATA3 is sent first, and received data will be shifted into the LSbit of the selected frame size set in the SPILEN field. When LSBIT_1ST = 1, the LSbit of the selected frame size is sent first, and the received data will be shifted into the MSbit of SPIDATA3.

Data returning from the SPI target will normally have its most significant data in the SPIDATA3 register. An exception will occur when LSBIT_1ST = 1 to indicate a right-shift transaction. In this case the most significant byte of an 8-bit transaction will be located in SPIDATA0, a 16-bit transaction's most significant byte will be located in SPIDATA1, and a 24-bit transaction's most significant byte will be located in SPIDATA2.

Audio (J26)

Connector J26 provides an audio interface using the IDT 92HD75B (S and E models) or 92HD87B (A and F models) Audio Codec. Drivers are available for most Windows-based operating systems. The interface provides the line-level stereo input and line-level stereo output connection points. The outputs will drive any standard-powered PC speaker set. This interface is protected against ESD damage. difference

Table 23: Audio Pinout

J26 Pin	Signal Name	Function
1	LINE_OUTR	Line-Out Right
2	Ground	Ground
3	LINE_OUTL	Line-Out Left
4	Ground	Ground
5	LINE_INR	Line-In Right
6	Ground	Ground
7	LINE_INL	Line-In Left
8	Ground	Ground

eUSB Solid State Drive (J27)

Connector J27 on the bottom board provides an interface for an eUSB solid state drive (SSD). The VersaLogic VL-F15 series of eUSB SSDs come in a variety of sizes from 2-8 GB, as well as standard and extended temperature ratings. Contact [VersaLogic Sales](#) for information. eUSB modules are secured to the board using the VL-HDW-109 hardware kit from VersaLogic. The kit contains one M2.5 x 6 mm round aluminum standoff and two M2.5 x 4 mm pan head Philips screws.

System Interrupts and I/O Devices

Interrupts

The VL-EBX-37 has the standard complement of PC-type interrupts. Up to eight IRQ lines can be allocated as needed to PCI devices. There are no interrupt configuration jumpers. All configuration is handled through CMOS Setup.

Table 24: VL-EBX-37 IRQ Settings

● = default setting ○ = allowed setting

Source	IRQ															
	0	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
Timer 0	●															
Keyboard		●														
Slave PIC			●													
COM1				○	●	○		○								
COM2				●	○	○		○								
COM3				○	○	○		○								
COM4				○	○	○		○								
Floppy							●									
RTC								●								
Mouse													●			
Math Chip														●		
Pri. IDE															●	
SPX				○	○	○					○					
Fan Tach.								○								
PCI INTA#					○					○	○	●				
PCI INTB#					○					○	○	●				
PCI INTC#					○					○	○	●				
PCI INTD#					○					●	○	○				
PCI INTE#					○					●	○	○				
PCI INTF#					○					●	○	○				
PCI INTG#					○					●	○	○				
PCI INTH#					○					●	○	○				

PCI interrupt routings apply to legacy Programmable Interrupt Controller (PIC) mode. When the OS switches to Advanced PIC (APIC) mode, PCI devices use IRQs beyond IRQ 15.

Table 25: PCI Interrupt Settings

Source	PCI Interrupt						
	INTA#	INTB#	INTC#	INTD#	INTE#	INTF#	INTG#
82541IT Ethernet	●						
82574IT Ethernet				●			
SATA		●					
USB EHCI 1					●		
USB EHCI 2			●				
USB UHCI 1					●		
USB UHCI 2						●	
USB UHCI 3							●
USB UHCI 4	●						
USB UHCI 5		●					
USB UHCI 6			●				
Audio	●						
Video	●						
PCIe Port 1	●						
PCIe Port 2		●					
PCIe Port 4				●			

On-board I/O Devices

Table 26: On-board I/O Devices

I/O Device	Standard I/O Addresses
PLED and Product ID Register	CA0h
Revision Indicator Register	CA1h
BIOS and Jumper Status Register	CA2h
Interrupt Control Register	CA3h
Interrupt Status Register	CA4h
8254 Timer Control/Status Register	CA5h
8254 Timer MS Base Address Register	CA6h
8254 Timer LS Base Address Register	CA7h
SPX Control Register	CA8h
SPX Status Register	CA9h
SPX Data Register 0	CAAh
SPX Data Register 1	CABh
SPX Data Register 2	CACh
SPX Data Register 3	CADh
Reserved for System Test	CAEh
A/D, D/A Control/Status Register	CAFh



PLED and Product Code Register

PLEDPC (Read/Write) CA0h (or C90h)

D7	D6	D5	D4	D3	D2	D1	D0
PLED	PC6	PC5	PC4	PC3	PC2	PC1	PC0

Table 27: PLEDPC Register Bit Assignments

Bit	Mnemonic	Description																
D7	PLED	Light Emitting Diode — Controls the programmable LED on connector J18. 0 = Turns LED off 1 = Turns LED on																
D6-D0	PC	Product Code — These bits are hard-coded to represent the product type. The VL-EBX-37 is uniquely identified by the code 0000101. <table style="margin-left: auto; margin-right: auto;"> <tr> <td>PC6</td> <td>PC5</td> <td>PC4</td> <td>PC3</td> <td>PC2</td> <td>PC1</td> <td>PC0</td> <td>Product Code</td> </tr> <tr> <td>0</td> <td>0</td> <td>0</td> <td>0</td> <td>1</td> <td>0</td> <td>1</td> <td>VL-EBX-37</td> </tr> </table> These bits are read-only.	PC6	PC5	PC4	PC3	PC2	PC1	PC0	Product Code	0	0	0	0	1	0	1	VL-EBX-37
PC6	PC5	PC4	PC3	PC2	PC1	PC0	Product Code											
0	0	0	0	1	0	1	VL-EBX-37											

PLD Revision and Type Register

REVTYP (Read-only) CA1h (or C91h)

D7	D6	D5	D4	D3	D2	D1	D0
PLD4	PLD3	PLD2	PLD1	PLD0	TEMP	CUSTOM	BETA

This register is used to indicate the PLD revision level and model of the VL-EBX-37.

Table 28: Revision and Type Register Bit Assignments

Bit	Mnemonic	Description												
D7-D3	PLD	<p>PLD Code Revision Level — These bits are hard-coded and represent the PLD code revision.</p> <table> <tr> <td>PLD4</td> <td>PLD3</td> <td>PLD2</td> <td>PLD1</td> <td>PLD0</td> <td>Revision</td> </tr> <tr> <td>0</td> <td>0</td> <td>0</td> <td>0</td> <td>0</td> <td>Rev. 0.1x</td> </tr> </table> <p>These bits are read-only.</p>	PLD4	PLD3	PLD2	PLD1	PLD0	Revision	0	0	0	0	0	Rev. 0.1x
PLD4	PLD3	PLD2	PLD1	PLD0	Revision									
0	0	0	0	0	Rev. 0.1x									
D2	TEMP	<p>Temperature Rating — This bit indicates whether the VL-EBX-37 is rated for standard or extended temperature operation.</p> <p>0 = Standard temperature operation 1 = Extended temperature operation</p> <p>This bit is read-only.</p>												
D1	CUSTOM	<p>PLD Class — This bit indicates whether the PLD code is standard or customized.</p> <p>0 = Standard PLD code 1 = Custom PLD code</p> <p>This bit is read-only.</p>												
D0	BETA	<p>Production Level — This bit indicates if the PLD code is at the beta or production level.</p> <p>0 = Production level PLD 1 = Beta level PLD</p> <p>This bit is read-only.</p>												

Special Control Register

SCR (Read/Write) CA2h (or C92h)

D7	D6	D5	D4	D3	D2	D1	D0
BIOS_JMP	BIOS_OR	BIOS_SEL	Reserved	Reserved	Reserved	Reserved	Reserved

Table 29: Special Control Register Bit Assignments

Bit	Mnemonic	Description
D7	BIOS_JMP	System BIOS Selector Jumper Status — Indicates the status of the system BIOS selector jumper at V2[1-2]. 0 = Jumper installed – backup system BIOS selected 1 = No jumper installed – primary system BIOS selected This bit is read-only.
D6	BIOS_OR	BIOS Jumper Override — Overrides the system BIOS selector jumper and selects the BIOS with BIOS_SEL. 0 = No BIOS override 1 = BIOS override
D5	BIOS_SEL	BIOS Select — Selects the system BIOS when BIOS_OR is set. 0 = Backup BIOS selected 1 = Primary BIOS selected
D4-D0	Reserved	These bits are reserved. Only write 0 to these bits and ignore all read values.

Appendix A – References



CPU <i>Intel Core 2 Duo</i>	Intel Core 2 Duo Datasheet
Chipset <i>Intel GM45</i> <i>Intel ICH9</i>	Intel GM45 Datasheet Intel ICH9 Datasheet
Super I/O Chip <i>SMSC SCH3114</i>	SCH3114 Datasheet
Ethernet Controller <i>Intel 82574IT Ethernet Controller</i>	Intel 8257IT Datasheet
PC/104 Interface	PC/104 Specification
PC/104- <i>Plus</i> Interface	PC/104-<i>Plus</i> Specification

Appendix B – Custom Programming



PLD Interrupts

The PLD can generate interrupts for the internal 8254 timers and the external SPI interrupt (which includes the DIO device interrupt). The SPI interrupt settings are discussed in the section on “SPX Expansion Bus (J23).” This section covers the interrupt settings for the 8254 timers.

INTERRUPT CONTROL REGISTER

This register enables interrupts.

IRQCTRL (Read/Write) CA3h (or C93h)

D7	D6	D5	D4	D3	D2	D1	D0
IRQEN	IRQSEL2	IRQSEL1	IRQSEL0	reserved	IMSK_TC5	IMSK_TC4	IMSK_TC3

Table 30: Interrupt Control Register Bit Assignments

Bit	Mnemonic	Description
D7	IRQEN	IRQ Enable — Enables or disables an interrupt. 0 = Disable interrupt 1 = Enable interrupt
D6-D5	IRQSEL(2:0)	Specifies the interrupt mapping (this setting is ignored when IRQEN = 0 ... interrupts are disabled): "000" IRQ3 (default) "001" IRQ4 "010" IRQ5 "011" IRQ10 "100" IRQ6 "101" IRQ7 "110" IRQ9 "111" IRQ11
D4	Reserved	These bits are reserved. Only write 0 to these bits and ignore all read values.
D2	IMASK_TC5	Mask for the 8254 Timer #5 output (terminal count) Interrupt. 0 = Disable interrupt 1 = Enable interrupt
D1	IMASK_TC4	Mask for the 8254 Timer #4 output (terminal count) Interrupt. 0 = Disable interrupt 1 = Enable interrupt
D0	IMASK_TC3	Mask for the 8254 Timer #3 output (terminal count) Interrupt. 0 = Disable interrupt 1 = Enable interrupt

Note: IRQ3, IRQ4, IRQ5, IRQ10 are also defined for the SPX interface interrupts. If one of these interrupts is selected for the SPX interface and also enabled here for the timer interrupts, then the interrupt sources are combined (i.e., logically OR'd).

INTERRUPT STATUS REGISTER

This register is used for reading the status of interrupts generated by the PLD.

IRQSTAT (Read-Status/Write-Clear) CA4h (or C94h)

D7	D6	D5	D4	D3	D2	D1	D0
Reserved	Reserved	Reserved	Reserved	Reserved	ISTAT_TC5	ISTAT_TC4	ISTAT_TC3

Table 31: Interrupt Status Register Bit Assignments

Bit	Mnemonic	Description
D7-D3	Reserved	These bits are reserved. Only write 0 to these bits and ignore all read values.
D2	ISTAT_TC5	Status for the 8254 Timer #5 output (terminal count) Interrupt when read. 0 = Timer output (terminal count) has not transitioned from 0 to a 1 level 1 = Timer output (terminal count) has transitioned from a 0 to a 1 level This bit is read-status and a write-1-to-clear.
D1	ISTAT_TC4	Status for the 8254 Timer #4 output (terminal count) Interrupt when read. 0 = Timer output (terminal count) has not transitioned from 0 to a 1 level 1 = Timer output (terminal count) has transitioned from a 0 to a 1 level This bit is read-status and a write-1-to-clear.
D0	ISTAT_TC3	Status for the 8254 Timer #3 output (terminal count) Interrupt when read. 0 = Timer output (terminal count) has not transitioned from 0 to a 1 level 1 = Timer output (terminal count) has transitioned from a 0 to a 1 level This bit is read-status and a write-1-to-clear.

The interrupt status register is valid whether the interrupt mask is set or not for the interrupt (that is, it can be used for polled status). An interrupt status is acknowledged (cleared to a 0) by writing a '1' to the status bit.

The PLD implements an 8254 timer (consisting of three individual timers). The outputs of these timers can generate interrupts when they transition from a 0 level to a 1 level (edge sensitive).

8254 Timer Control Register

This register is used to set modes related to the inputs on the 8254 Timers.

TIMCNTRL (Read/Write) CA5h (or C95h)

D7	D6	D5	D4	D3	D2	D1	D0
TIM5GATE	TIM4GATE	TIM3GATE	TM4MODE	TM4SEL	TM3SEL	Reserved	Reserved

Table 32: 8254 Timer Control Register Bit Assignments

Bit	Mnemonic	Description
D7	TIM5GATE	Sets the level on the Gate input for the 8254 Timer #5. 0 = GCTC5 Gate is disabled (set to a logic 0) 1 = GCTC5 Gate is enabled (set to a logic 1)
D6	TIM4GATE	Sets the level on the Gate input for the 8254 Timer #4. 0 = GCTC4 Gate is disabled (set to a logic 0) 1 = GCTC4 Gate is enabled (set to a logic 1)
D5	TIM3GATE	Sets the level on the Gate input for the 8254 Timer #3. 0 = GCTC3 Gate is disabled (set to a logic 0) 1 = GCTC3 Gate is enabled (set to a logic 1)
D4	TM4MODE	Configure how the 8254 Timer #4 and #5 are used. 0 – Timer #4 is cascaded with Timer #5 for a 32-bit timer 1 – Timer #4 operates in normal 16-bit mode
D3	TM4SEL	Configure the clock source for 8254 Timer #4. 0 – Timer #4 input clock is from User I/O connector Input ICTC4 1 – Timer #4 input clock is 4.16625 MHz internal clock (PCI clock divided by 8)
D2	TM3SEL	Configure the clock source for 8254 Timer #3. 0 – Timer #3 input clock is from User I/O connector Input ICTC3 1 – Timer #3 input clock is 4.16625 MHz internal clock (PCI clock divided by 8)
D1-D0	Reserved	These bits are reserved. Only write 0 to these bits and ignore all read values.

An 8254 timer is implemented in the PLD. It contains three independent 16-bit timers. It is fully software compatible with the Intel 8254, except that only binary counting modes are implemented (the BCD control bit is implemented but ignored). See the [Intel 82C54 Programmable Interval Timer Datasheet](#) for register definitions and programming information.

There is an option to cascade two of the timers together in a 32-bit mode. The timers are identified as Timer 3, 4, and 5. When Timers 4 and 5 are cascaded, Timer 4 is the LS 16-bits and Timer 5 is the MS 16-bits. In this 32-bit cascade mode the timer output of Timer 4 feeds the clock input of Timer 5. In this mode Timer 4 would normally be set so that it generates a clock after counting the full 16-bit range, but there is no requirement to do this.

The 32-bit cascade mode is set in TM4MODE in the Timer Control Register. There are also internal or external clock selections for the timers in this register using the external clocks ICTC3 and ICTC4 signals on the connector at J22. The internal clock is the PCI clock divided by 8 ($33.33 \text{ MHz} / 8 = 4.167 \text{ MHz}$). ICTC3 can only be used with Timer 3. ICTC4 can only be used with Timer 4. The clock for Timer 5 is always the internal clock except in the 32-bit cascade mode when the output from Timer 4 is the clock for Timer 5.

The timer outputs can generate interrupts. When a timer output transitions from a 0 to a 1 then an interrupt status bit is set and can generate an interrupt. This bit sticks until cleared.

8254 Timer Base Address

This register is used to set the I/O base address on the 8254 Timers. The timers only require 4 continuous bytes of I/O memory space (byte addressing only). The address must be 8-byte aligned. Two 8-bit registers must be set. Make sure there is a space opened up in the LPC space for this base address.

TIMBASEMS (Read/Write) CA6h (or C96h)

D7	D6	D5	D4	D3	D2	D1	D0
TIMBASE15	TIMBASE14	TIMBASE13	TIMBASE12	TIMBASE11	TIMBASE10	TIMBASE9	TIMBASE8

Table 33: 8254 Timer Base MS Address Register Bit Assignments

Bit	Mnemonic	Description
D7-D0	TIMBASE(15:8)	Most significant 8 bits of the 16-bit Timer Base Address. Default is 0x3F (default timer base address is 0x3FFC)

TIMBASELS (Read/Write) CA7h (or C97h)

D7	D6	D5	D4	D3	D2	D1	D0
TIMBASE7	TIMBASE6	TIMBASE5	TIMBASE4	TIMBASE3	TIMBASE2	0	0

Table 34: 8254 Timer Base LS Address Register Bit Assignments

Bit	Mnemonic	Description
D7-D2	TIMBASE(7:2)	Most significant 6 bits of the 16-bit Timer Base Address. Default is 0x3F (default timer base address is 0x3FFC)
D1-D0	0	These read-only bits always return 0

A/D and D/A Control/Status Register

This register is used to control A/D and D/A conversion.

ADCONSTAT (Read/Write) CAFh (or C9Fh)

D7	D6	D5	D4	D3	D2	D1	D0
Reserved	Reserved	Reserved	DACLDA0	Reserved	ADCBUSY0	Reserved	ADCONVST0

Table 35: A/D, D/A Control/Status Register Bit Assignments

Bit	Mnemonic	Description
D7-D6	Reserved	These bits are reserved. Only write 0 to these bits and ignore all read values.
D5	Reserved	This bit is reserved. Only write 0 to this bit and ignore read values.
D4	DACLDA0	This is a write-only (pulsed) bit. When a '1' is written it will strobe the LDAC signal on the LTC2634 D/A Converter. Writing a '0' is ignored.
D3	Reserved	This bit is reserved. Only write 0 to this bit and ignore read values.
D2	ADCBUSY0	This read-only status bit returns the A/D conversion status. 0 – A/D is not busy doing a conversion. 1 – A/D is busy doing a conversion.
D1	Reserved	This bit is reserved. Only write 0 to this bit and ignore read values.
D0	ADCONVST0	This is a write-only (pulsed) bit. When a '1' is written it will start a conversion on the LTC1857 A/D converter. Writing a '0' is ignored.

System Test Register

This register is used for system test and should not be accessed.

SYSTEST (Read/Write) CAEh (or C9Eh)

D7	D6	D5	D4	D3	D2	D1	D0
Reserved	Reserved	Reserved	Reserved	Reserved	Reserved	Reserved	Reserved

Table 36: System Test Register Bit Assignments

Bit	Mnemonic	Description
D7-D0	Reserved	These bits are reserved. Only write 0 to these bits and ignore all read values.