## **KXTIA Accelerometer**





#### **FEATURES**

- Small Package 3x3x0.9mm LGA
- User-selectable g Range
- User-selectable Output Data Rate
- Enhanced integrated Directional Tap/Double-Tap<sup>™</sup>,
  Activity-monitoring, and Device-orientation Algorithms
- Digital SPI
- 8-bit or 12-bit Resolution
- FIFO/FILO Memory Buffer
- Digital High-Pass Filter Outputs
- Low Power Consumption
- Lead-free Solderability
- Excellent Temperature Performance
- High Shock Survivability
- Factory Programmable Offset and Sensitivity
- Self-test Function

### **APPLICATIONS**

- User Interface
- Power Management
- Active/Inactive Monitoring
- Device Orientation
- Inclination and Tilt Sensing
- Gesture Recognition
- Tap Detection
- Pedometer/Activity Monitoring

#### **FOR**

- Smartphones and Mobile Devices
- Laptops
- Gaming and Virtual Reality
- Health and Fitness

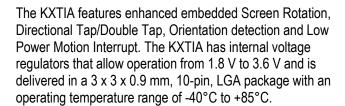


## PRODUCT OVERVIEW



The Kionix KXTIA is a low power, high performance tri-axis accelerometer with digital SPI output. The KXTIA features user selectable parameters including 8 or 12 bit modes, g-ranges from +- 2, 4 or 8g, and Output Data Rates from 12.5 Hz to 800 Hz. A 252 byte FIFO/FILO buffer offers programmable watermark interrupt.













# **KXTIA Accelerometer**



3x3x0.9mm Accelerometer with FIFO/FILO Buffer

The performance parameters below are programmed and tested at 2.6 volts and T = 25°C. The device can accept supply voltages from 1.8V to 3.6V. Due to internal voltage regulators, there should be minimal change with supply voltage variations.

	PERFOR	RMANCE SPECIFICATIONS	
PARAMETERS	UNITS	KXTIA-1006	CONDITION
Range	g	±2.0, ±4.0, ±8.0	User-selectable full-scale output range
Sensitivity <sup>1</sup>	counts/g	64, 32, 16	8-bit
		1024, 512, 256	12-bit
0g Offset vs. Temp	mg/°C	±0.7 (xy) ±0.4 (z) typical	-40°C to +85°C
Sensitivity vs. Temp	%/°C	±0.01 (xy) ±0.03 (z) typical	-40°C to +85°C
Mechanical Resonance <sup>2</sup>	Hz	3500 (xy) 1800 (z) typical	-3dB
Output Data Rate (ODR) <sup>3</sup>	Hz	12.5 min; 50 typical; 800 max	
Bandwidth (-3dB) <sup>4</sup>	kHz	1.59	RES = 0
	Hz	ODR/2	RES = 1
Non-Linearity	% of FS	0.6 typical	% of full scale output
Cross-axis Sensitivity	%	2.0 typical	
SPI Communication Rate	MHz	20 max	
Power Supply	V	2.6 typical	1.8V – 3.6V
Current Consumption	μΑ	325 typical	RES = 1; All Engines
		165 typical	Directional Tap <sup>™</sup>
		100 typical	Low Power
		10 typical	Standby
	ENVIRON	MENTAL SPECIFICATIONS	
PARAMETERS	UNITS	KXTIA-1006	CONDITION
Operating Temperature	°C	-40 to 85	Powered
Storage Temperature	°C	-55 to 150	Un-powered
Mechanical Shock	g	5,000, 0.5 ms 10,000, 0.2 ms	Powered or un-powered, halversine
ESD	V	2,000	Human body model

## **NOTES**



<sup>&</sup>lt;sup>1</sup> Resolution and acceleration ranges are user selectable via SPI.

<sup>&</sup>lt;sup>2</sup> Resonance as defined by the dampened mechanical sensor.

<sup>&</sup>lt;sup>3</sup> User selectable via SPI.

<sup>&</sup>lt;sup>4</sup> Dependent on ODR and 8-bit or 12-bit resolution.